

KEY FRP TECHNOLOGIES IN STRUCTURAL RETROFITTING AND STRENGTHENING

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Outline

1. **Background**
2. Introduction of FRP and research status
3. Hybrid FRP technology
4. Prestressing FRP technology
5. Damage-controllable FRP structures
6. Integrated high performance FRP structures
7. Intelligent infrastructures
8. Summary

Background

Exhaustion of iron ore, large emission of CO₂ ,
great needs of steel for construction



LC economy, 1 ton steel(2 ton CO₂),steel CO₂(10%)

Iron ore 11.5 billion ton,0.6 billion/y, 20 y exhaustion

Future 20-30 years reach peak of civil infrastructure, exceeds total amount of aboard

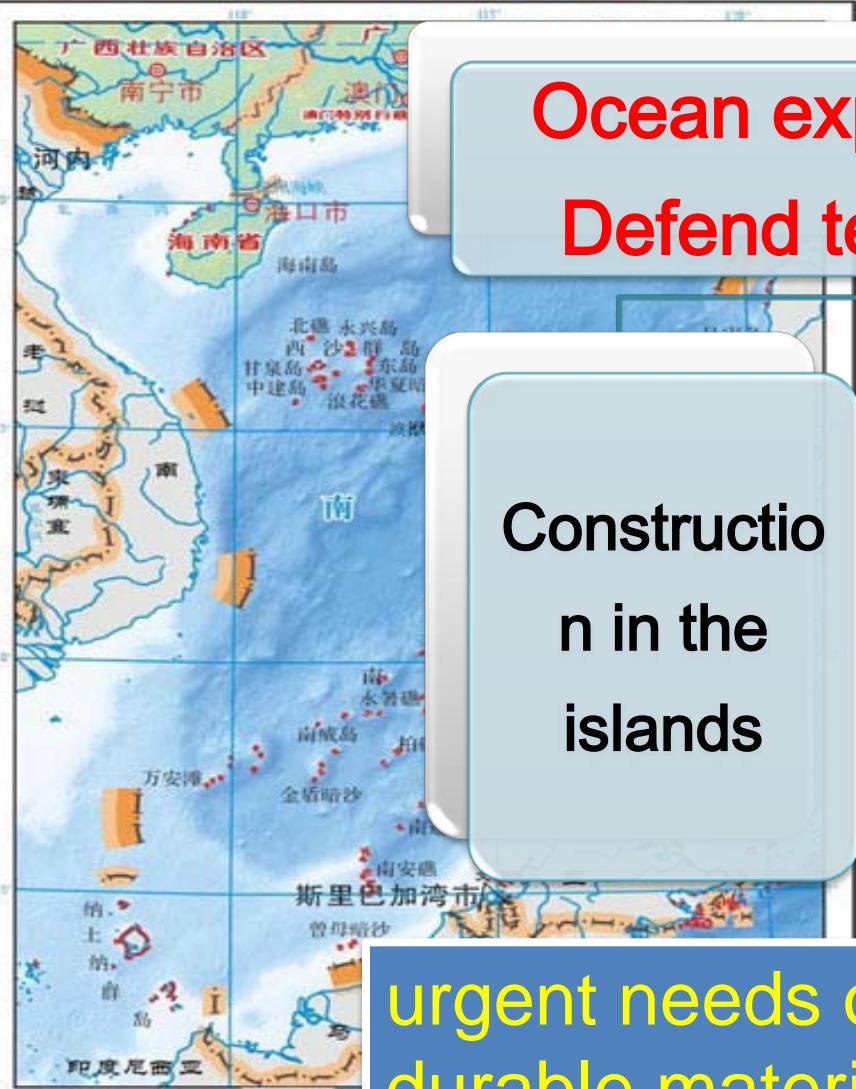
Development of new resource materials

Relief resource crisis

low carbon emission

Sustainable development

Background



Ocean exploration and
Defend territorial sea

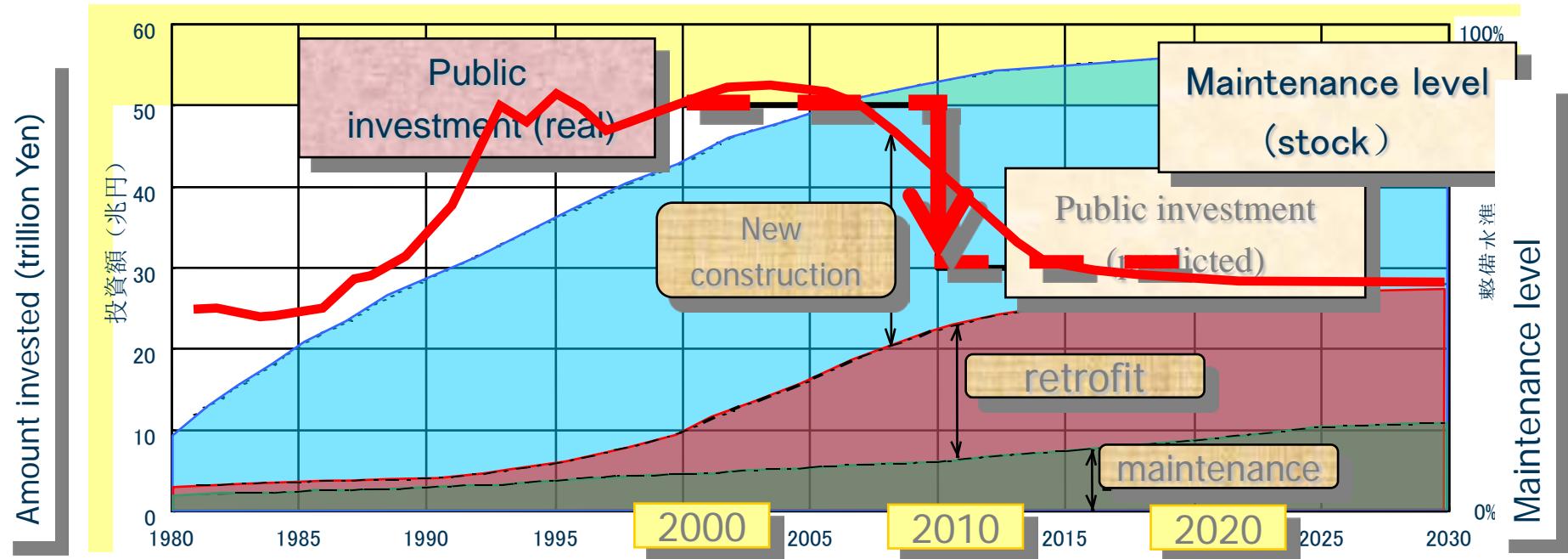
Construction
in the
islands

Explore
deep
ocean
resource

urgent needs of safe and
durable materials and structures
under corrosive environment



Lessons from developed countries



Long-term prediction of public investment in Japan

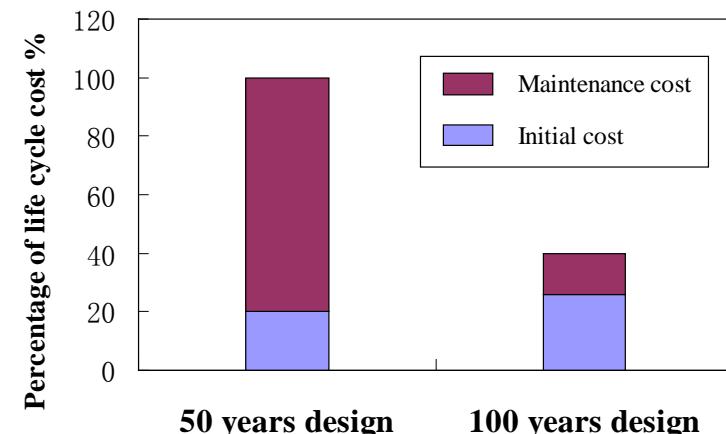
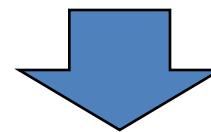
FHWA, US data : 26.9% of 600905 bridges structural or functional deficiencies, retrofitting needs \$17 billion/year, currently only 10.5 billion/year

Background

➤ Life cycle cost (LCC) minimization

LCC = initial investment+maintenance+retrofitting and rehabilitation+residual value

Five times law : reduce \$ 1 in design stage, add \$5 when find steel corrosion, add \$25 when concrete longitudinal cracks, add \$125 when serve damage



Minimization of LCC

Lesson from developed countries : improve structural life from current 50-100 years to 100-300 years, properly increase initial investment-----one of the methods of realizing LCC Min.

Constructions problems

Safety and durability need improvement



I-25W bridge (US) collapse
corrosion of joints



Corrosion of stay cables, such as XizhiMen bridge in Beijing, removed after 20 years

Cracks, large deflection, and severe corrosion—
Potential safety problems



Girder bridge's severe such as Luoxi bridge, safety problems



Deflection of girder bridge, such as Huangshi bridge, deflected 33cm after 15 years

Constructions problems

Improve safety and extend life through lightweight

Heavy weight

$$F_i(t) = -m_i[\ddot{x}_0(t) + \ddot{x}_i(t)]$$



Section increase
Large seismic response



Cost increase
Safety decrease



High rise building:
over 85% selfweight

Longer span, steel is a restriction

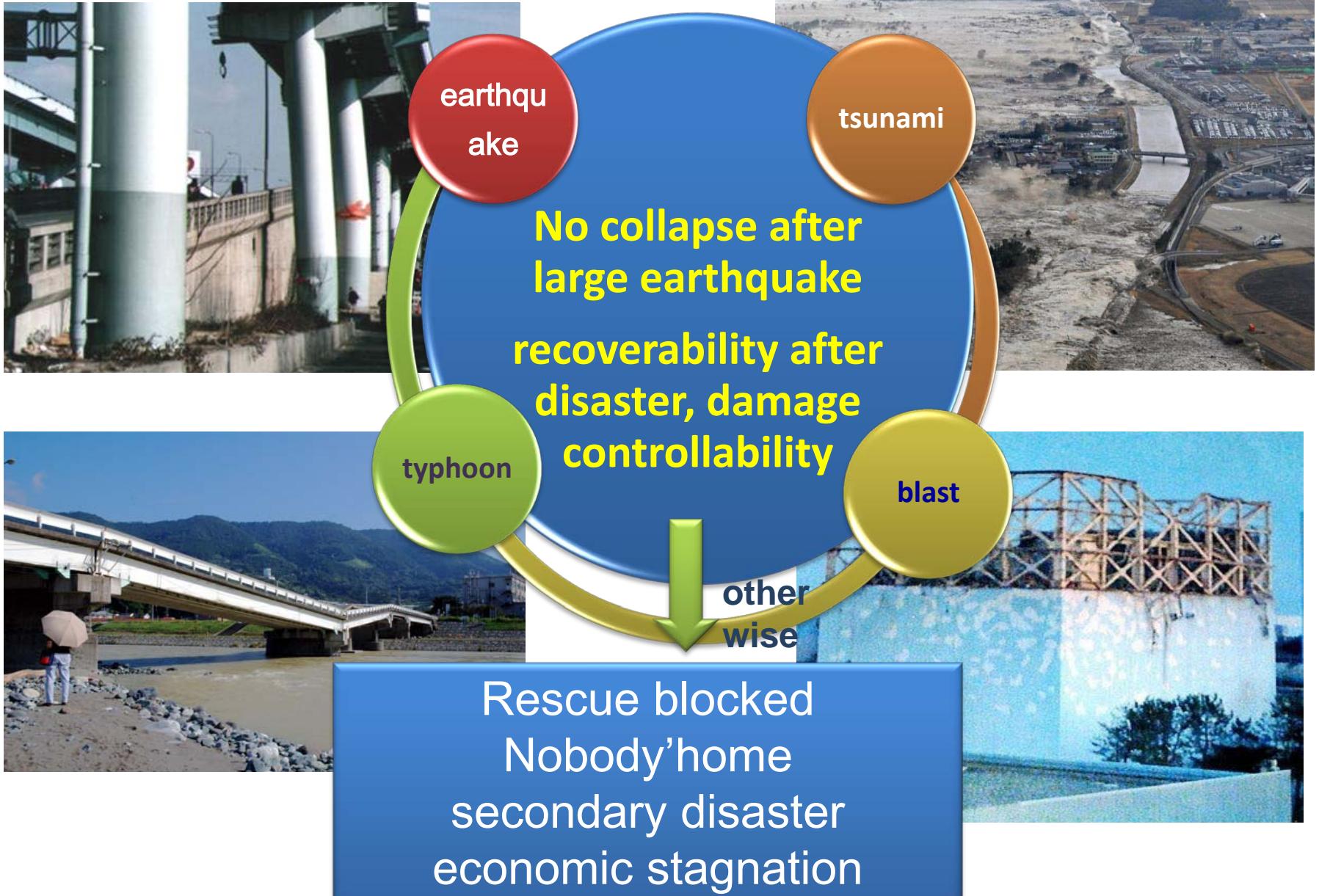


Lightweight



Reduce cost
Improve safety
Extend life

Constructions problems



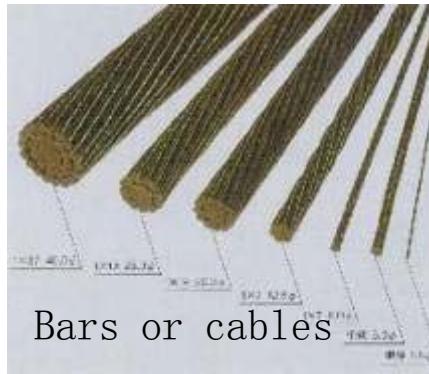
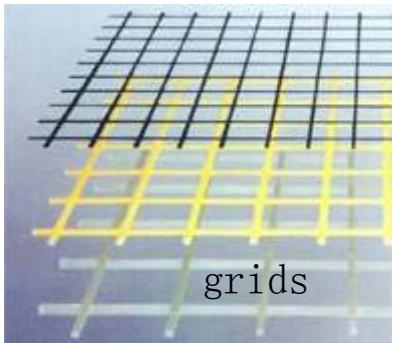
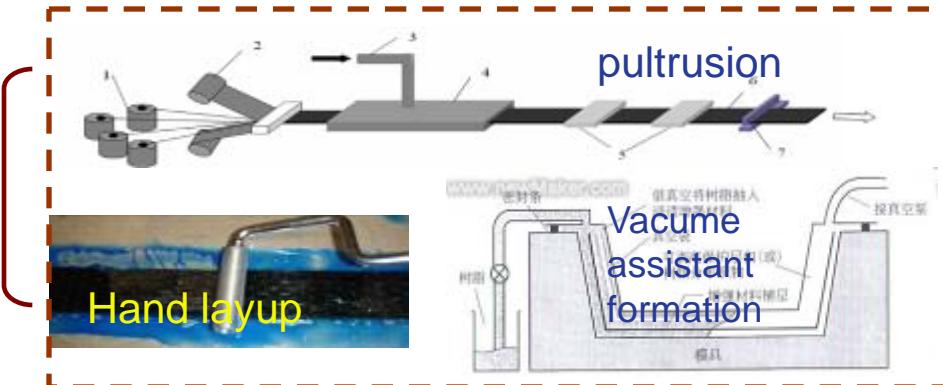
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FRP products for structural strengthening

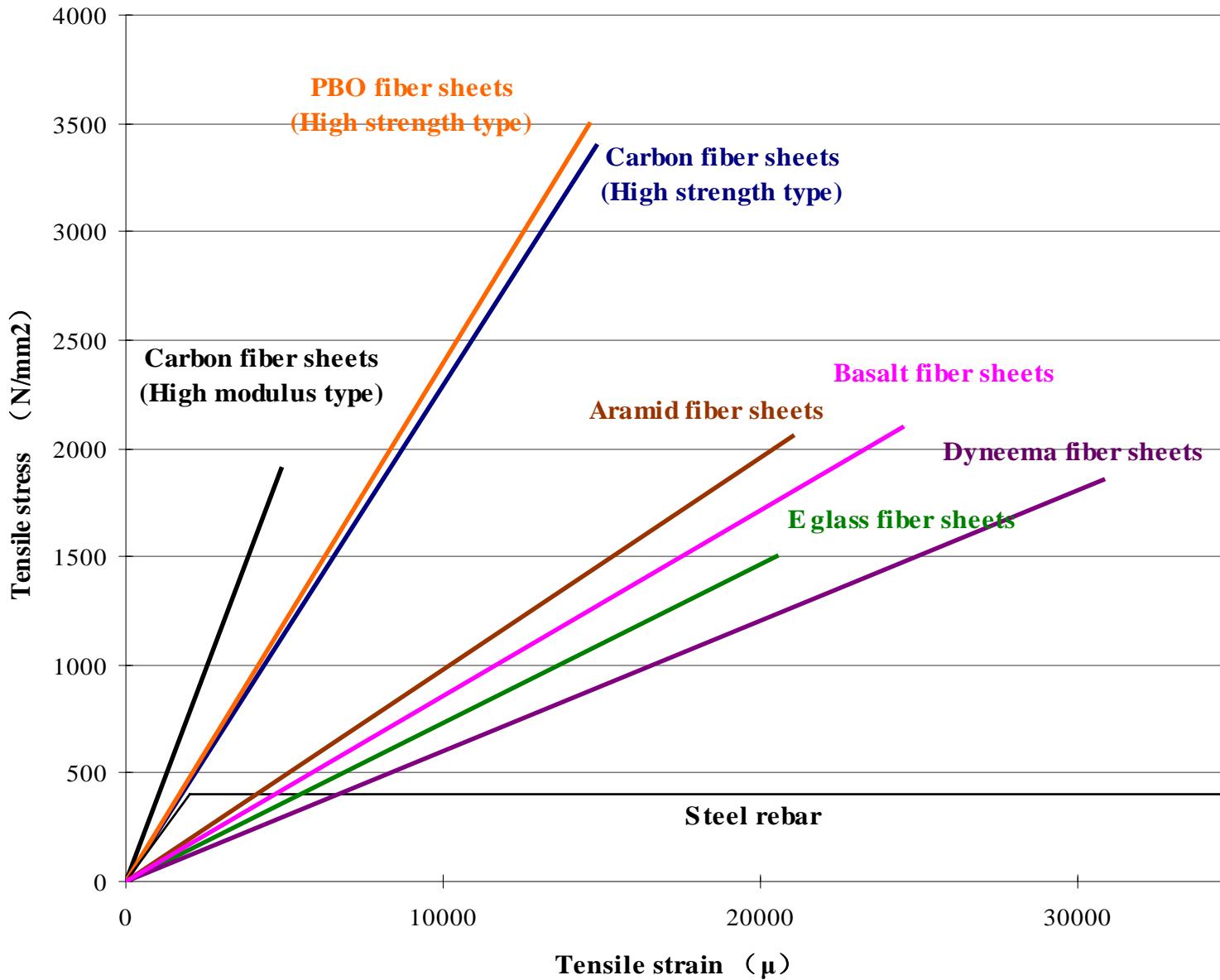


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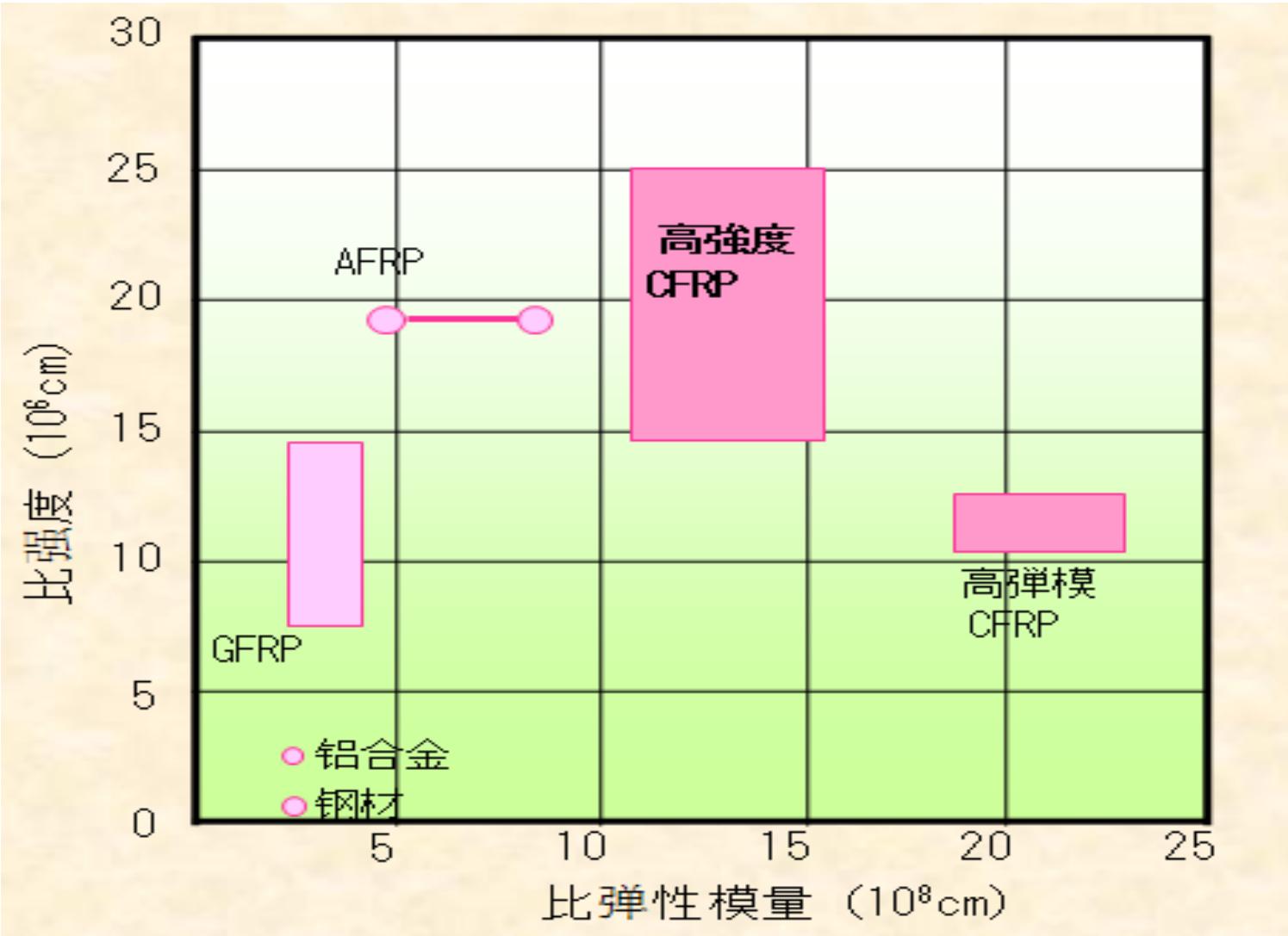


Various
FRP
products

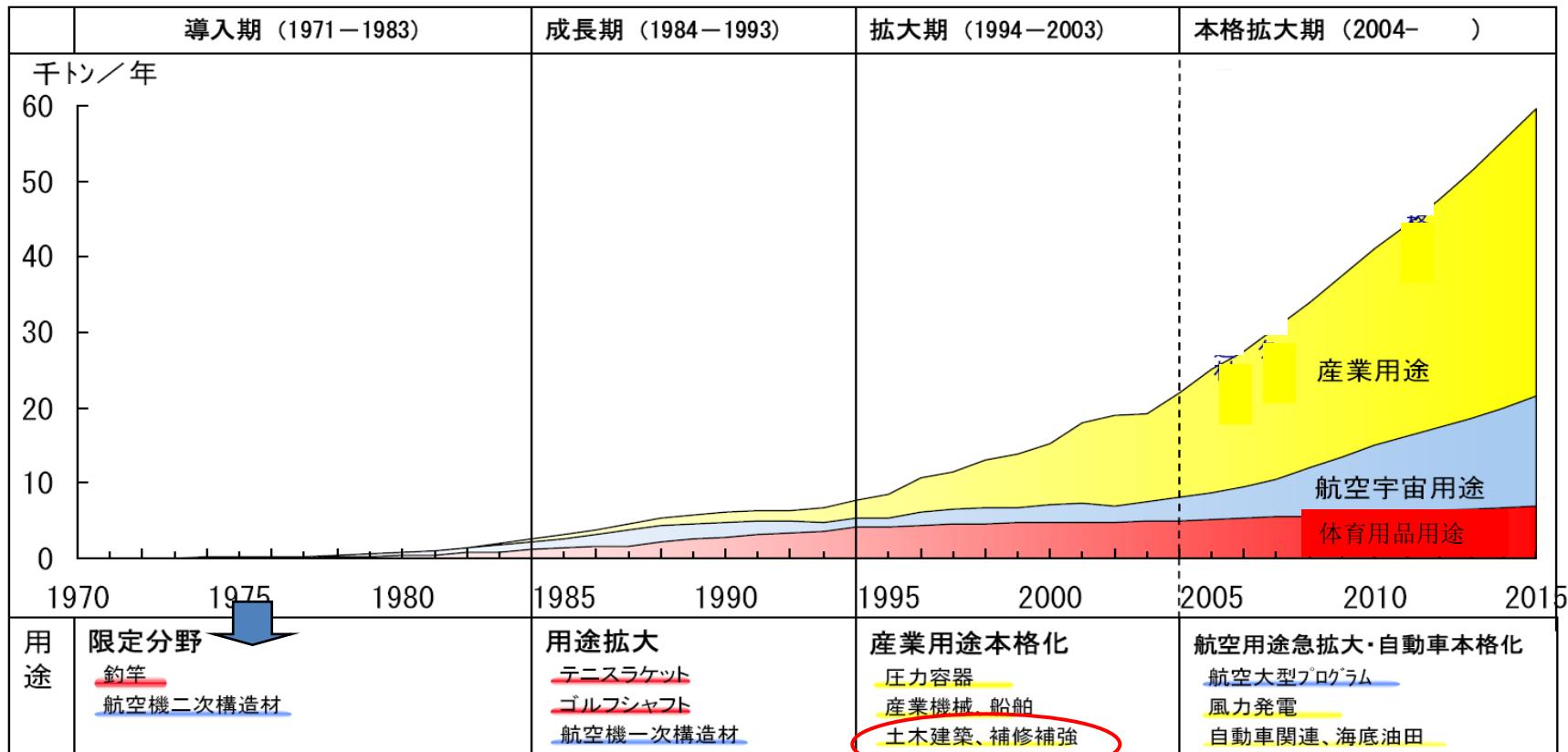
Mechanical properties of FRP



Mechanical properties of FRP



Development of FRP for construction (carbon FRP)



Beginning of
80's, structural
retrofitting and
rehabilitation

90's Hanshin
Earthquake, for
seismic
strengthening

1990-2000, new
structure
(composite
structures)

FRP for retrofitting structures

FRP bonded or wrapped



Beam or plate



Seismic strengthening



chimney



FRP profiles



FRP tubes for piers

FRP bars or tendons



FRP NSM

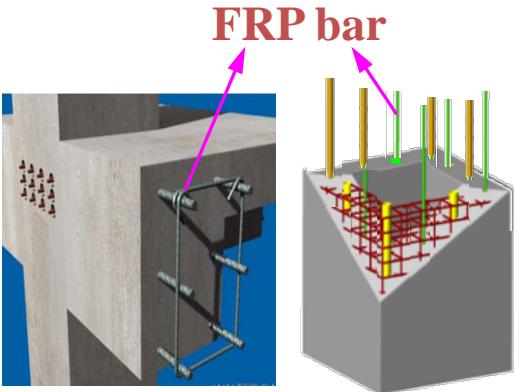


FRP cable externally strengthening

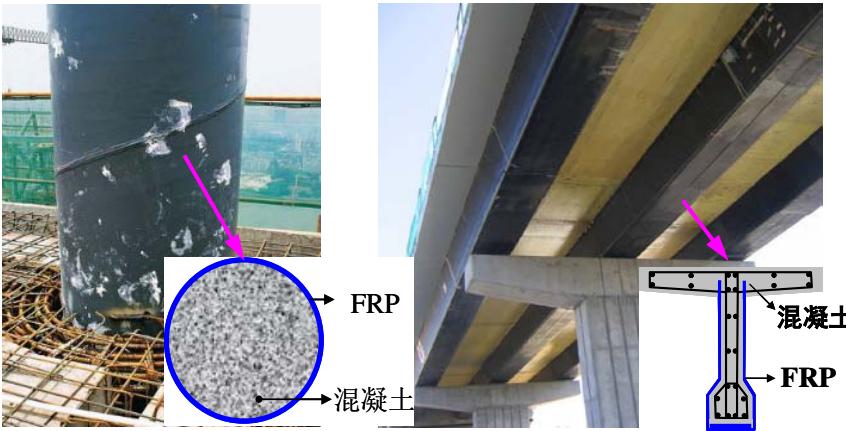


FRP for new construction

FRP replace steel bar



FRP-RC composite column/beam



FRP light roof



FRP cable structure



Offshore platform



FRP desulfurization chimney



FRP tanks



FRP techniques in bridge

*Flexural
strengthening*

Transverse direction

Longitudinal
direction

Girder

Slab

Wrapping

Longitudinal direction

*Flexural & shear
strengthening*

Overhang

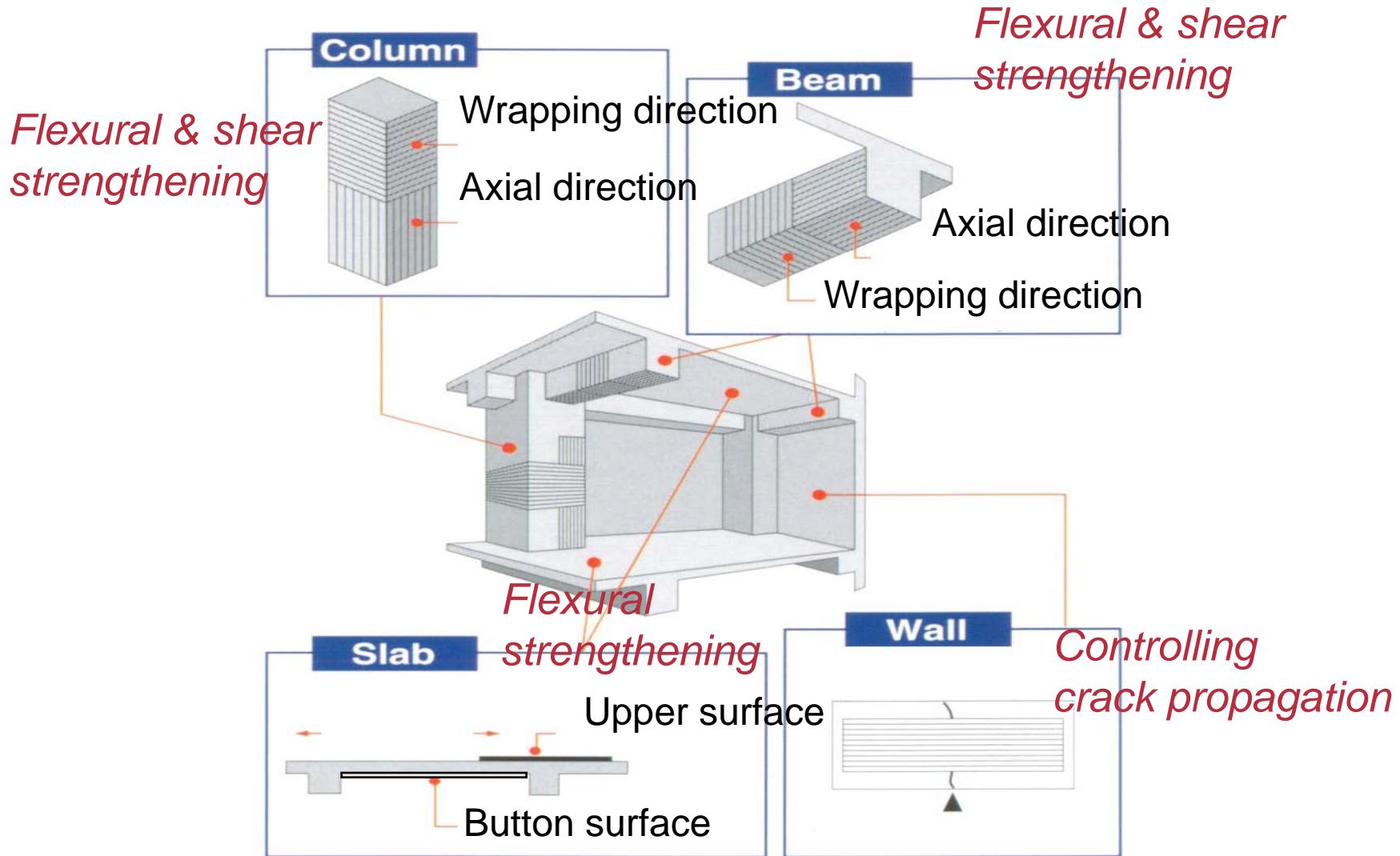
*Flexural & shear
strengthening*

Bridge pier

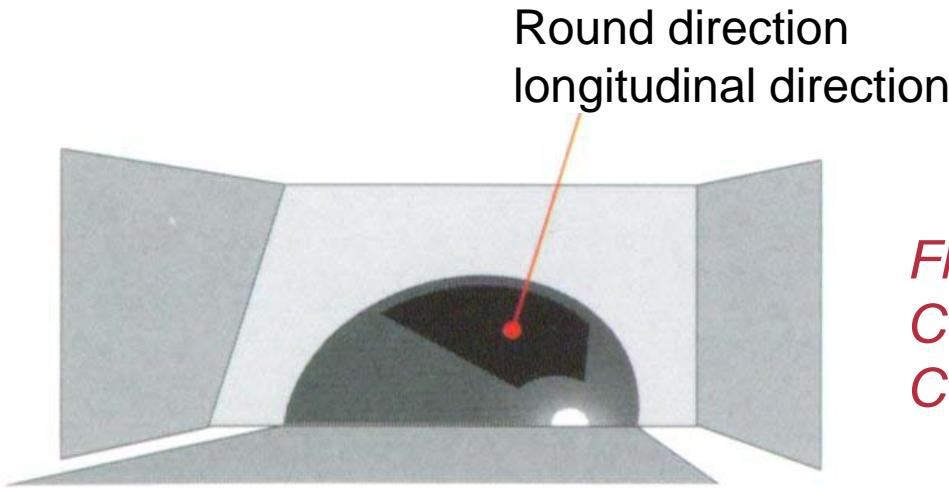
Wrapping direction

Vertical direction

FRP techniques in building



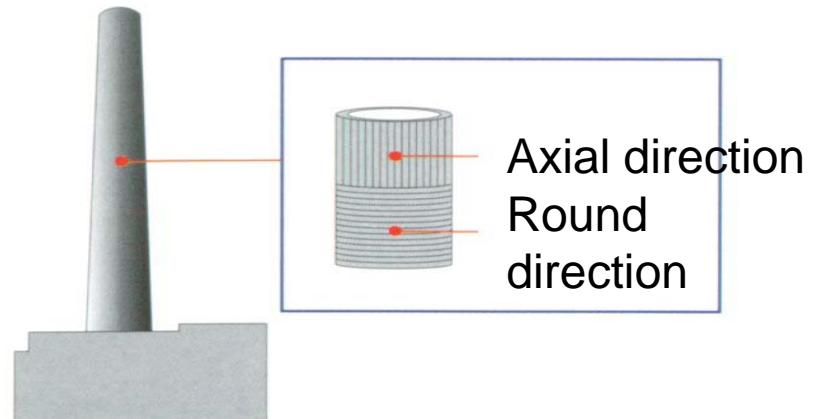
FRP techniques in special structure



*Flexural strengthening
Controlling crack propagation
Concrete spalling resistance*

Tunnel

*Flexural strengthening
Controlling crack propagation
Concrete spalling resistance*

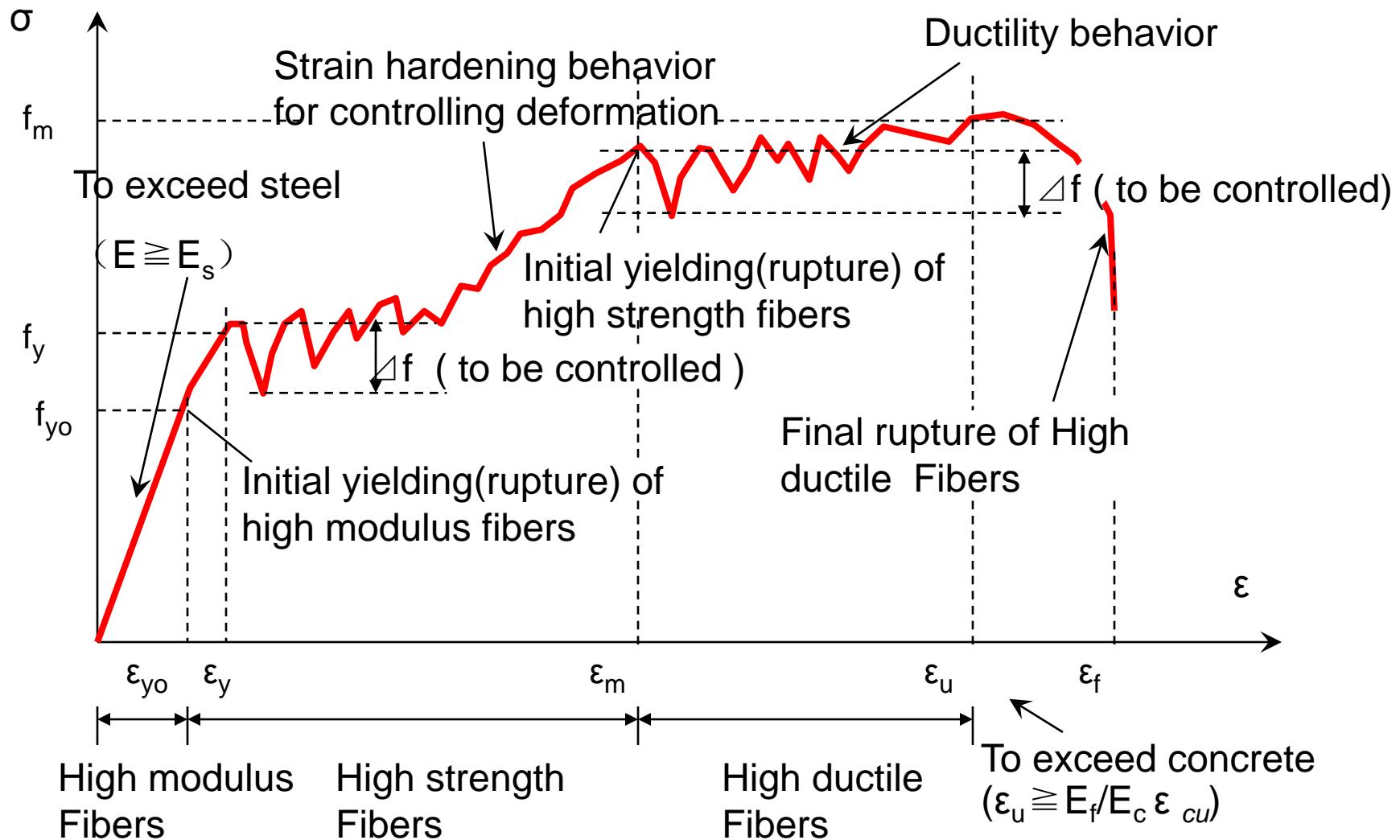


Chimney, etc.

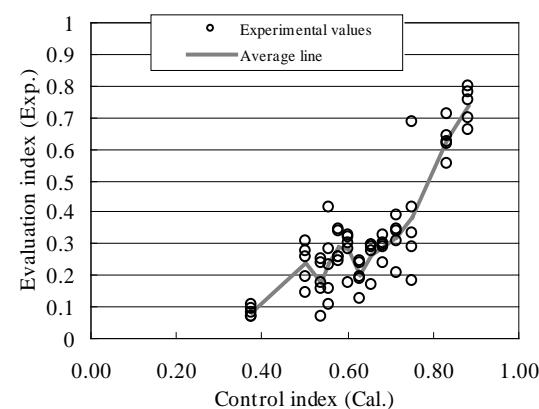
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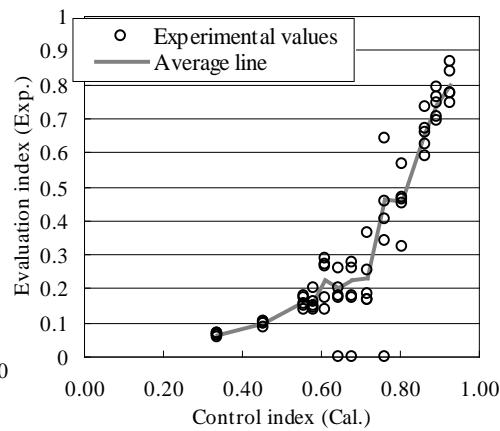
Hybrid concept of different fibers



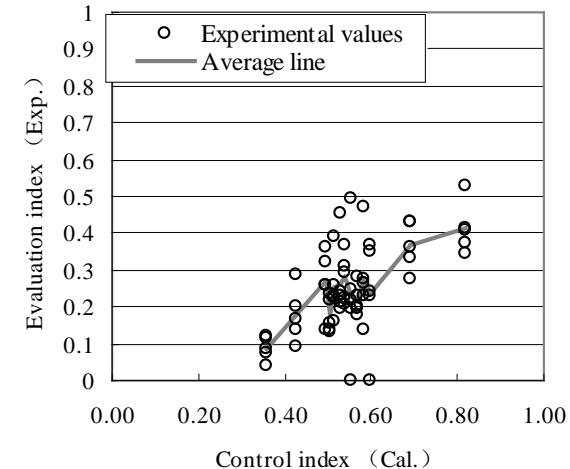
Stress drop control of hybrid FRP



HM/HS

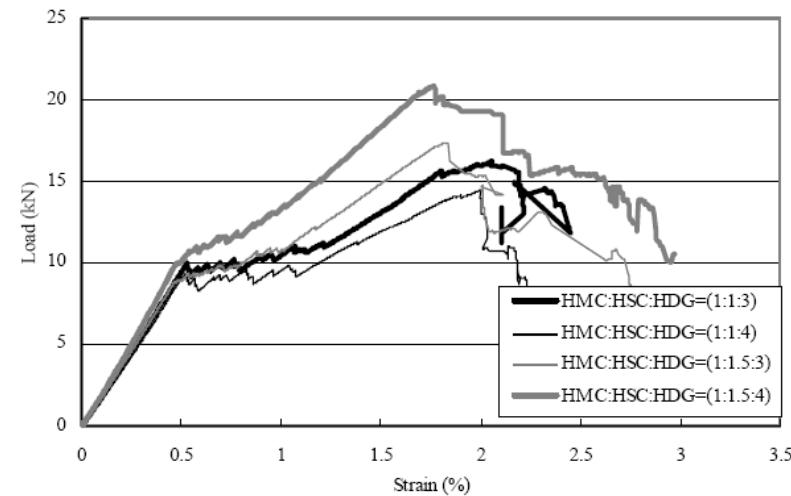


HM/PBO

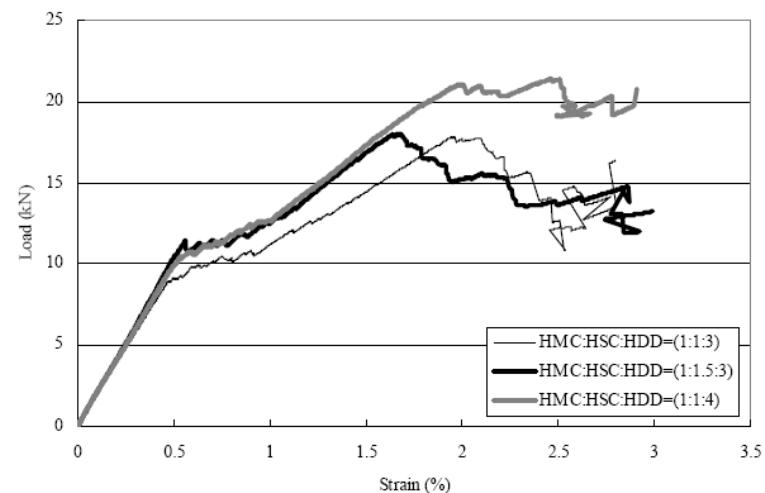


HM/Dyneema

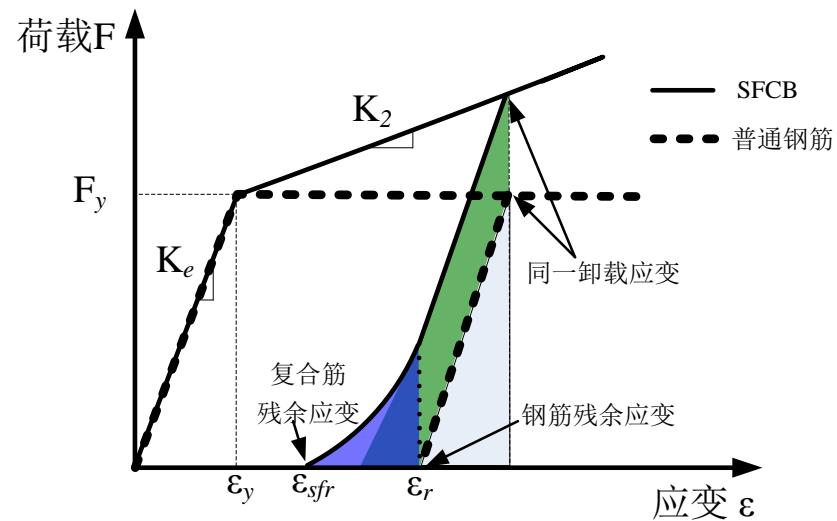
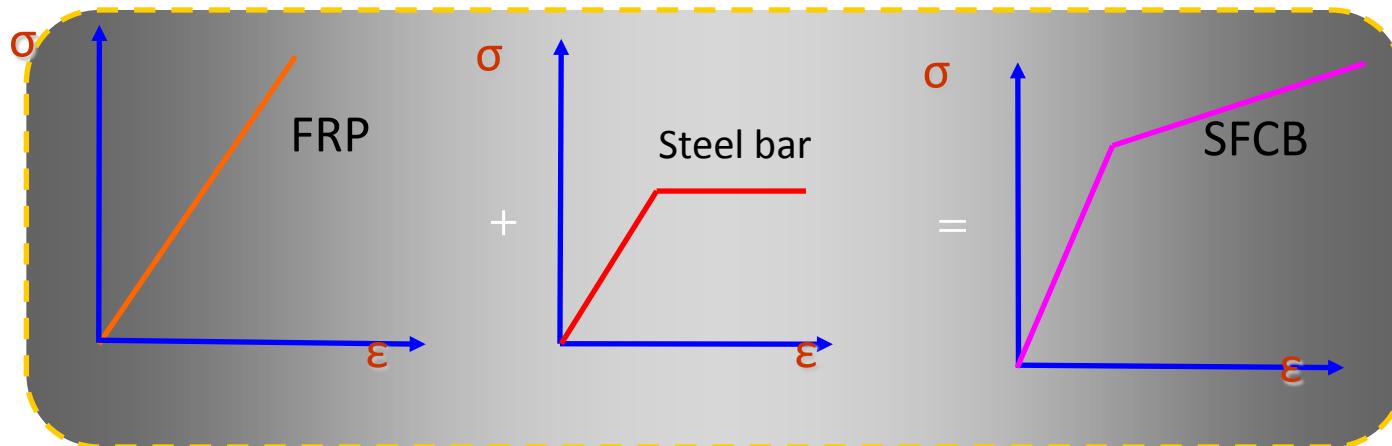
Realize hybrid
effect through
stress drop
control



Experimental tests

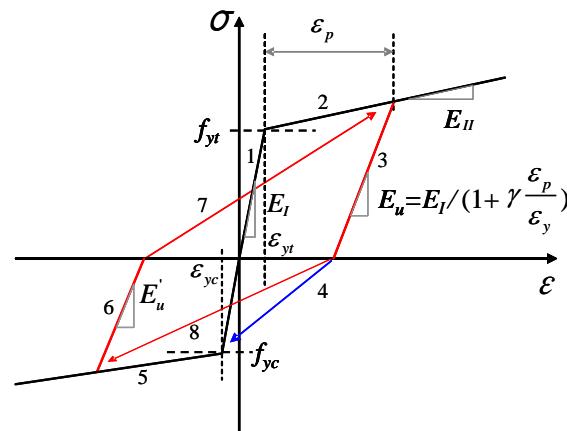
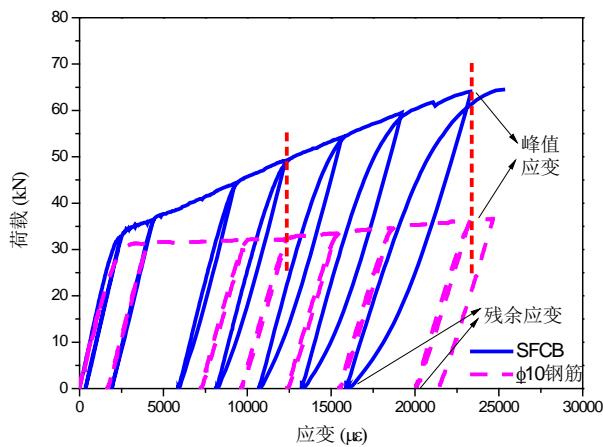
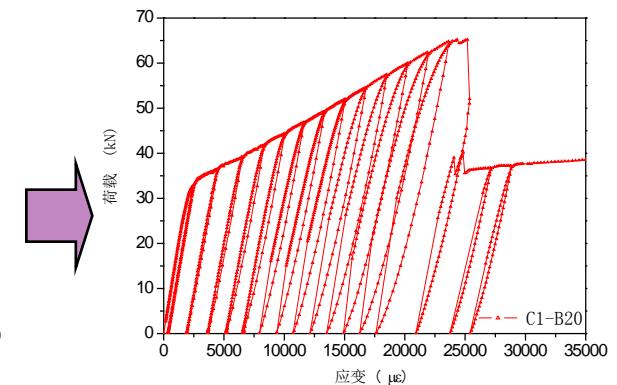
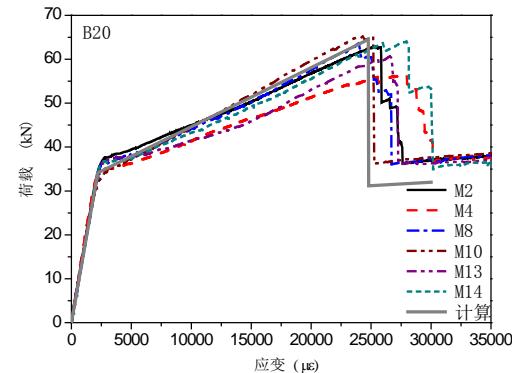
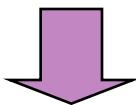


Hybrid concept of FRP and steel bar (SFCB)



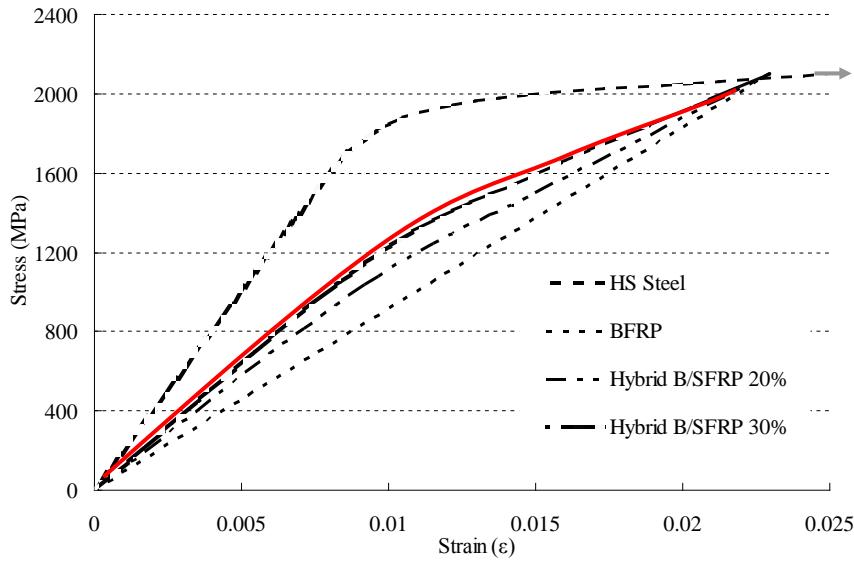
SFCB properties

SFCB

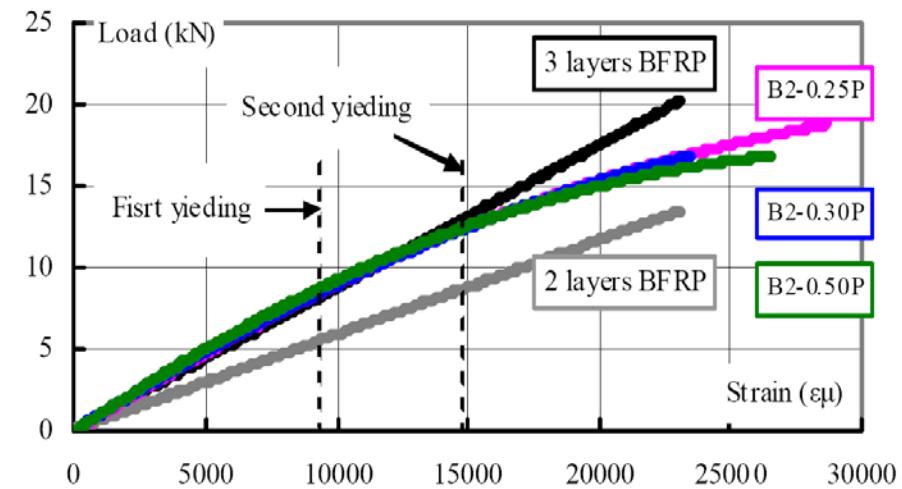


$$\sigma_{sf} = \begin{cases} E_I \varepsilon_{sf} & , 0 \leq \varepsilon_{sf} < \varepsilon_{sfy} \\ f_{sfy} + E_{II} (\varepsilon_{sf} - \varepsilon_{sfy}) & , \varepsilon_{sfy} \leq \varepsilon_{sf} \leq \varepsilon_{sfu} \\ f_{sfr} & , \varepsilon_{sfu} < \varepsilon_{sf} \end{cases}$$

Hybrid of FRP and steel-wires



Stress-strain relation



Optimization of steel wires

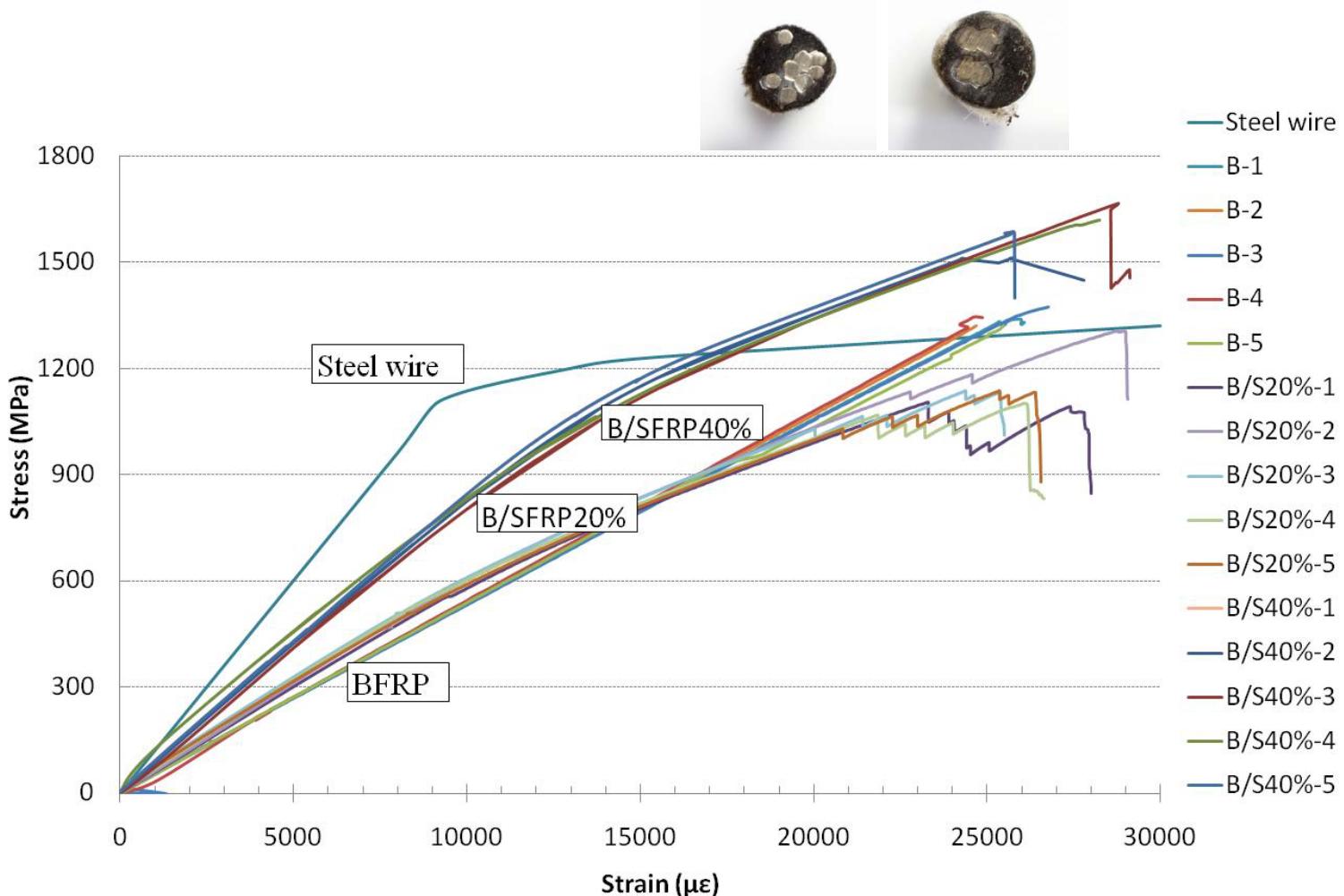
$$\sigma_{sf} = \begin{cases} E_I \epsilon_{sf}, & 0 \leq \epsilon_{sf} < \epsilon_{sfy} \\ f_{sfy} + E_{II} (\epsilon_{sf} - \epsilon_{sfy}), & \epsilon_{sfy} \leq \epsilon_{sf} < \epsilon_{sfu1} \\ E_{II} \epsilon_{sf}, & \epsilon_{sfu1} \leq \epsilon_{sf} \leq \epsilon_{sfu2} \end{cases}$$

$$V_{c|\frac{\epsilon}{\epsilon_c}} = \left. \frac{1}{1 + \frac{E_c \epsilon_c}{E_g (\epsilon_g - \epsilon_c)}} \right\}$$

$$V_{s|\frac{\epsilon}{\epsilon_c}} = \left. \frac{1}{1 + \frac{E_s}{E_f} \left(\frac{\epsilon_{sfy}}{\epsilon_{sfu2} - \epsilon_{sfu1}} \right)} \right\}$$

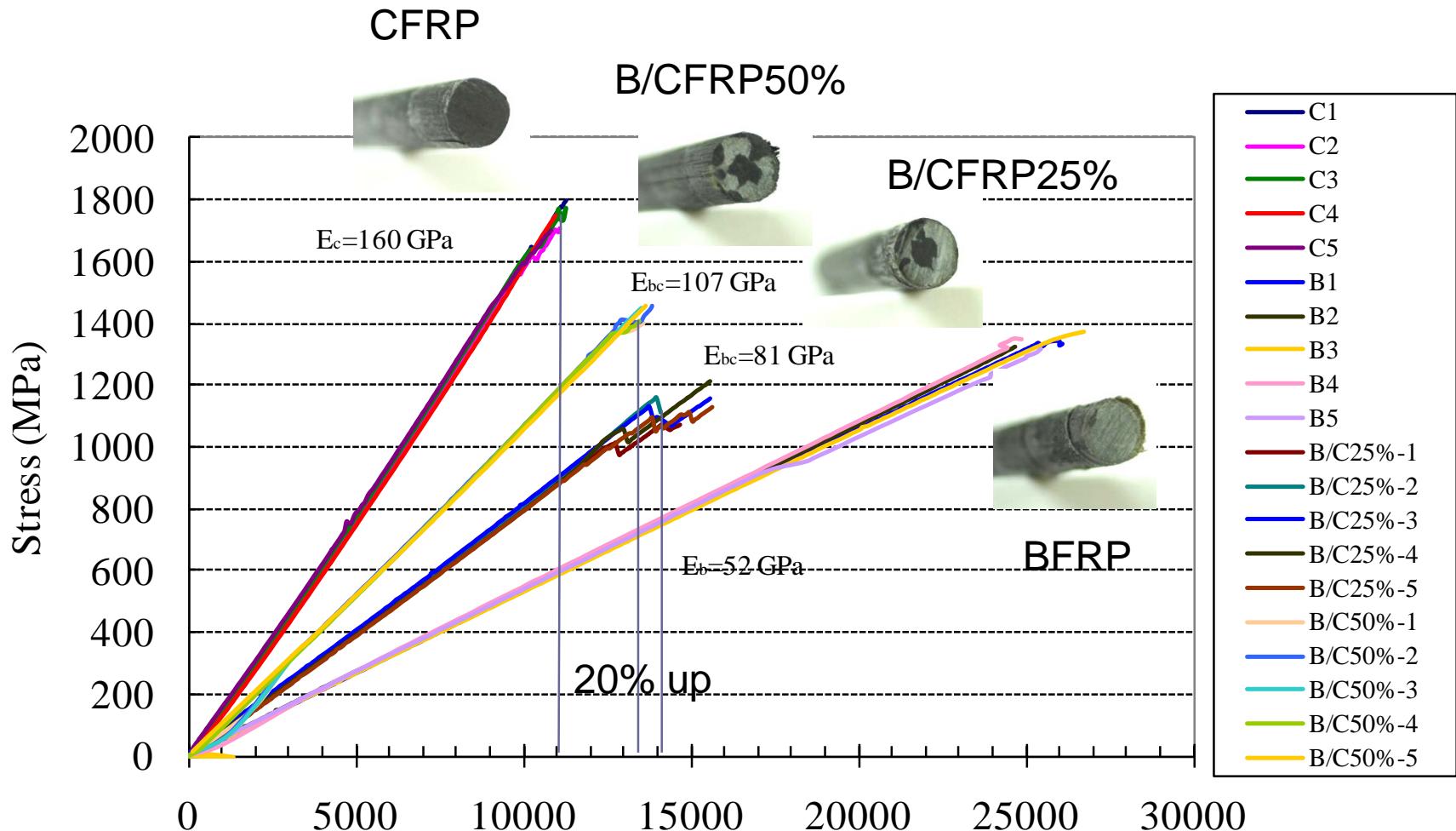
achieve max.
strength
through critical
volume fraction

Stress-strain relationship of hybrid basalt and steel-wire FRP tendon



- Initial modulus increase
- Ductility remains

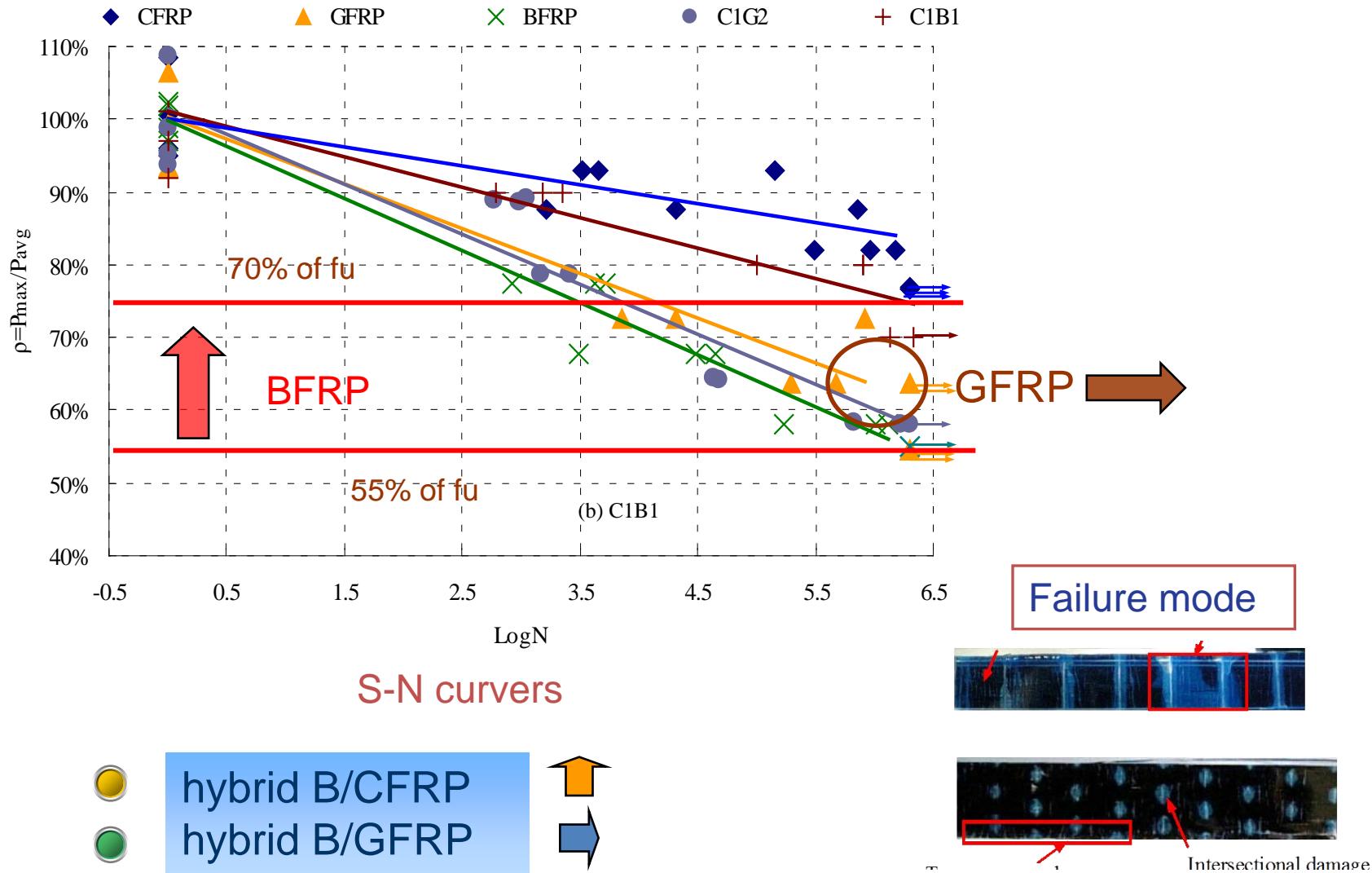
Stress-strain relationship of hybrid basalt and carbon FRP tendon



- Initial modulus increase
- potential strength of carbon fibers increase

Hybrid effect study

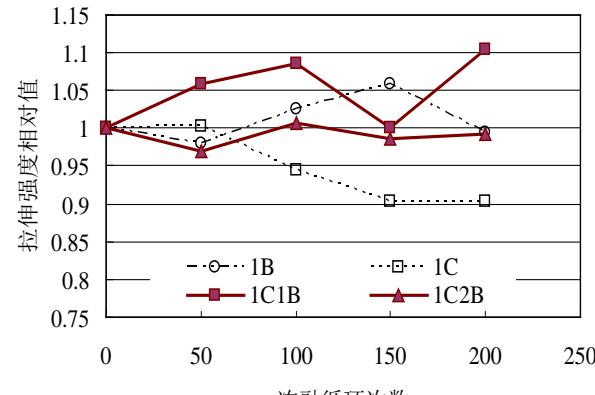
— fatigue strength



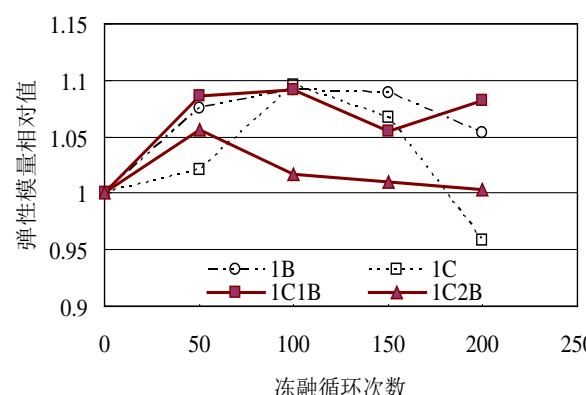
Hybrid effect study

——freeze-thaw behavior

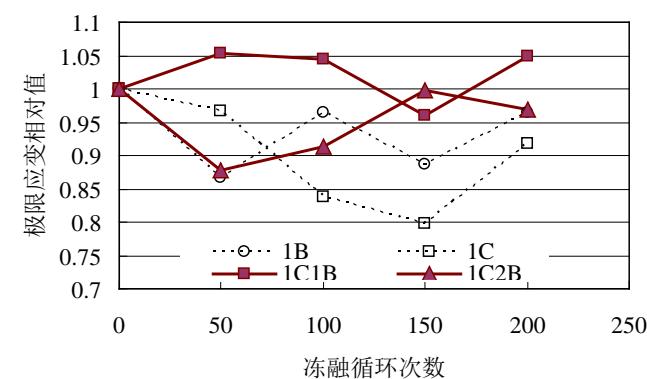
➤ Tensile properties



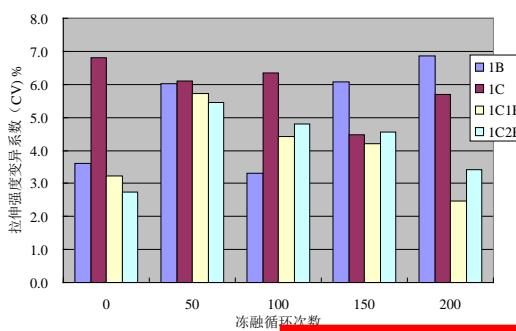
(a) tensile strength



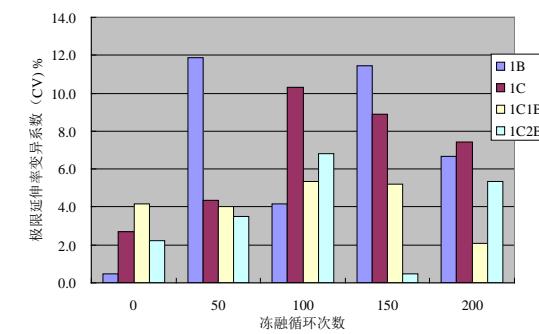
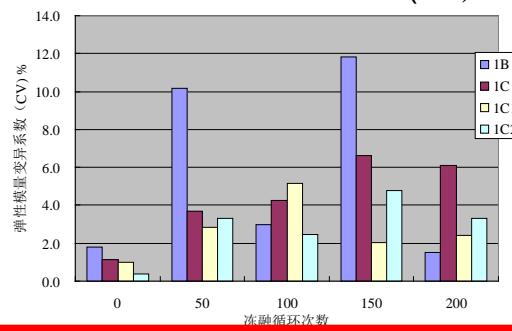
(b) elastic modulus



(c) failure strain



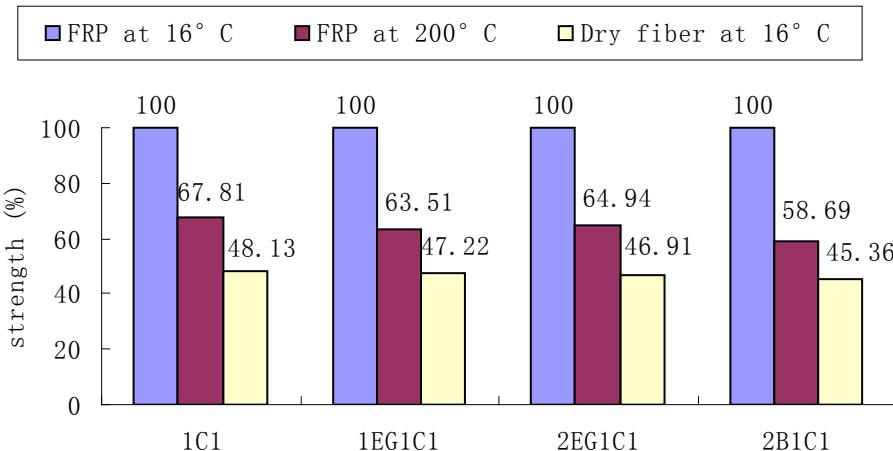
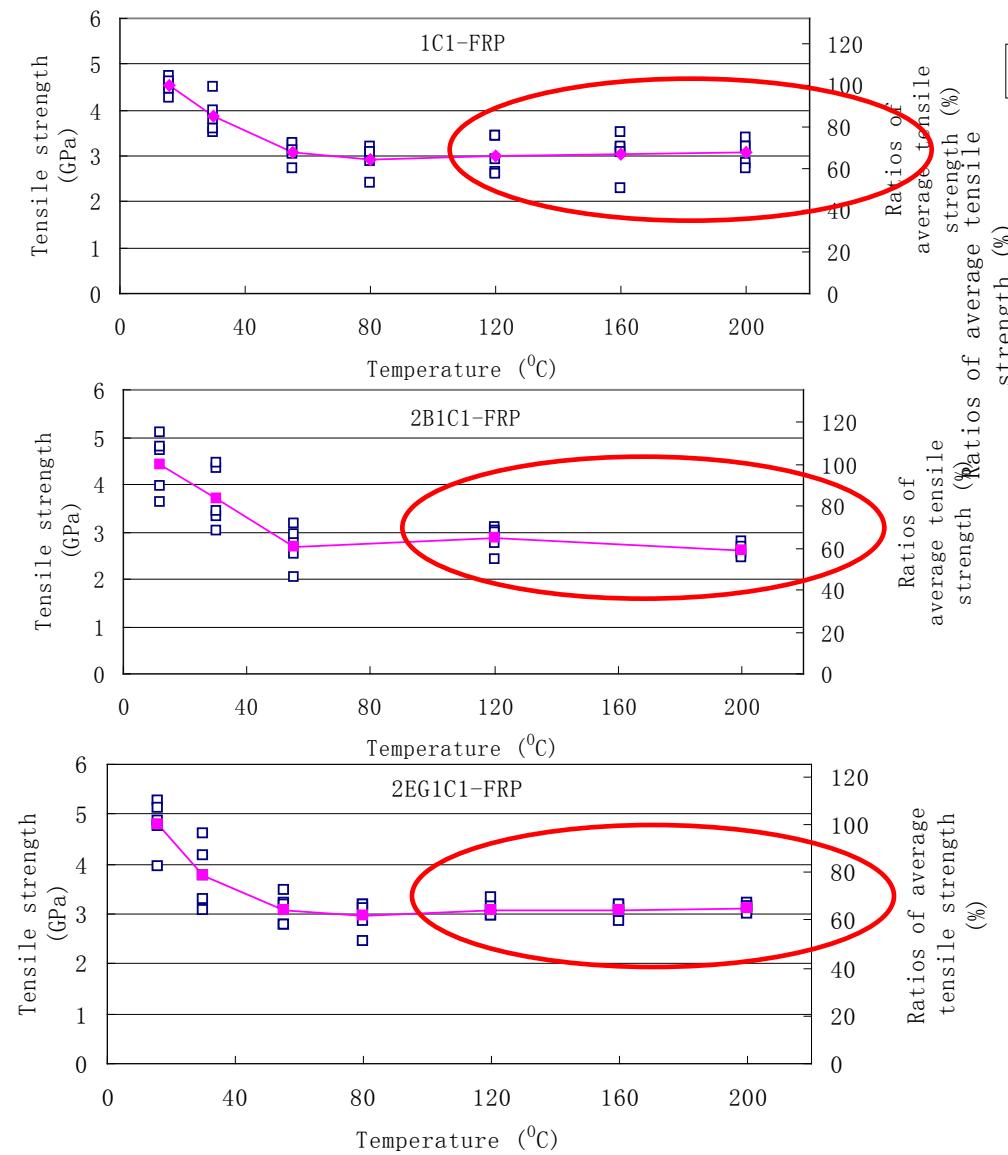
Coefficient Of Variation (Cv)



- ❑ Hybrid FRP superior than single type of FRP ;
- ❑ Low Cv of hybrid FRP .

Hybrid effect study

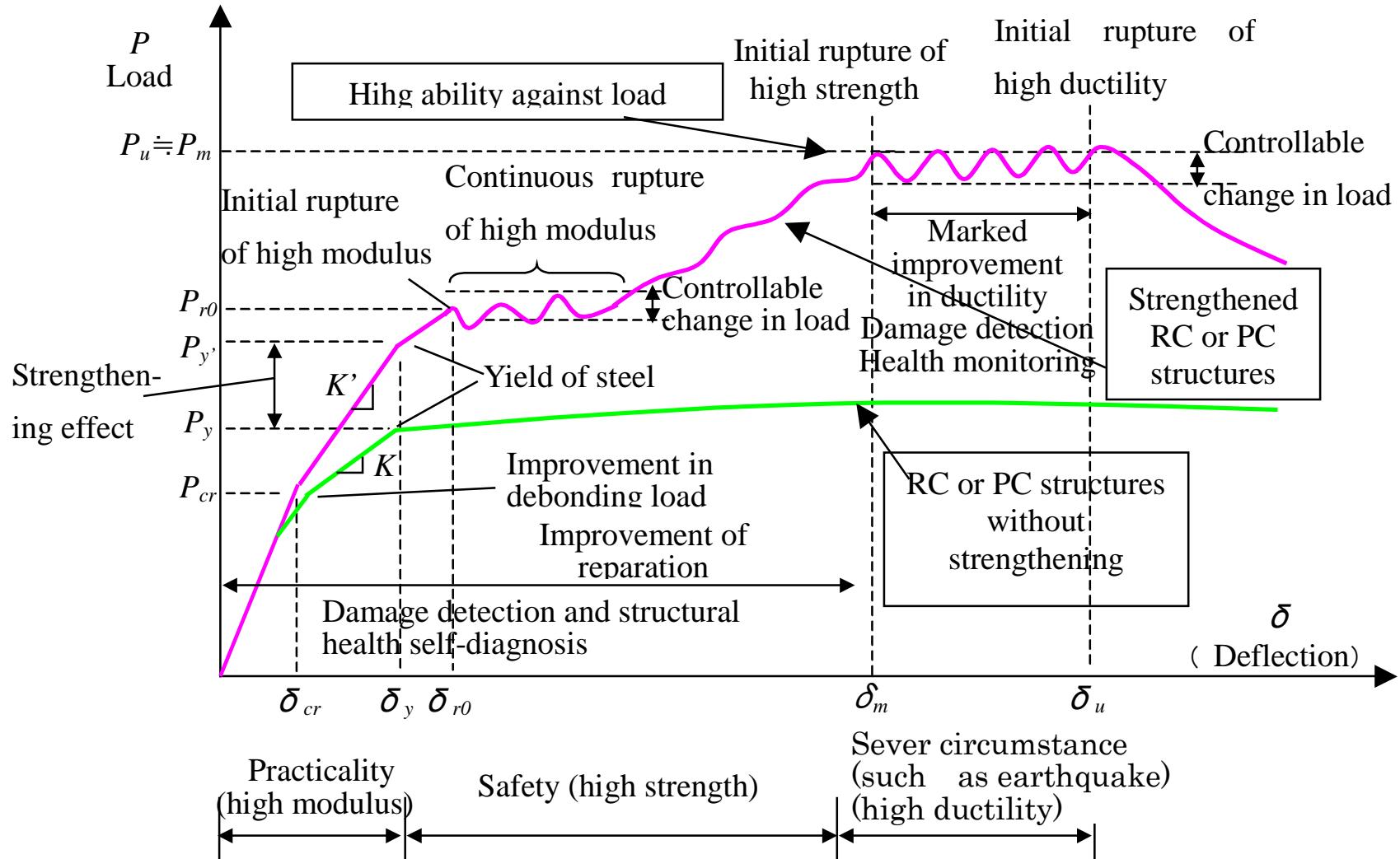
—under elevated temperatures



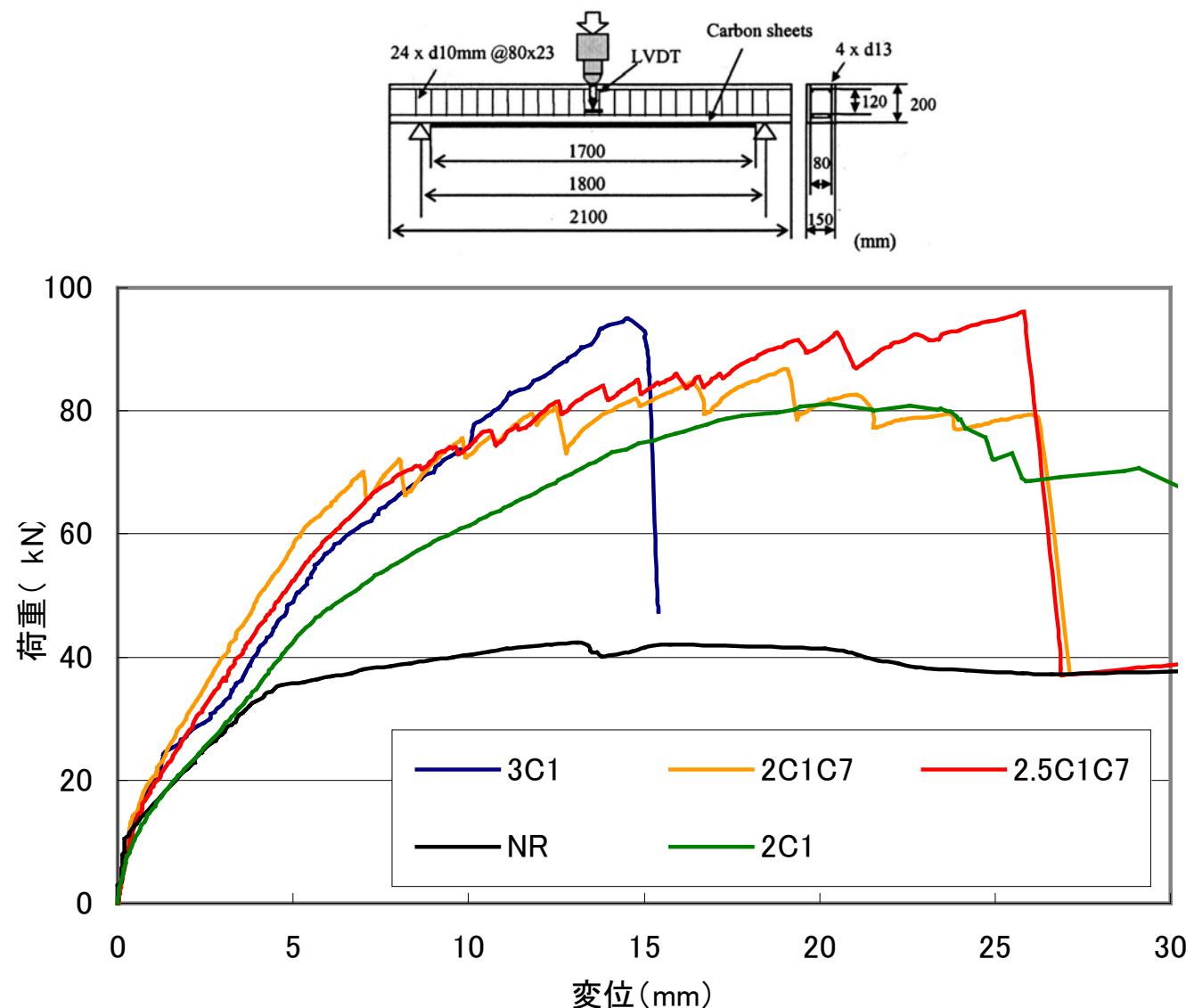
Effect:

- Improve stability of FRP under high temperature
- Residual strength can be utilized for design

Hybrid FRP for strengthening structures

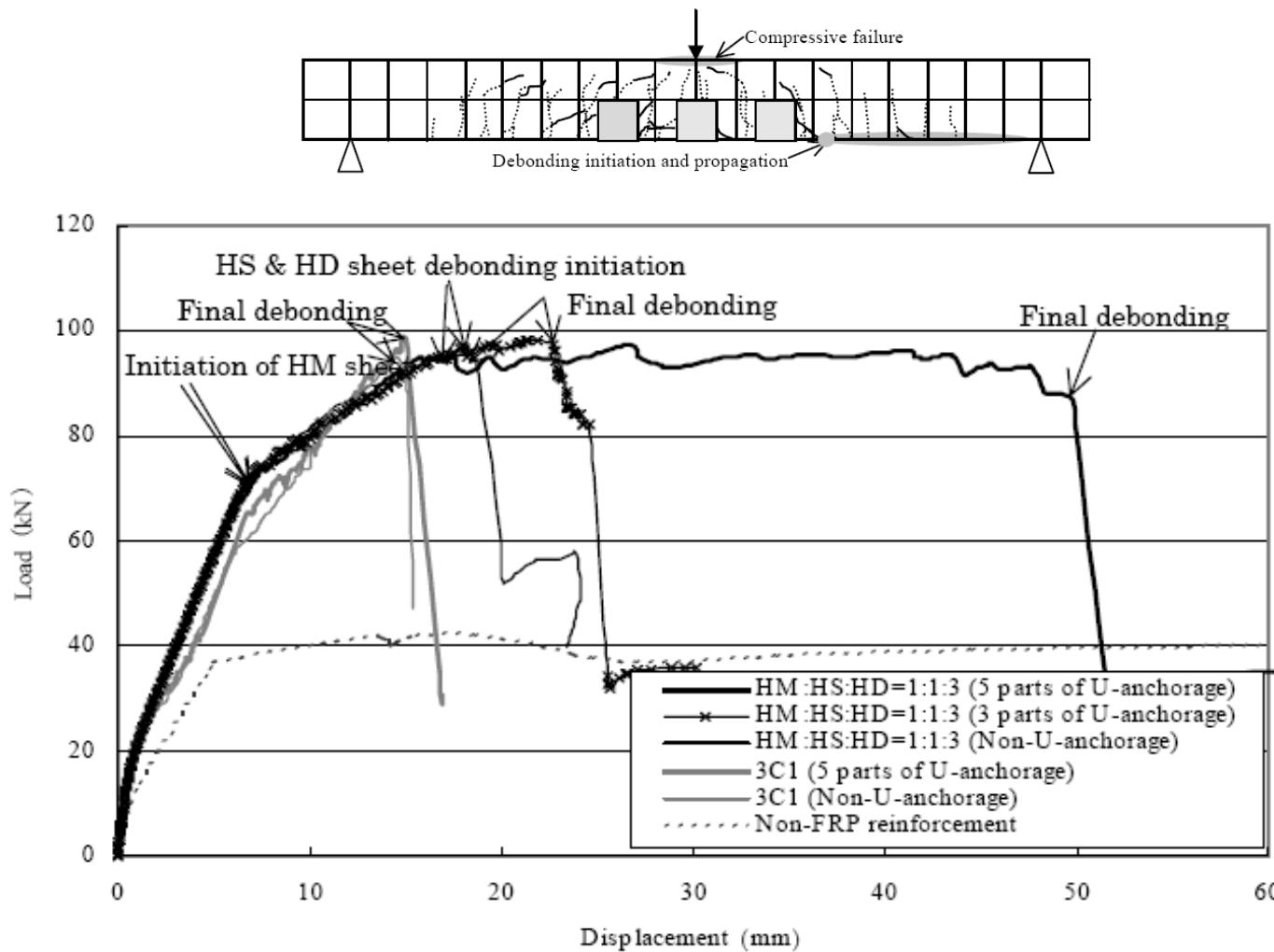


— Strengthening effect by hybrid FRP sheets



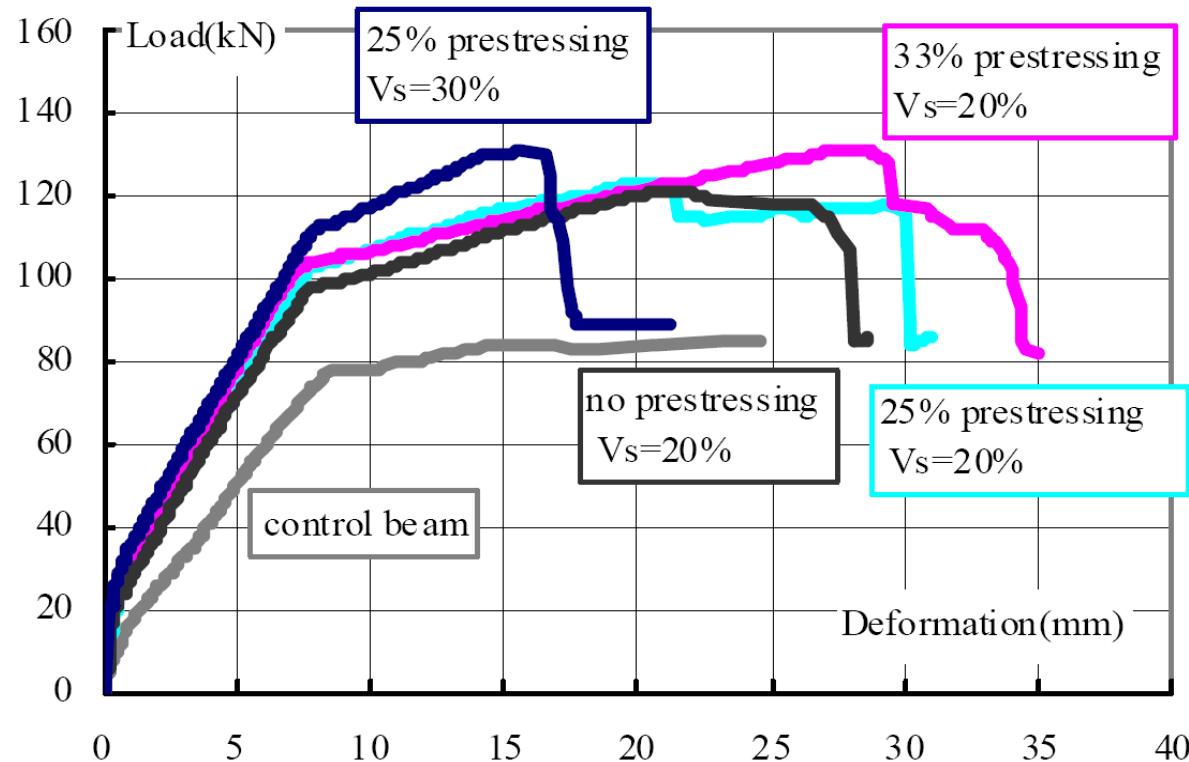
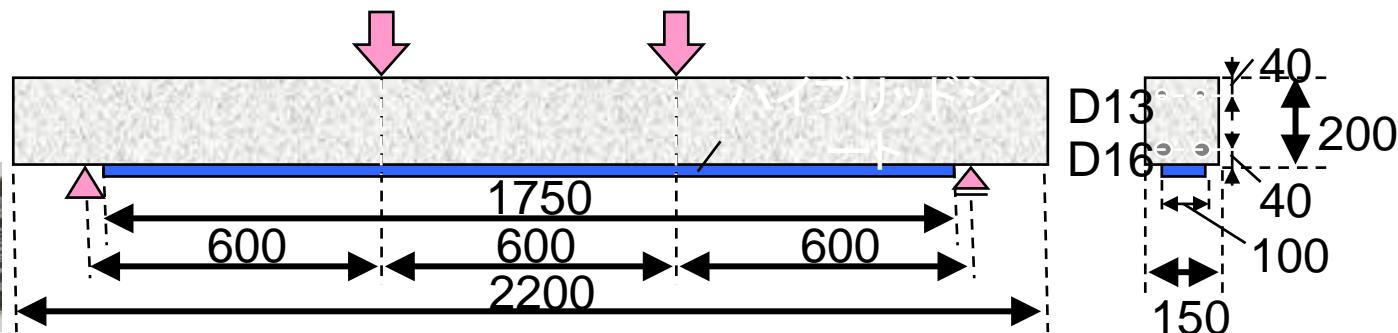
Two kinds of FRP: HS/HM FRP

— strengthening effect by hybrid FRP sheets



Three kinds of FRP: HS/HM/HD FRP

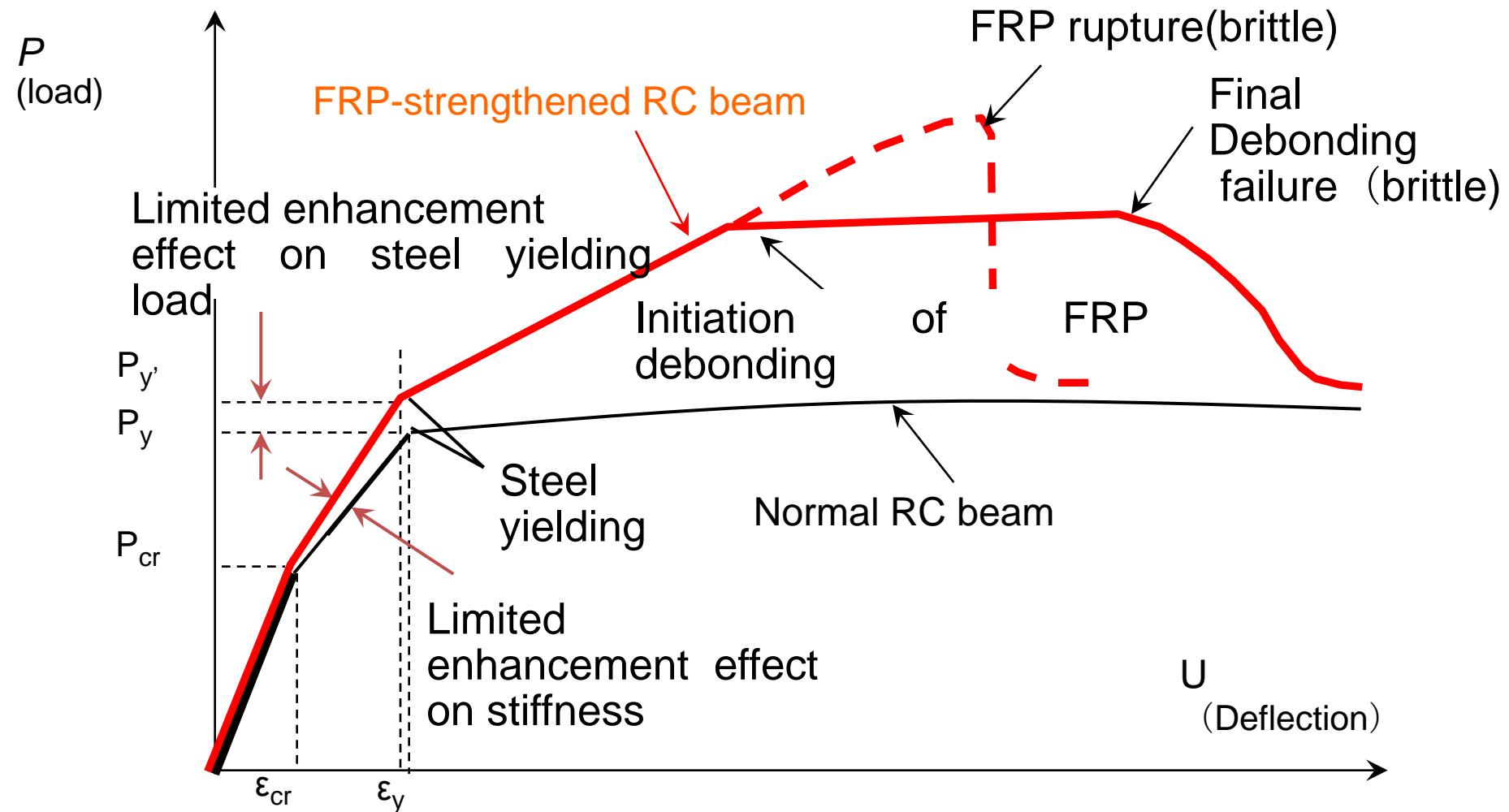
— Strengthening effect by hybrid FRP-steel wire sheets



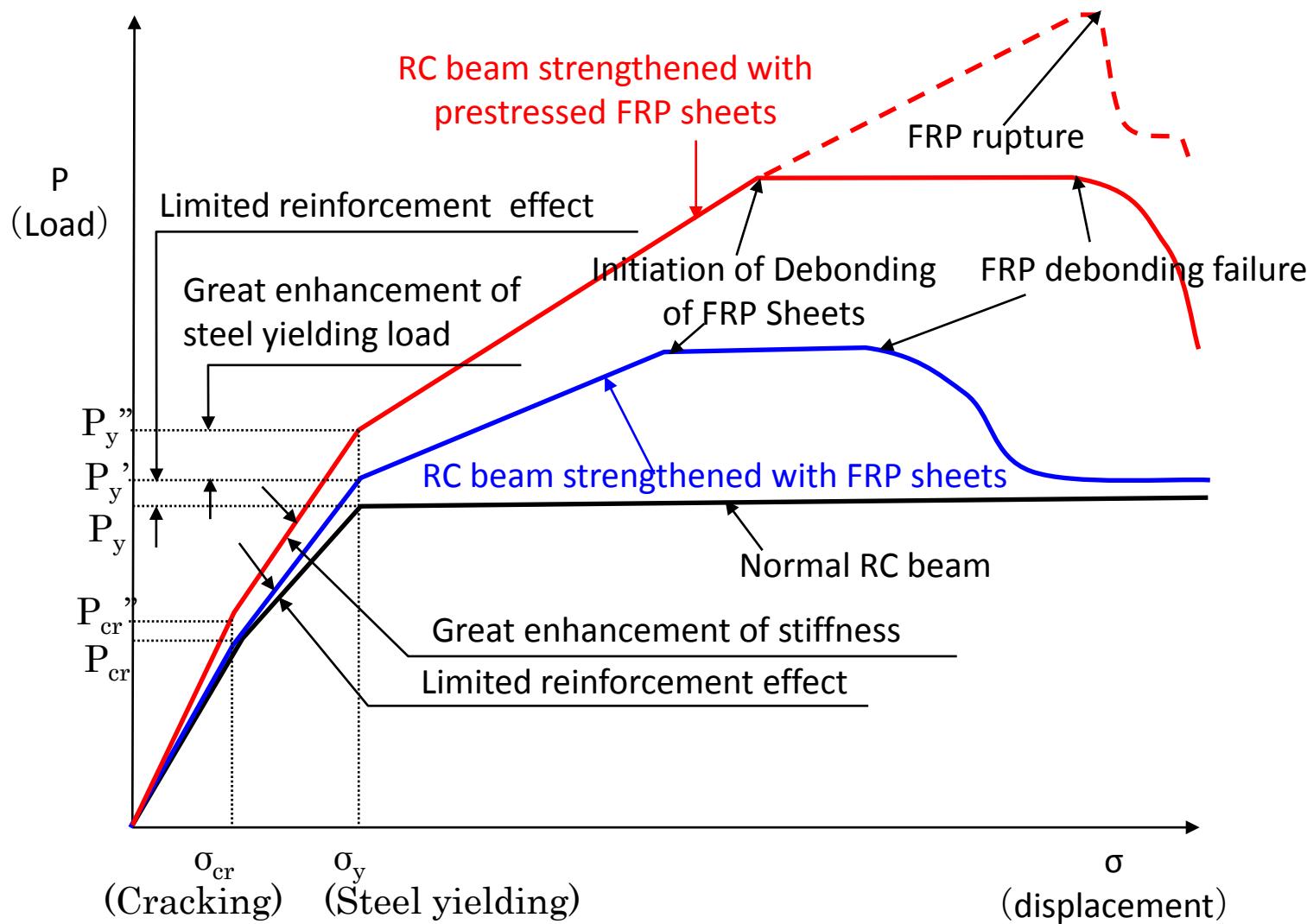
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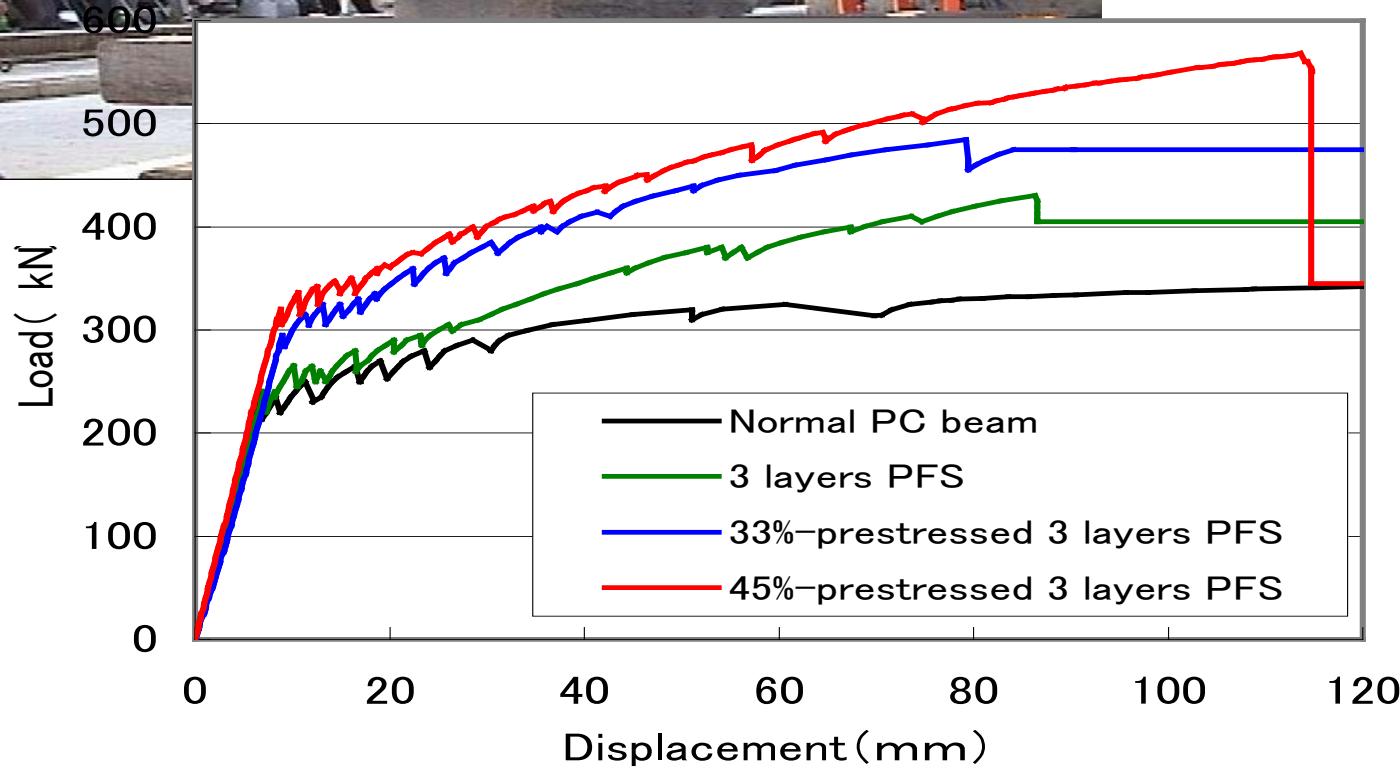
Deficiency of general external-bonded FRP sheets for strengthening



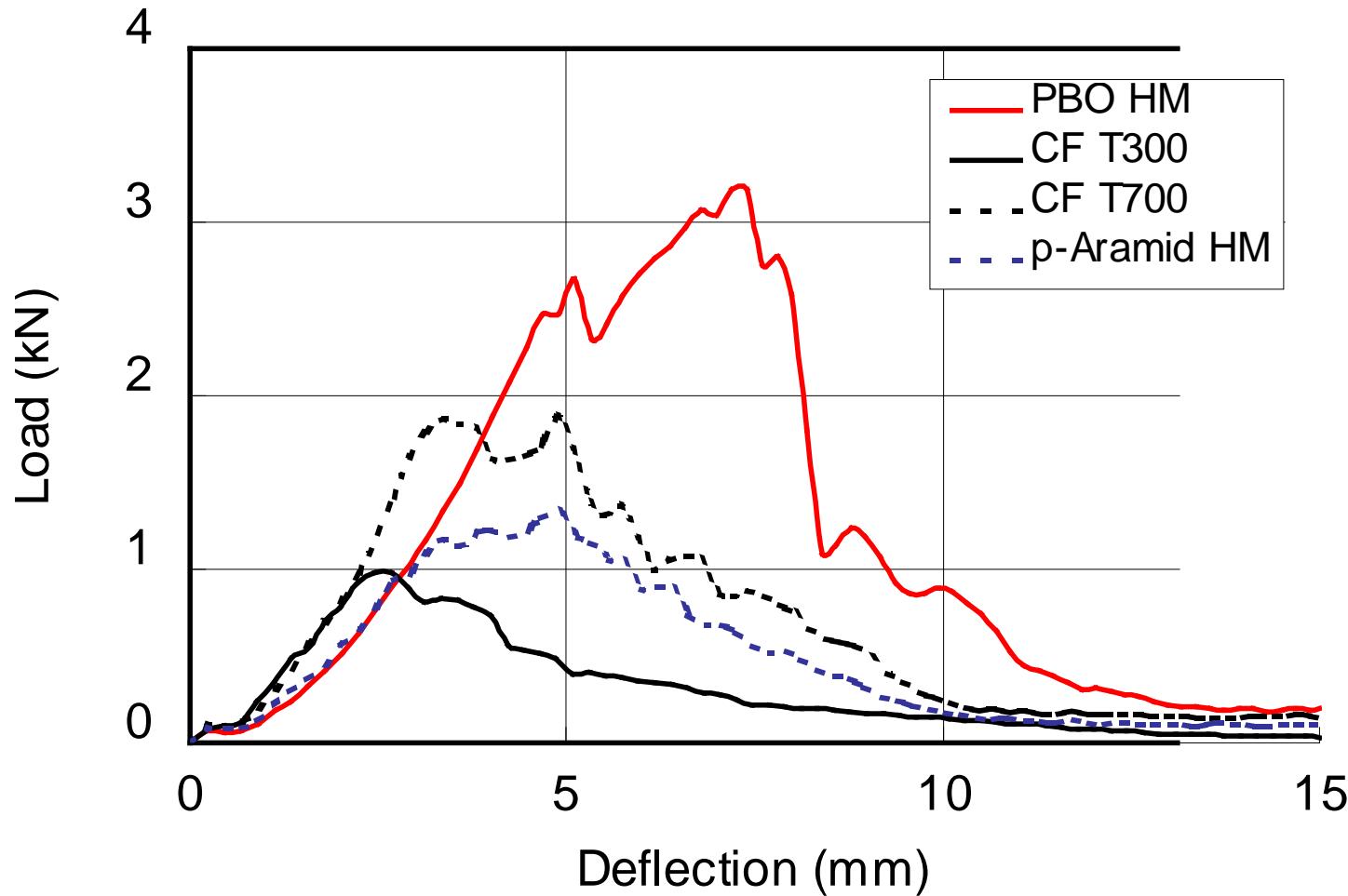
Advantages of prestressing FRP sheets for strengthening



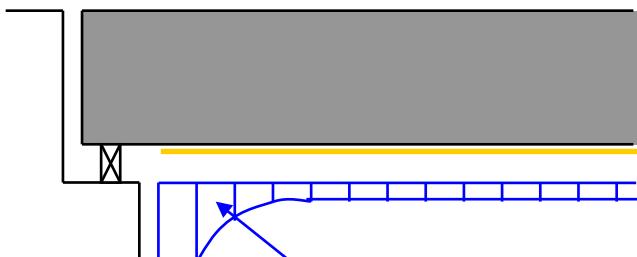
Demonstrate prestressing technique through public test



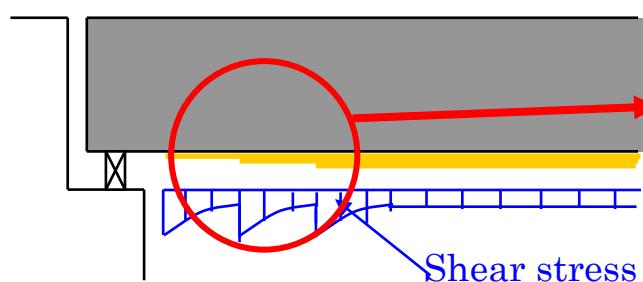
Ability of Energy Absorption From Impact Tests



COUNTERMEASURE FOR RELIEVING SHEAR STRESS CONCENTRATION AT PRESTRESSED FRP ENDS

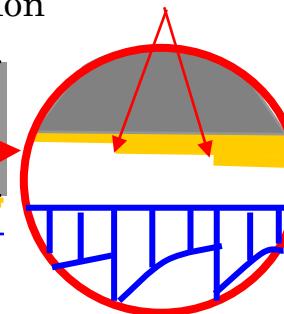


(a) shear stress concentration

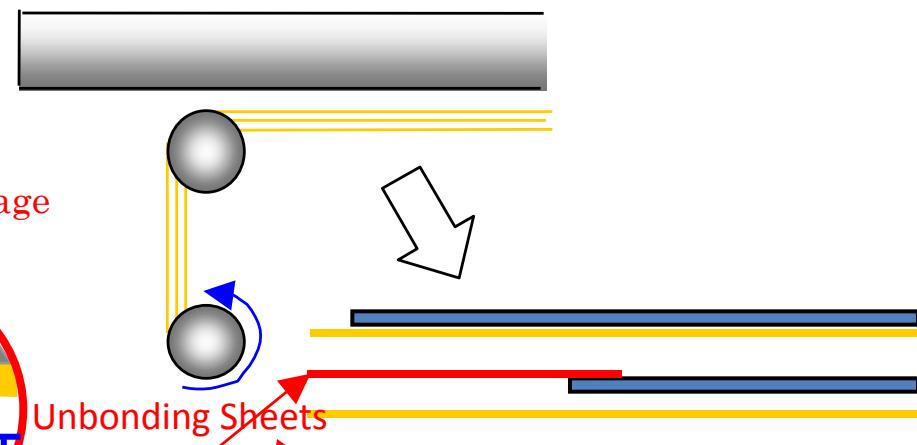


(b) Relieving stress concentration

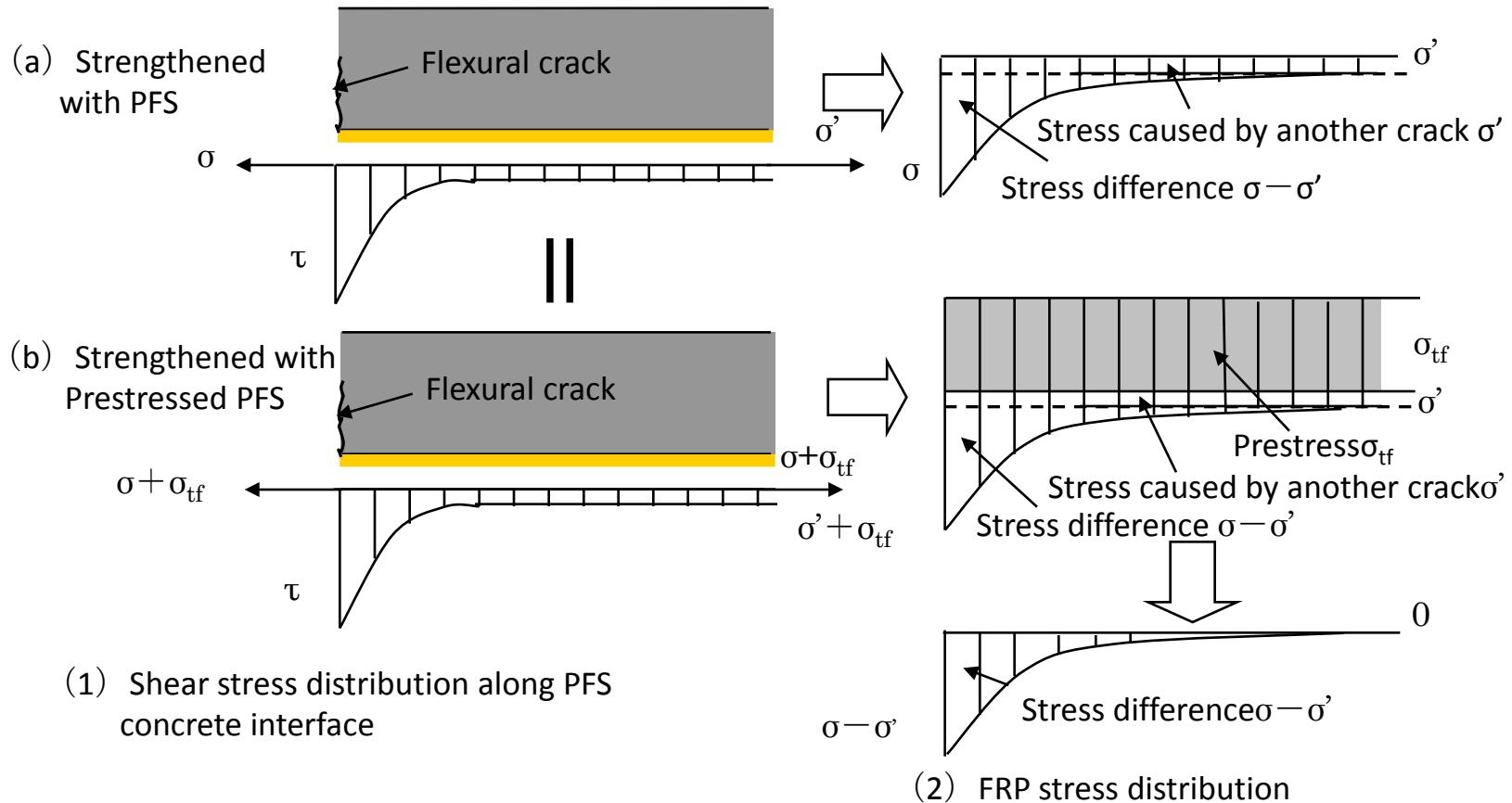
Stage by stage



Unbonding Sheets

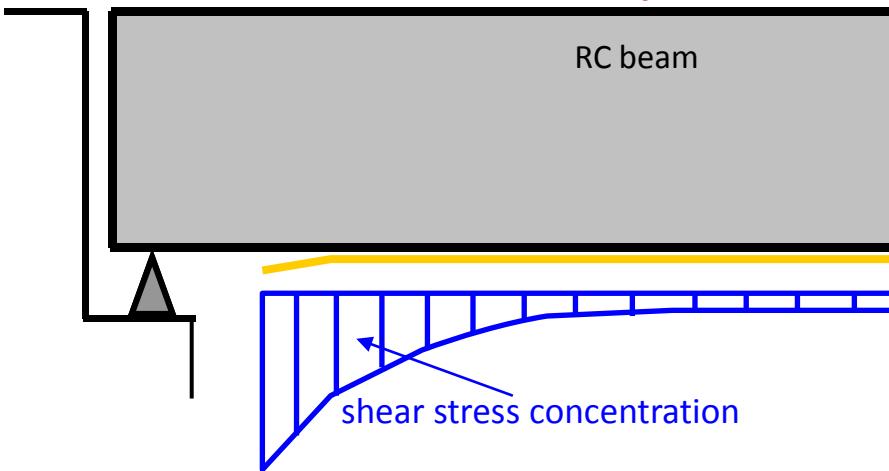


SHEAR STRESS DISTRIBUTION BETWEEN FLEXURAL CRACKS



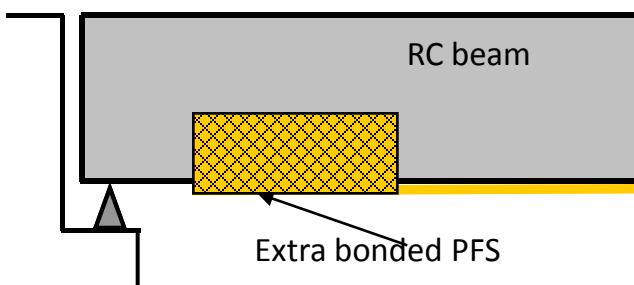
ANCHORAGE TREATMENT

- Stress concentration at FRP ends due to prestressing

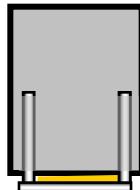
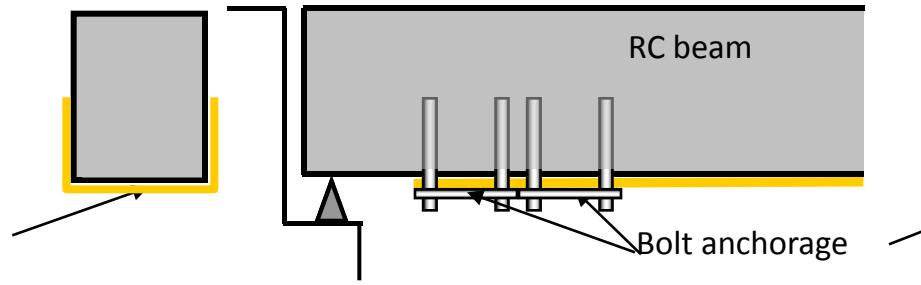


Anchorage Need

- Anchorage with extra bonded PFS

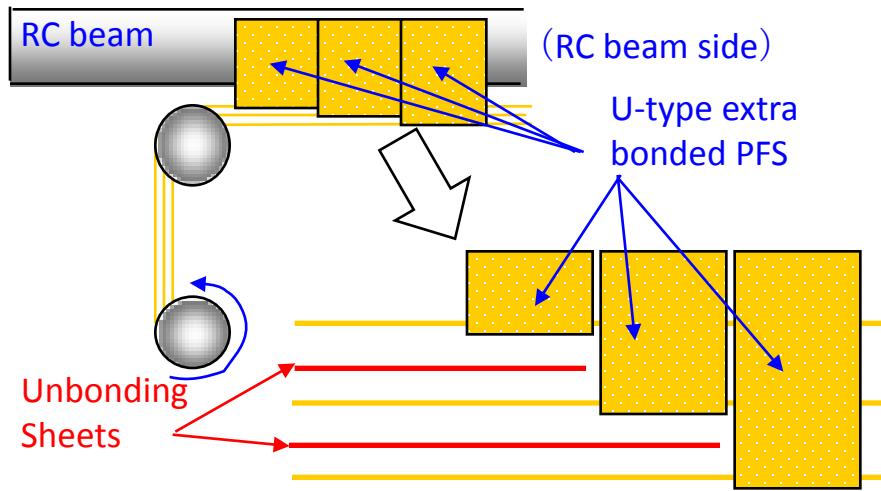


- Anchorage with anchor bolts

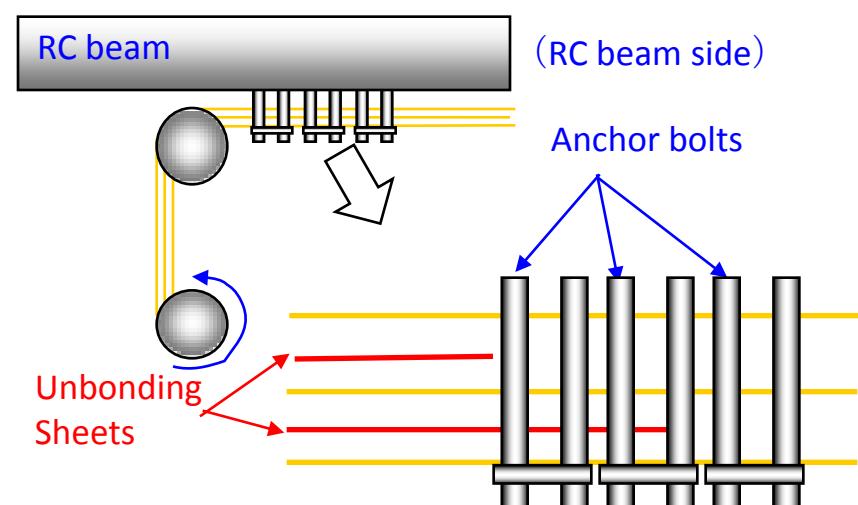


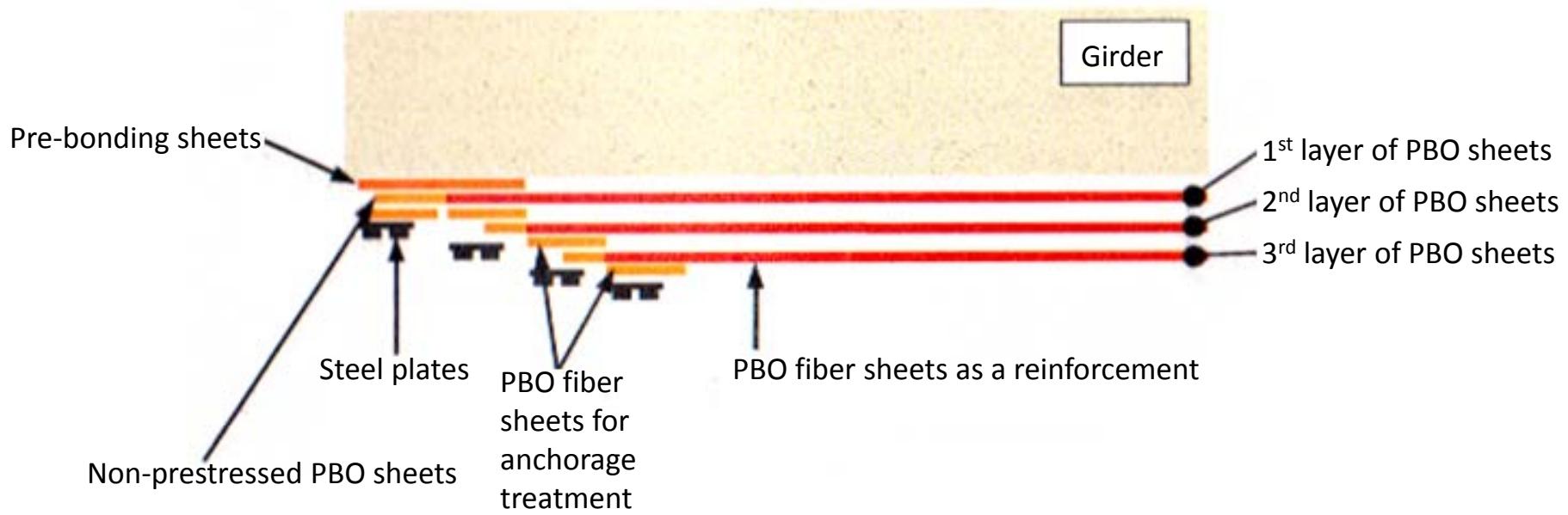
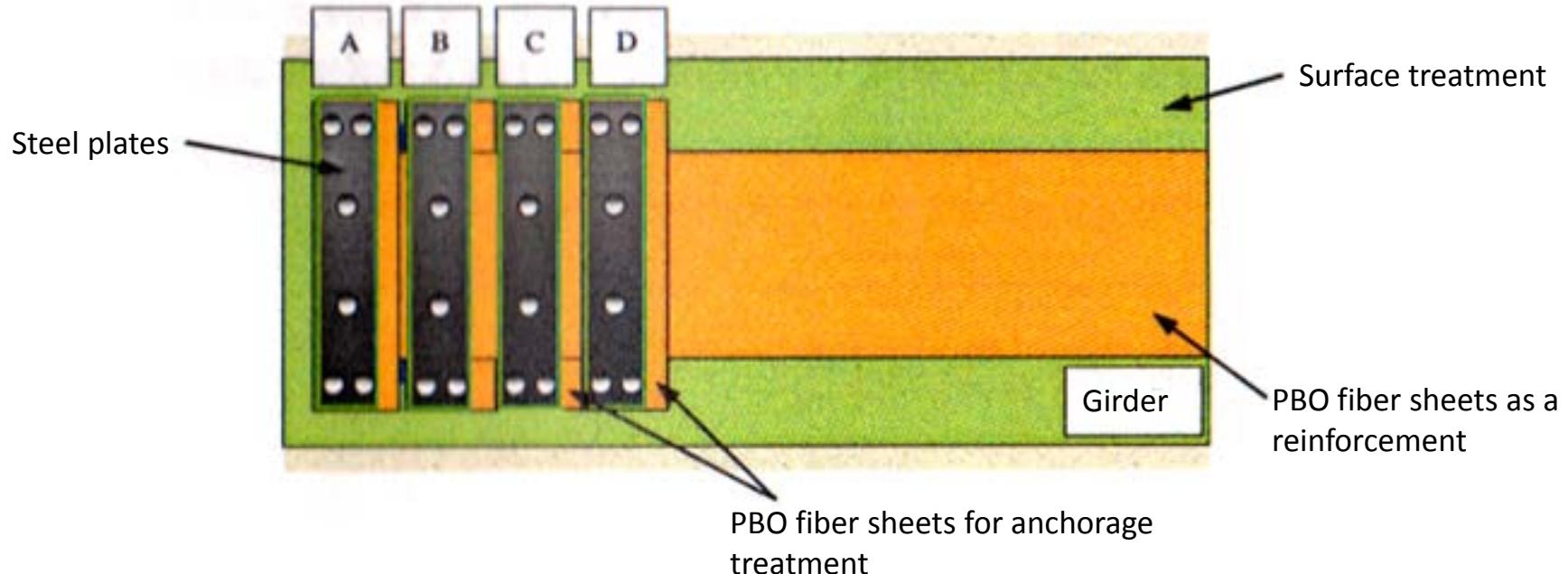
ANCHORAGE TREATMENT

① Anchorage with U-type extra bonded PFS

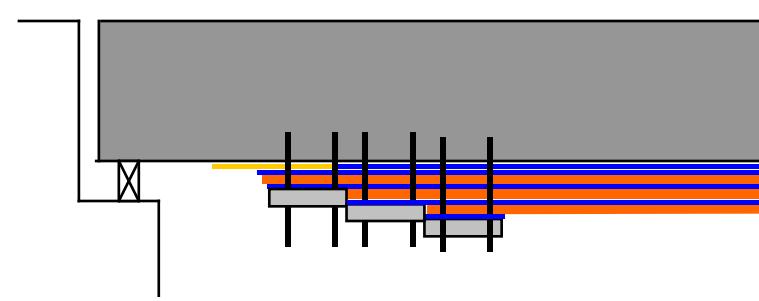
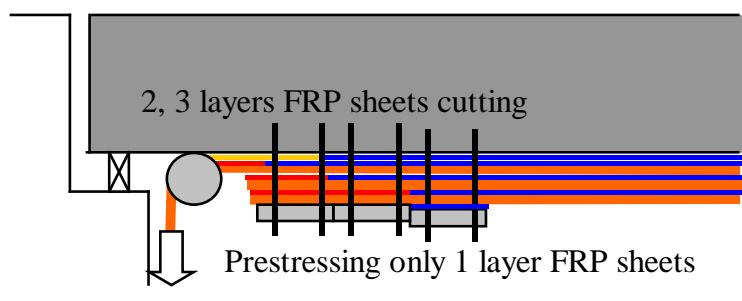
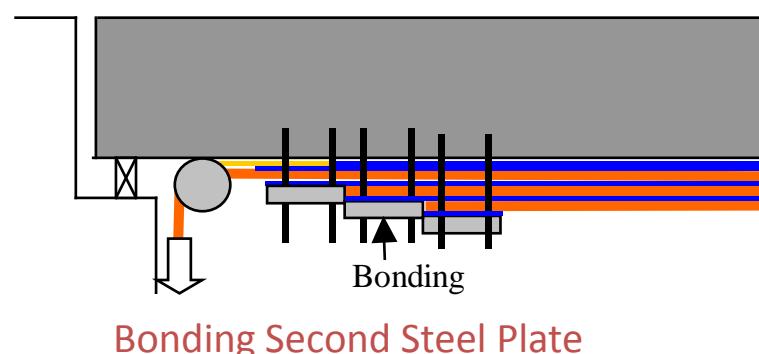
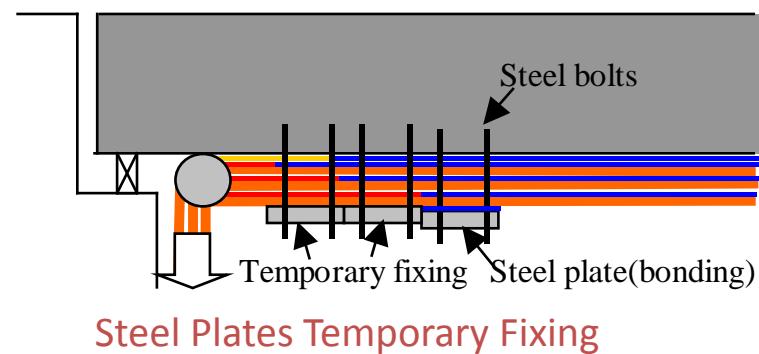
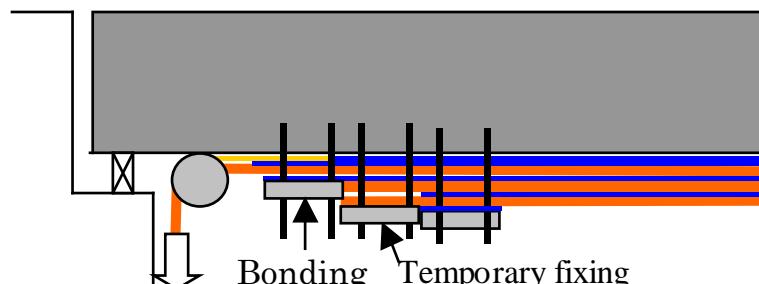
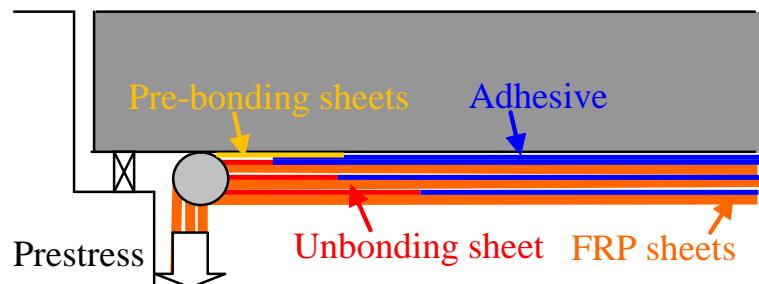


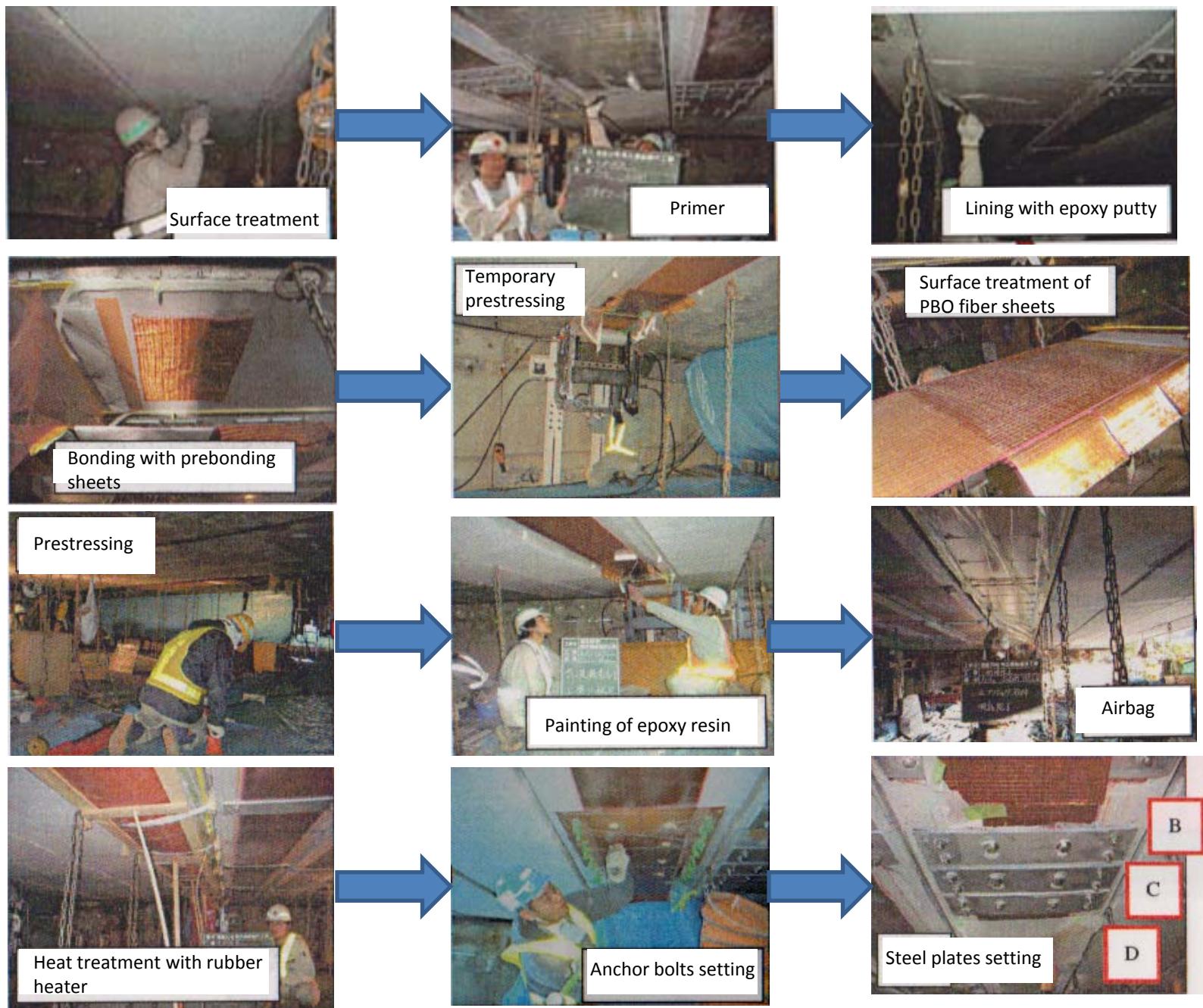
② Anchorage with bolts



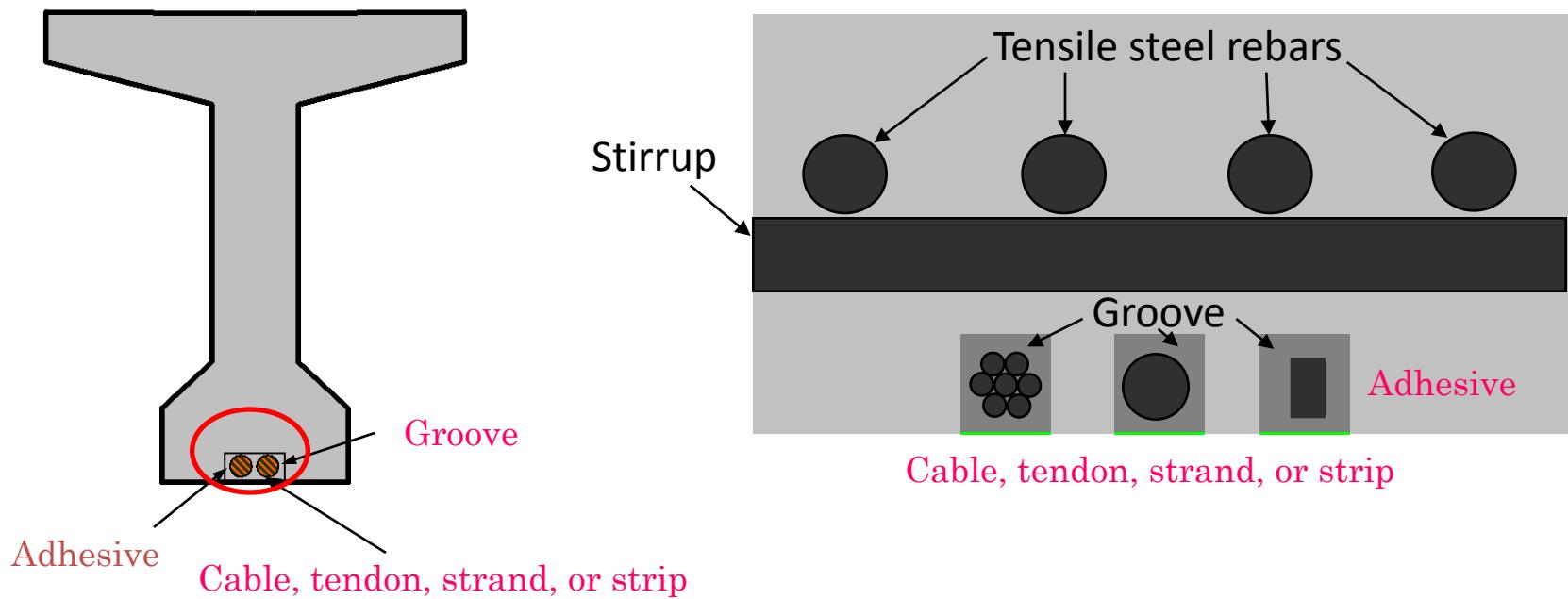
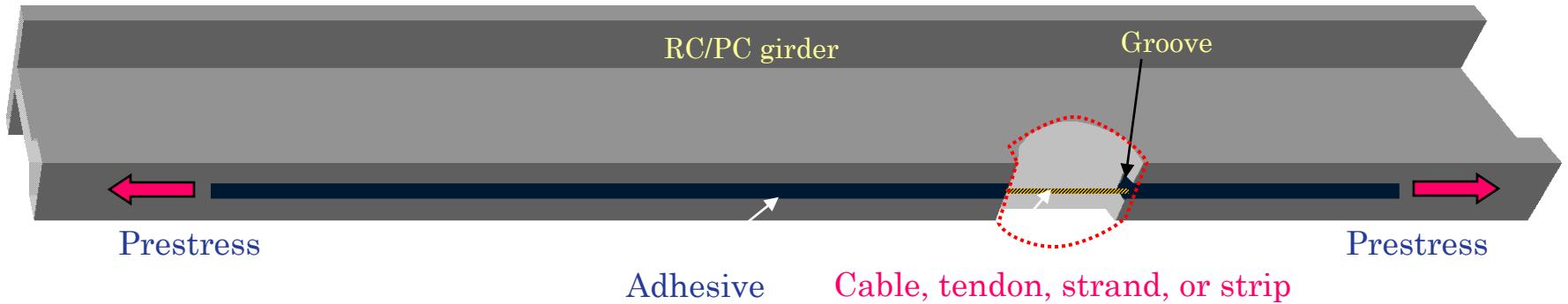


Process of Extra Anchorage Treatments

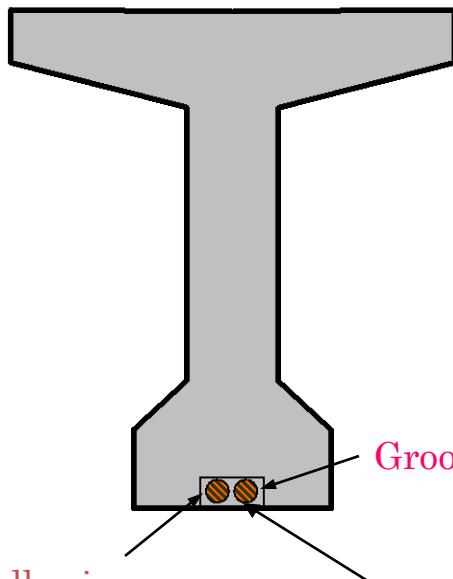
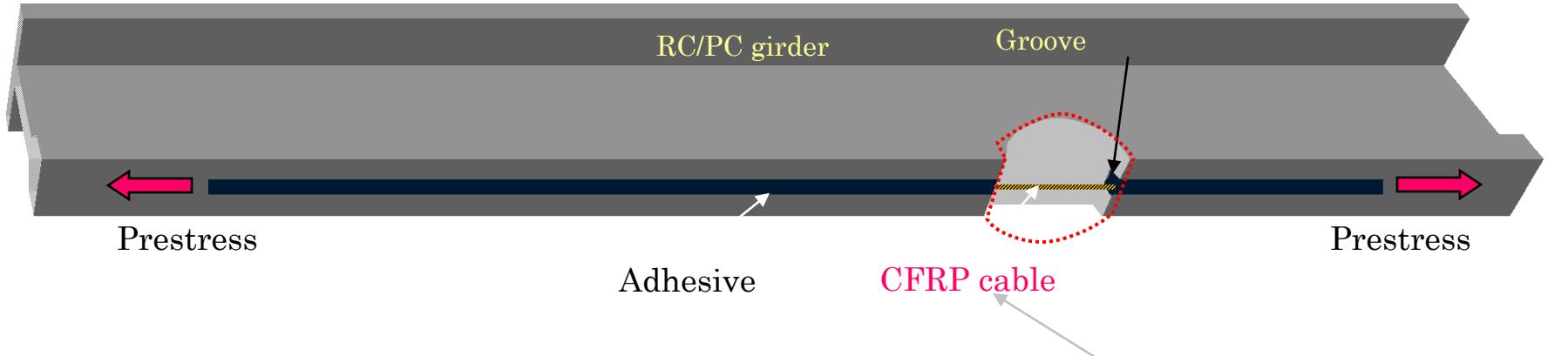




Structural Strengthening with Prestressed Near Surface Mounted (PNSM) FRP Cables



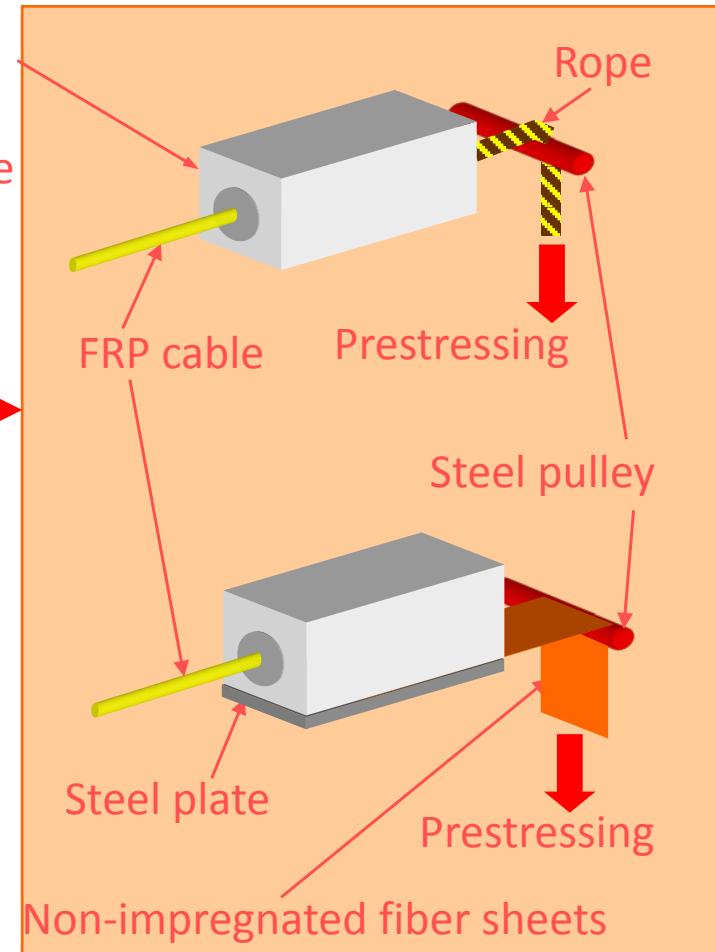
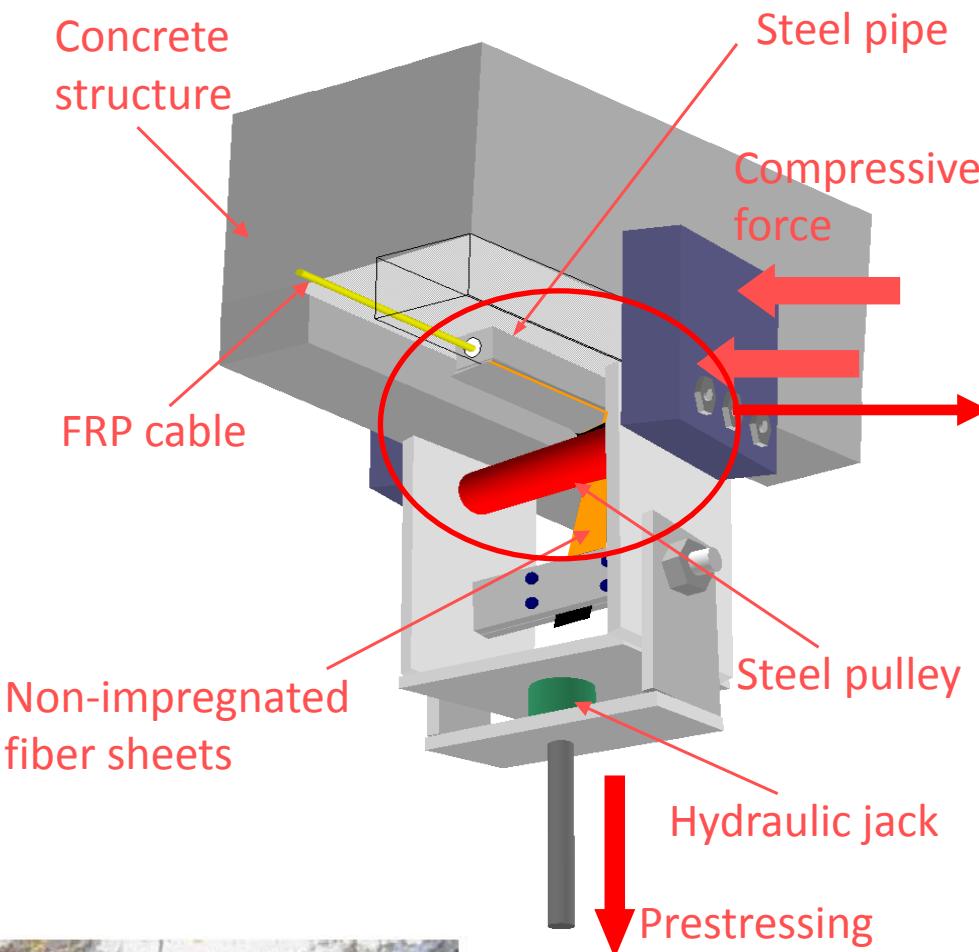
Structural Strengthening with Prestressed Near Surface Mounted (PNSM) FRP Cables



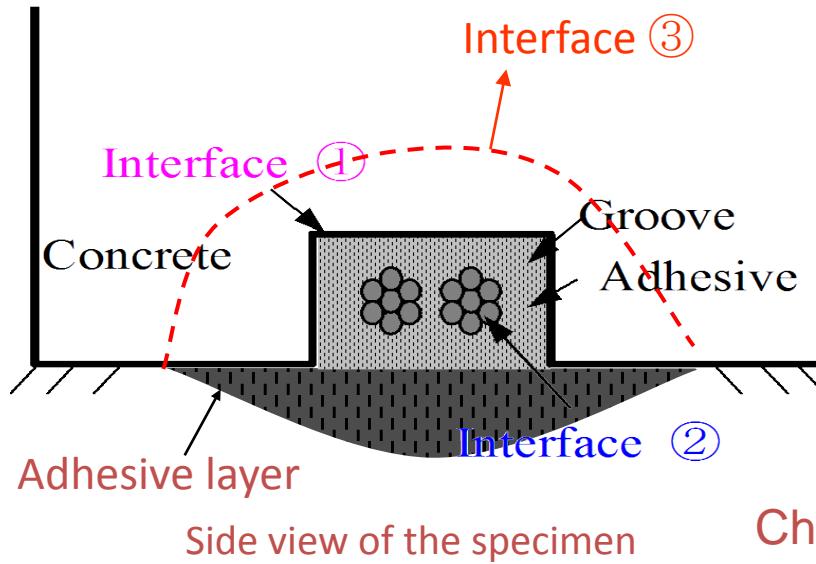
Summary of CFRP strand tendon

CFRP strand tendon	Modulus of elasticity (GPa)	94.9
	Tensile strength (MPa)	2,084
	Rupture strain (%)	2.2
	Relaxation ratio (20 °C, 1000h, 0.7P _u) (%)	3.0
	Nominal cross sectional area (mm ²)	42.78

Prestressing System

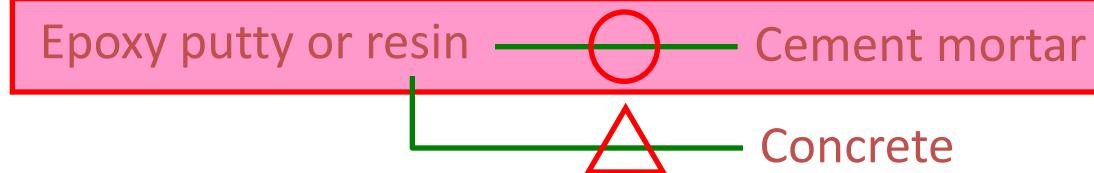
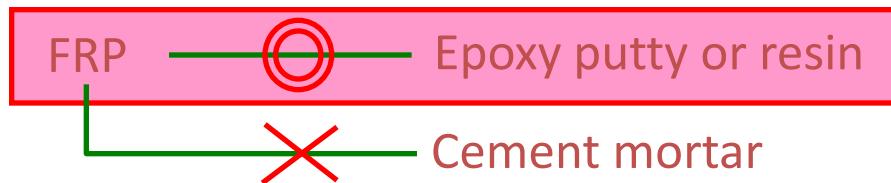


Interfaces of PNSM

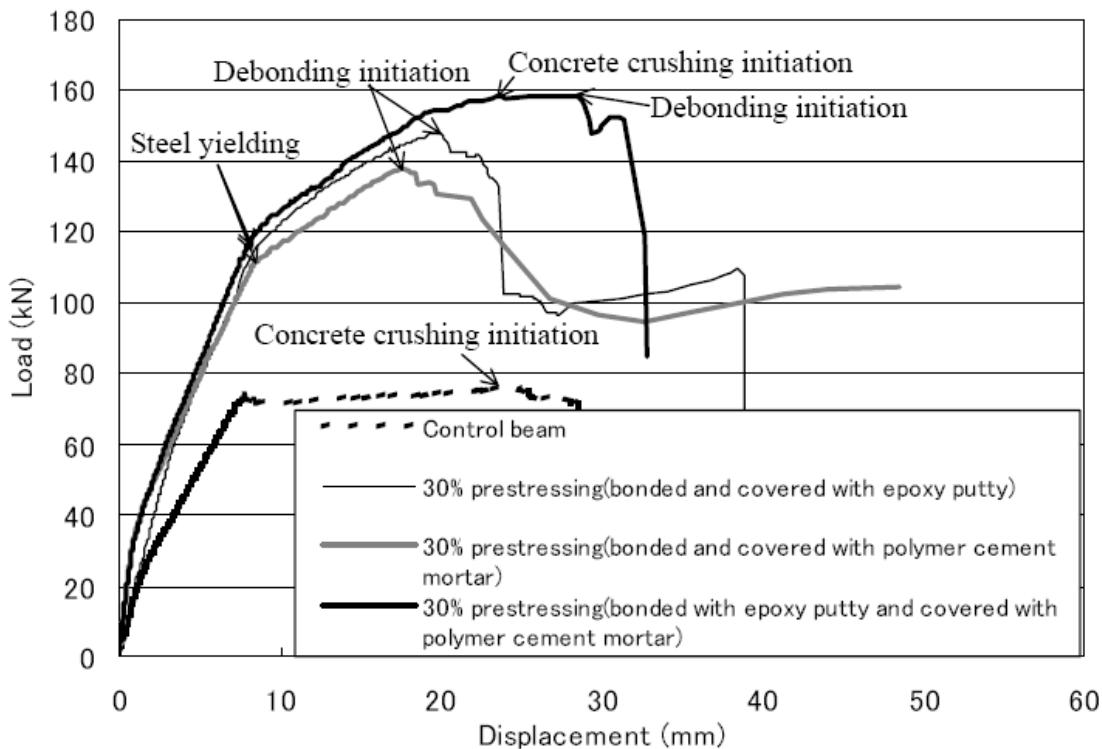
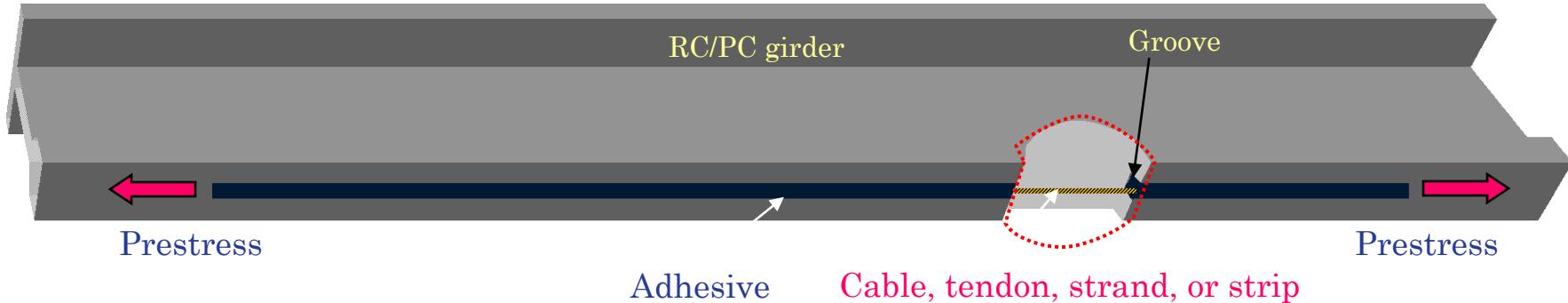


Change failure interface through adhesive layer

○Affinity between materials



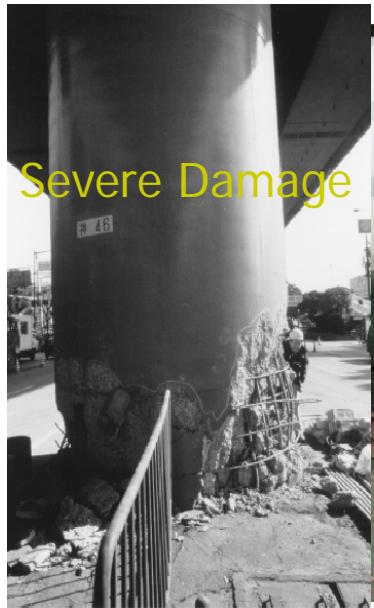
—NSM FRP cables for strengthening structure



Outline

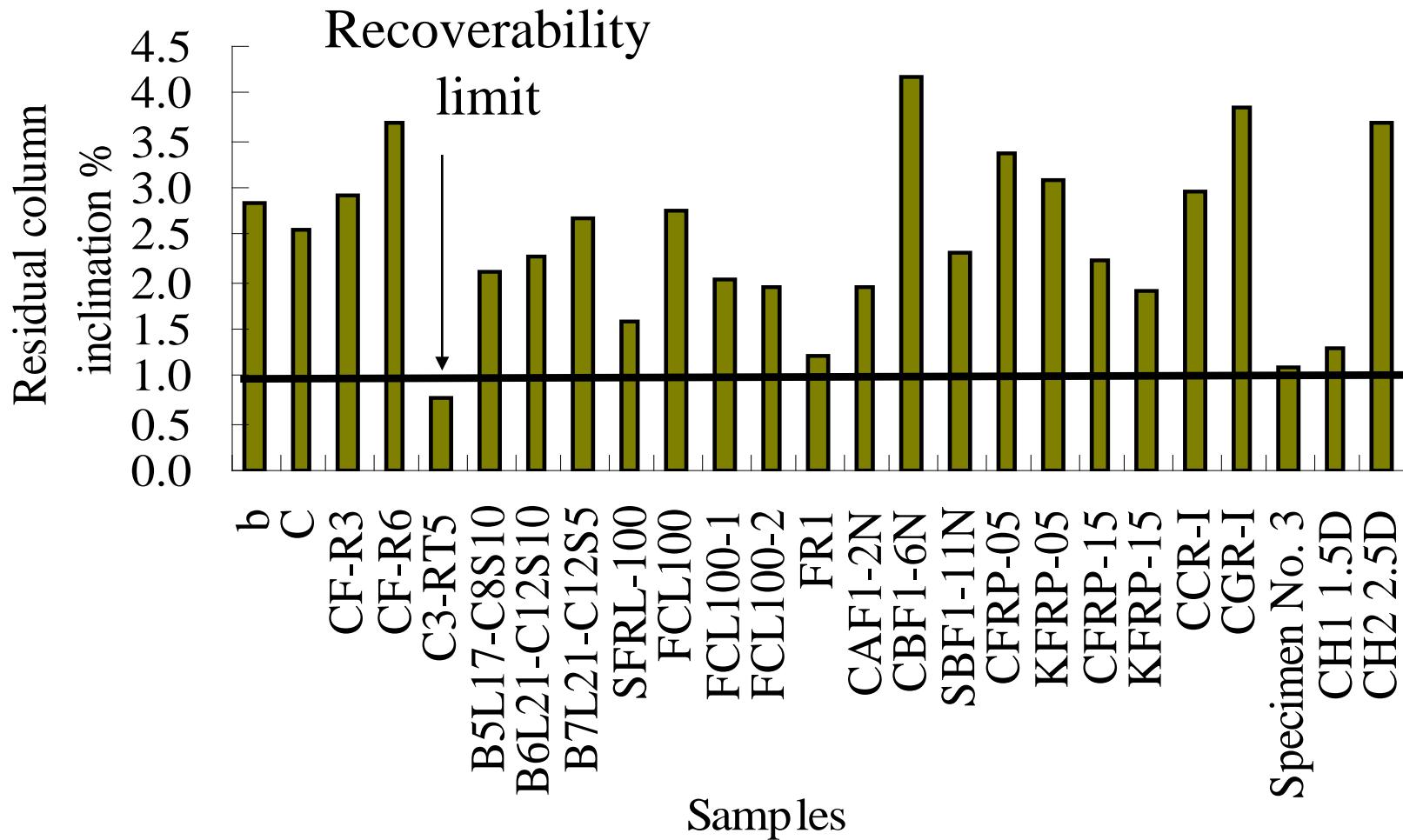
1. **Background**
2. **Introduction of FRP and research status**
3. **Hybrid FRP technology**
4. **Prestressing FRP technology**
5. **Damage-controllable FRP structures**
6. **Integrated high performance FRP structures**
7. **Intelligent infrastructures**
8. **Summary**

Facts

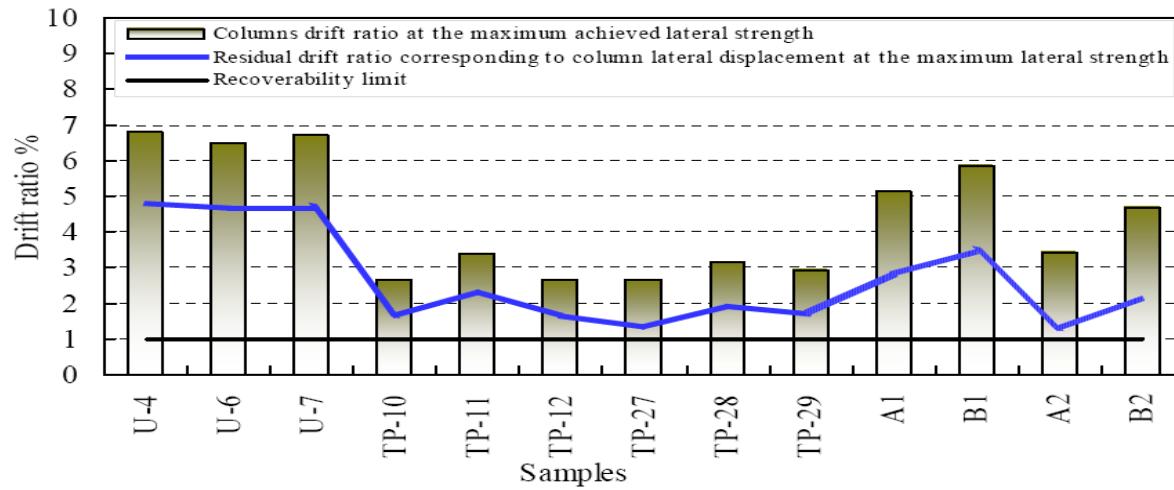
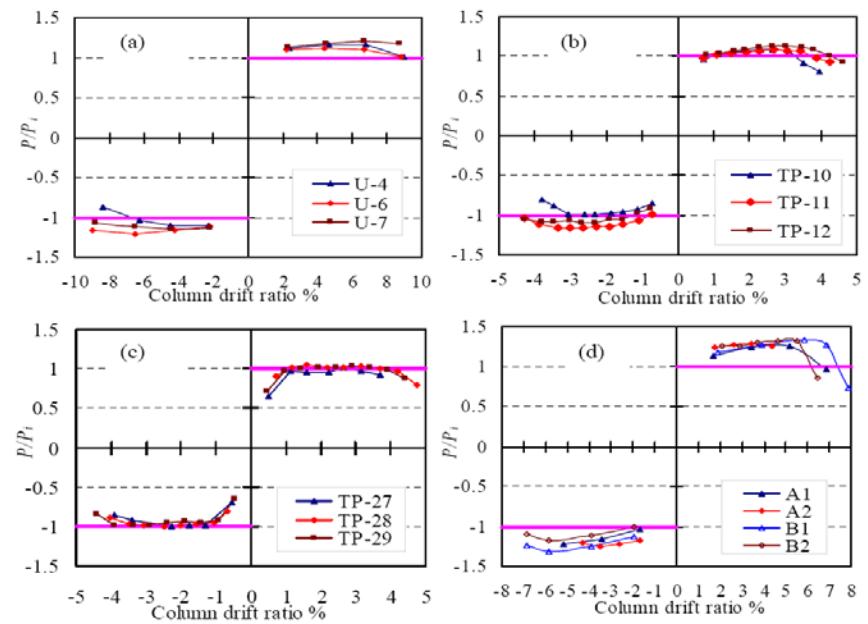
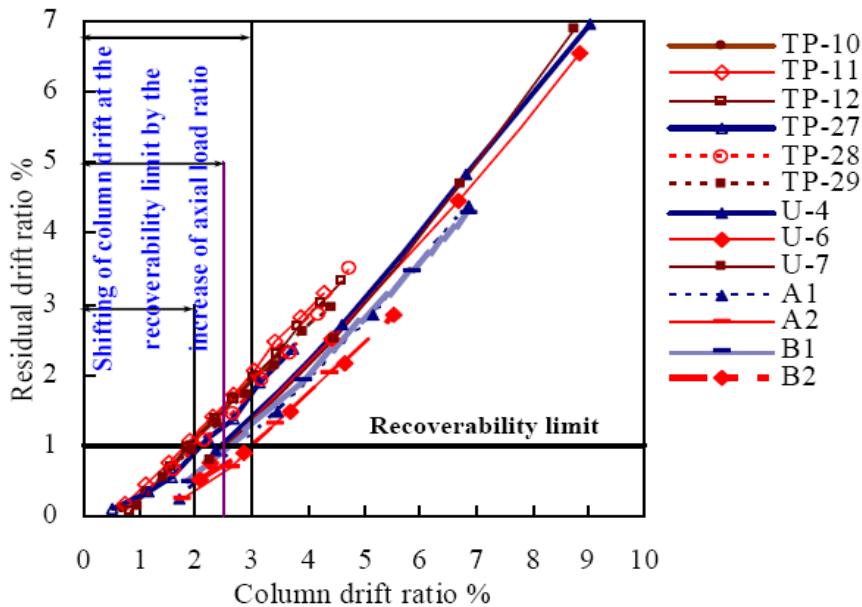


There are different damage levels under the effect of strong Earthquake.

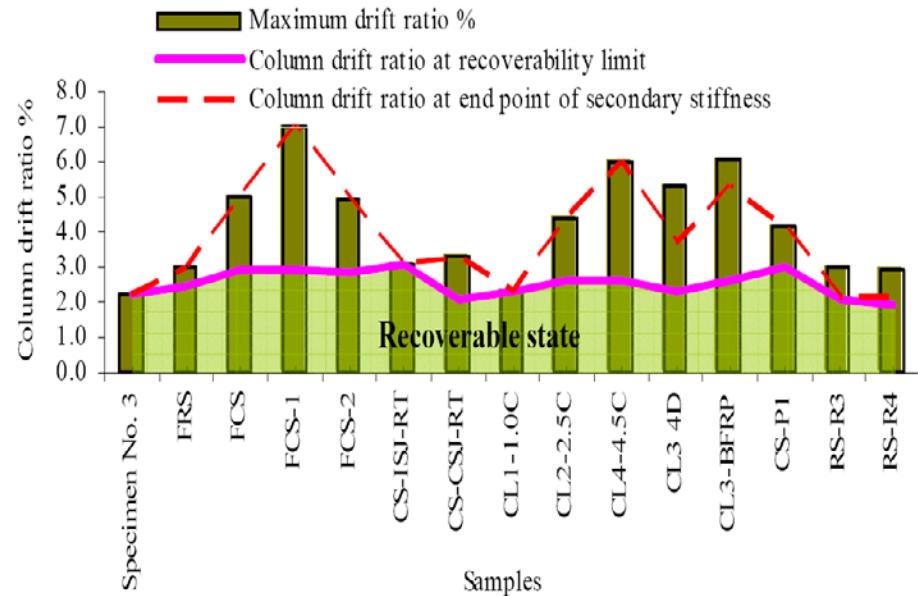
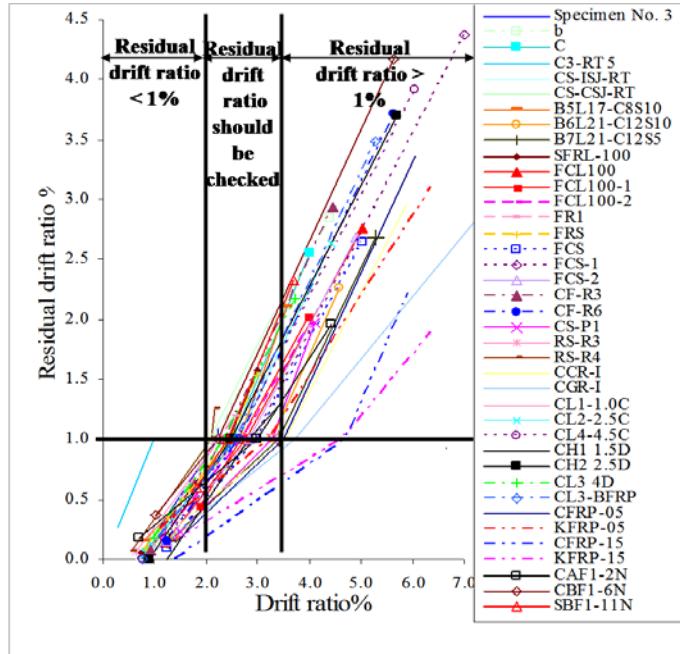
Seismic Performance Evaluation of FRP Retrofitted Columns Using Residual Deformation Index



— Damage recoverability of common RC column

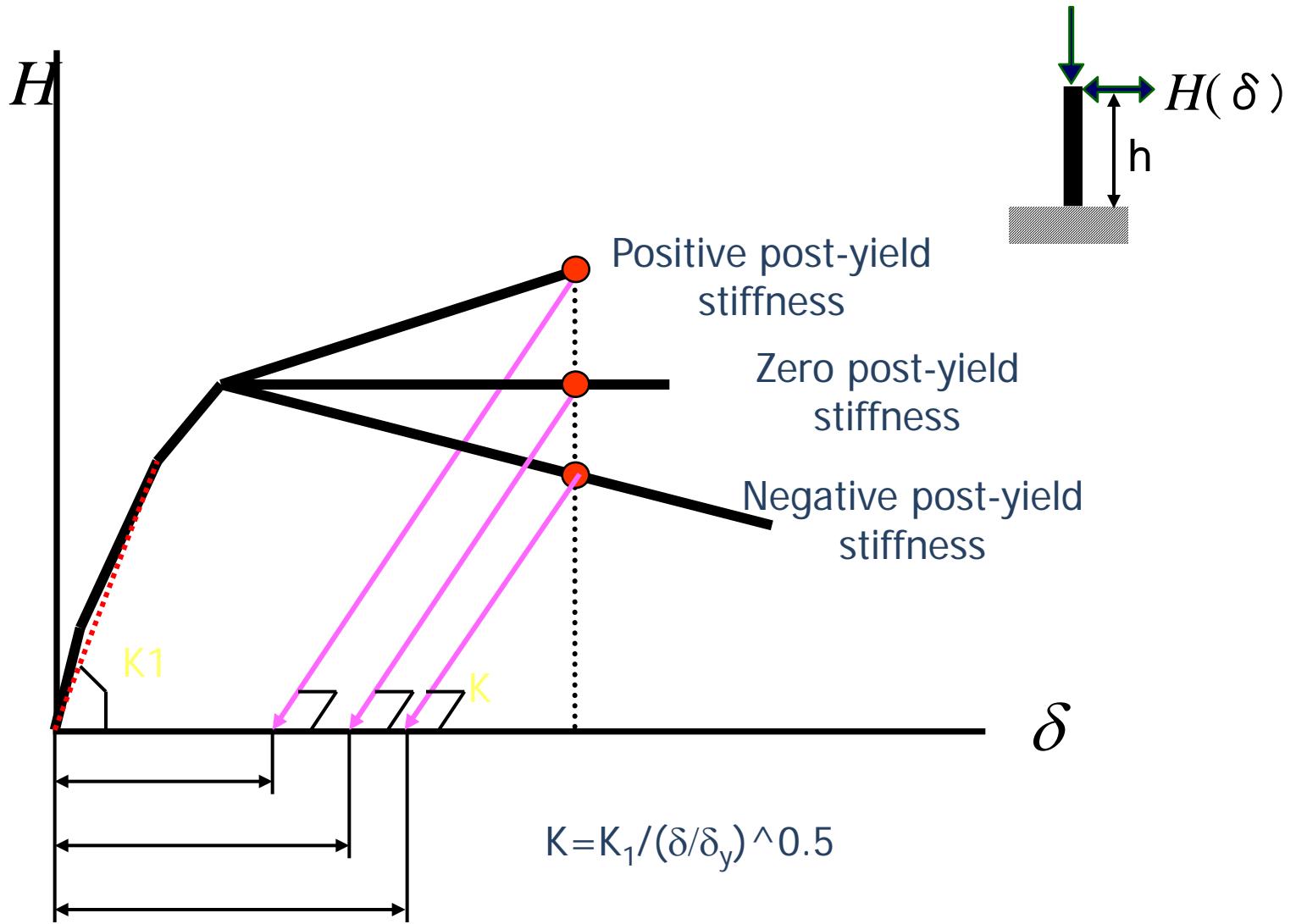


Seismic performance of FRP confined RC column FRP

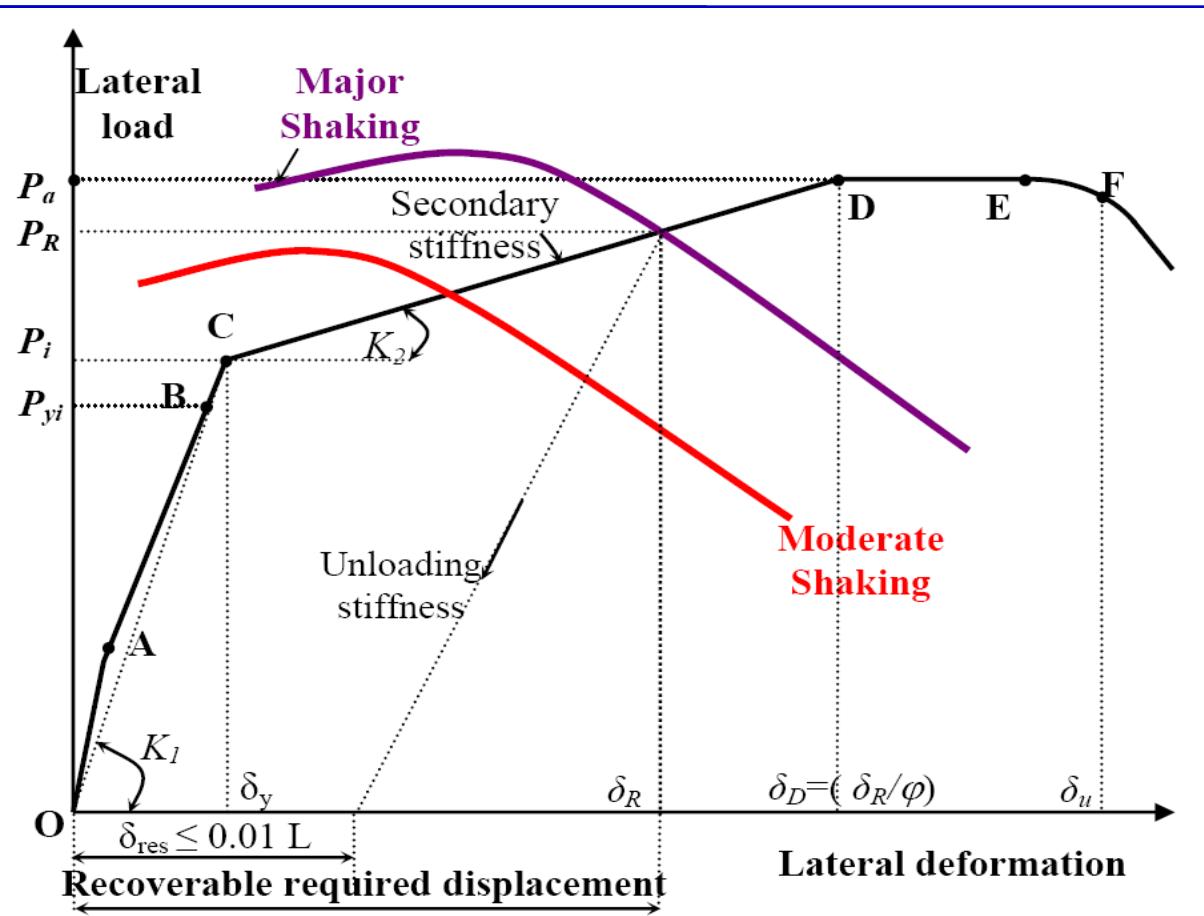


Column deficiency	Shear		Lap-splice		Flexural	
Cross-section	Circula	Rectangul	Circula	Rectangul	Circular	Rectangular
$\phi = (\delta_{\text{dres}}=0.01L / \delta_D)$	0.53	0.89	0.591	0.672	0.565	0.686

Importance of Post-Yield Stiffness in Seismic Design



Design method of FRP confined RC column FRP



$$P_a \geq S_{es} W$$

$$S_{es} = S_s / \sqrt{2\mu_a - 1}$$

$$\mu_a = 1 + \frac{\delta_u - \delta_y}{\alpha \delta_y}$$

$$P_a = P_i \left(1 + 0.55 \frac{f_l}{f_{co}} \right) = P_i \lambda$$

Assume the confinement ratio

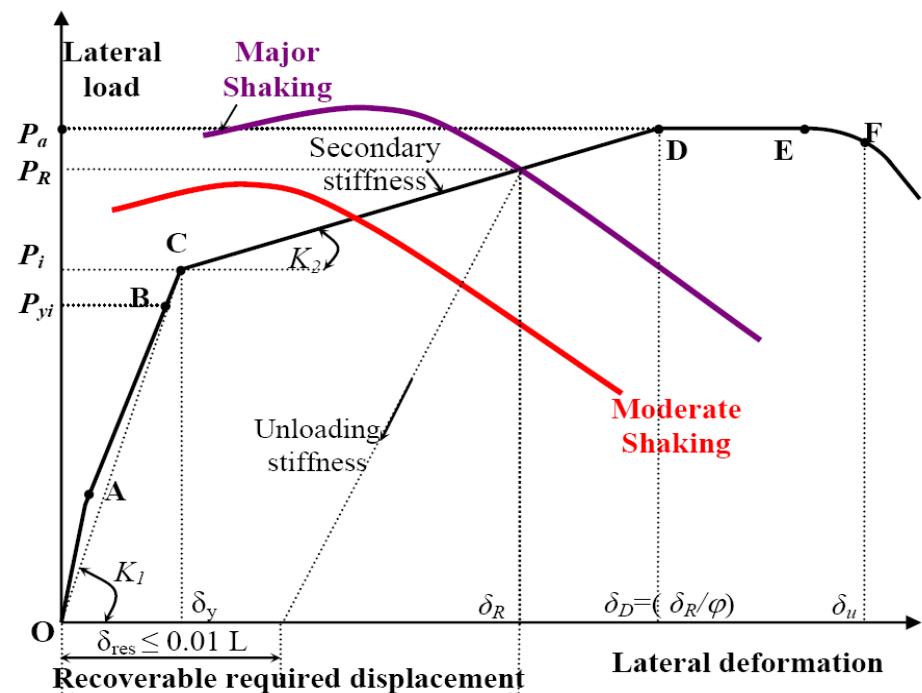
$$P_R = P_i \left(1 + 0.55\varphi \frac{f_l}{f_{co}} \right)$$

$$\mu_R = \frac{1}{2} \left\{ \left(\frac{S_s W}{P_R} \right)^2 + 1 \right\}$$

$$\delta_{u,req} = \delta_y \left\{ \alpha(\mu_R - 1) + 1 \right\}$$

$$\delta_{Rmax} = \frac{0.01L}{C_R \left(1 - \frac{K_2}{K_1} \right)} + \delta_y$$

$$\delta_{Rmax} = \frac{0.018L}{1 - \frac{(\lambda - 1)}{\left(\frac{\mu_R}{\varphi} - 1 \right)}} + \delta_y$$



$$K_1 = \frac{P_i}{\delta_y}$$

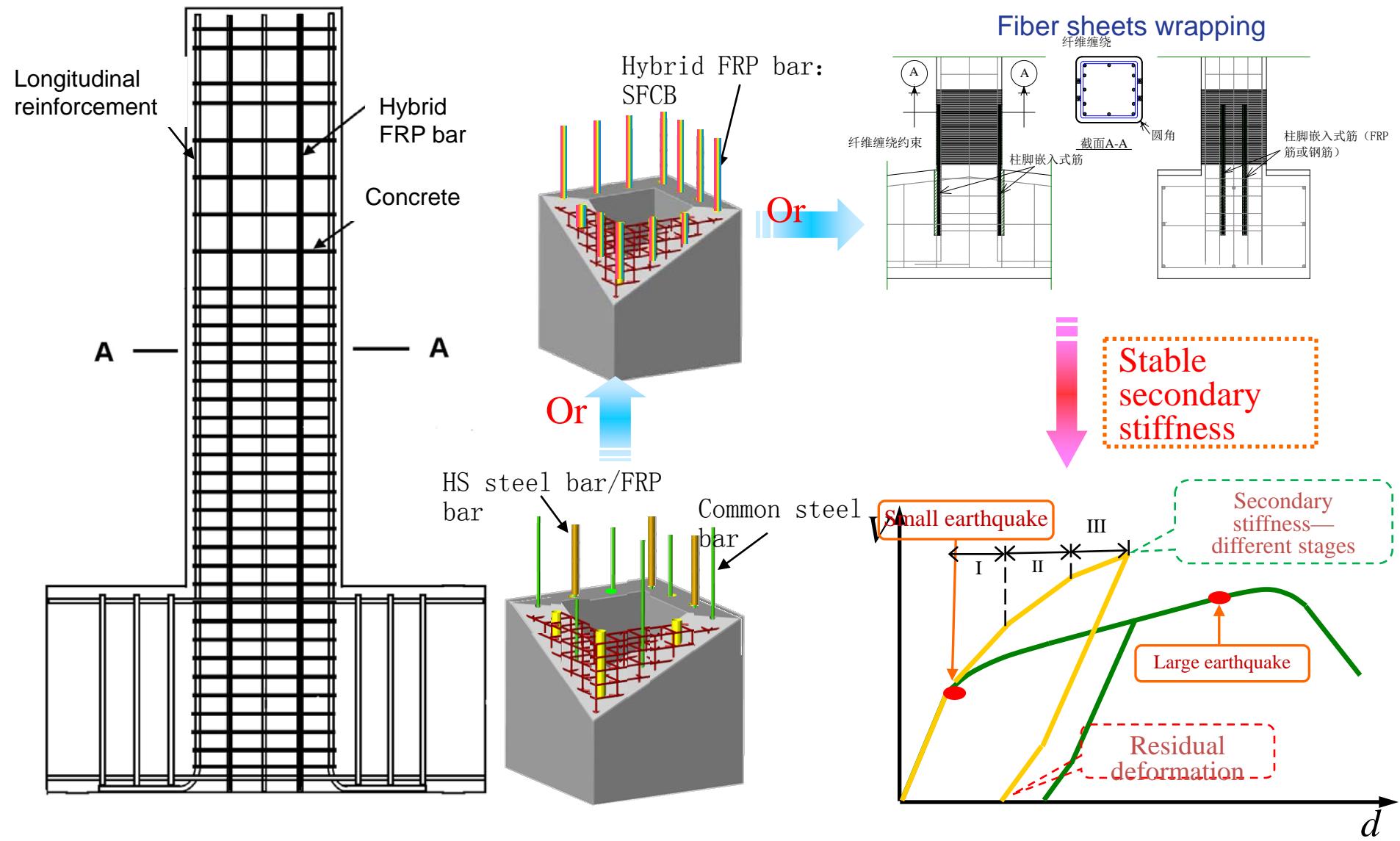
$$K_2 = \frac{P_a - P_i}{\delta_D - \delta_y}$$

$$K_2 / K_1 = \frac{(\lambda - 1)}{\left(\frac{\mu_R}{\varphi} - 1 \right)}$$

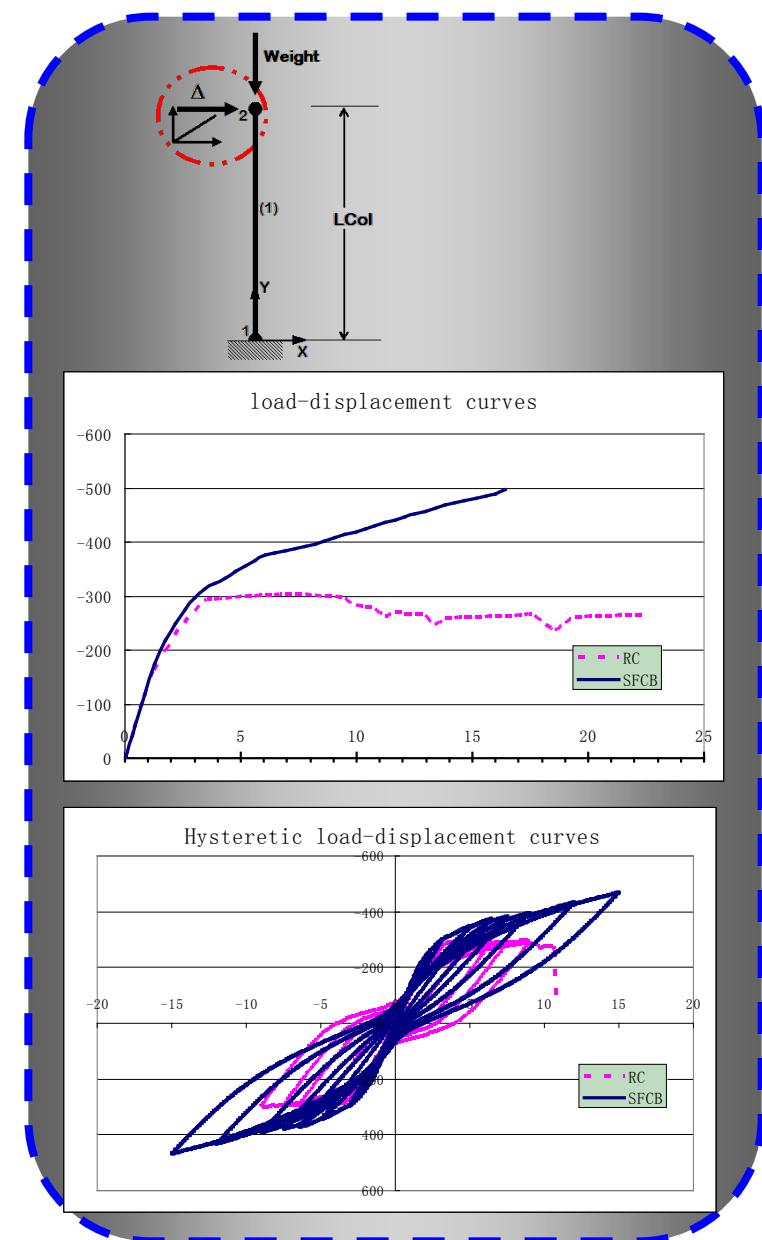
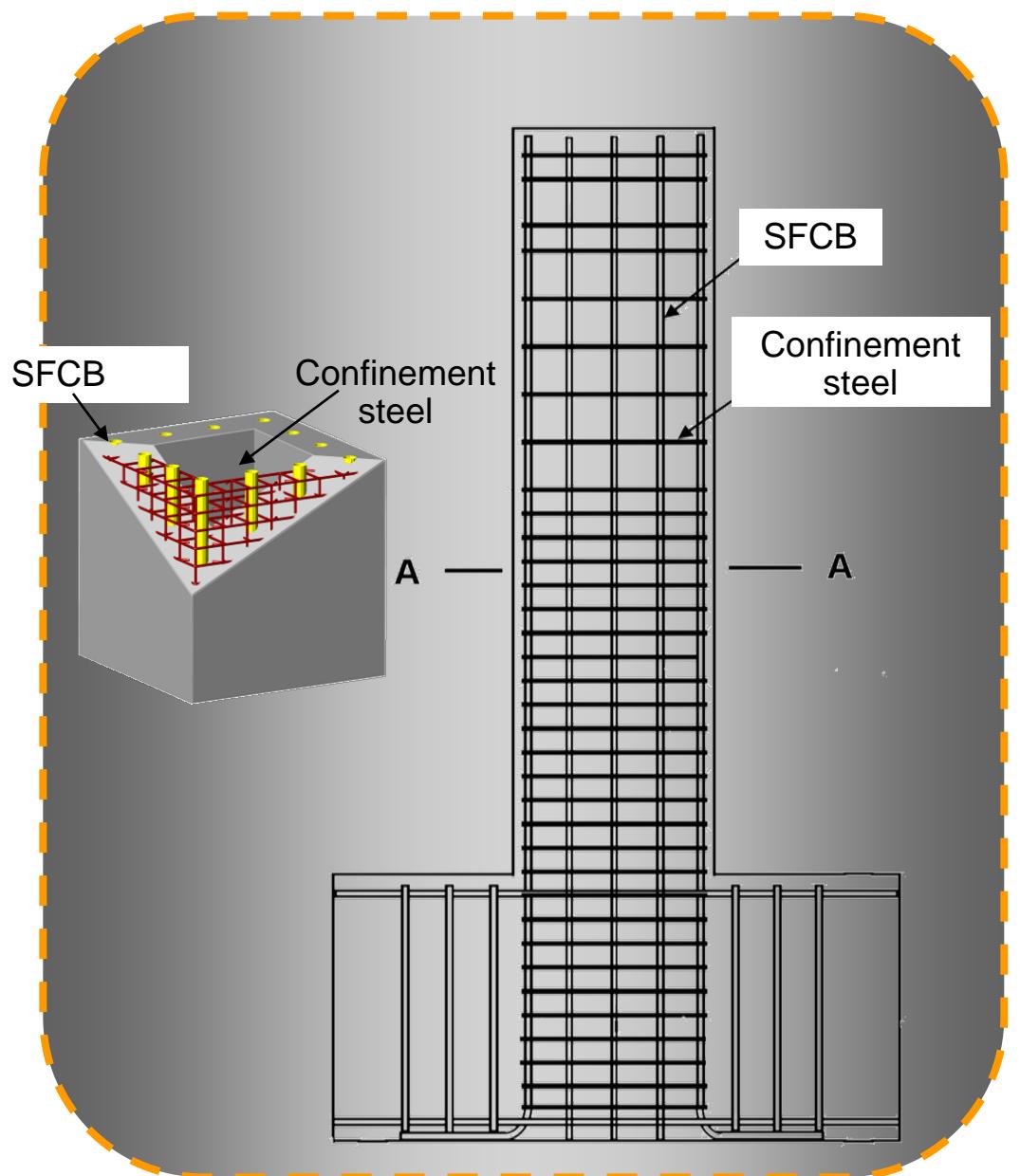
Check

$$(\delta_R = \mu_R \delta_y) \leq \delta_{Rmax}$$

New type damage-control aseismic structure

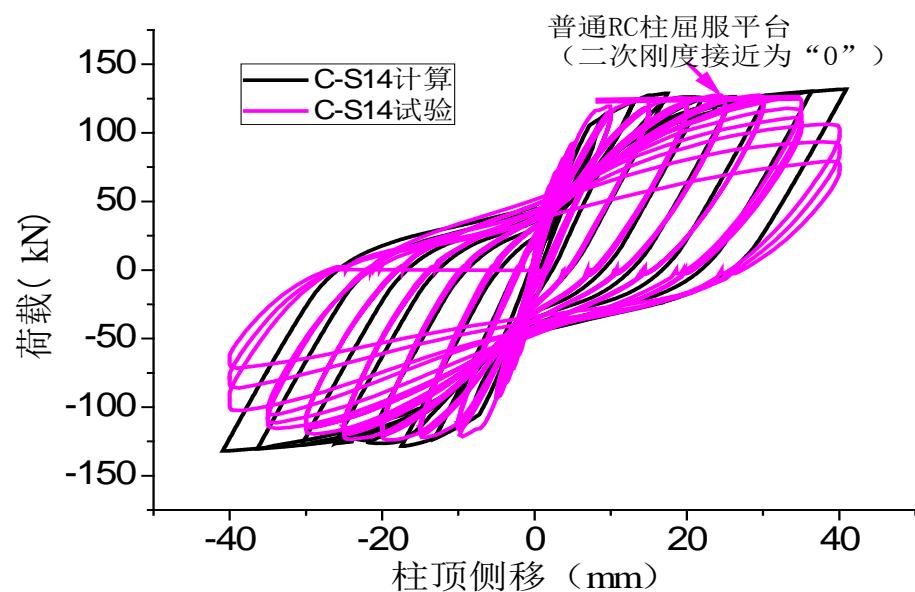


Numerical simulations on proposed column with SFCB

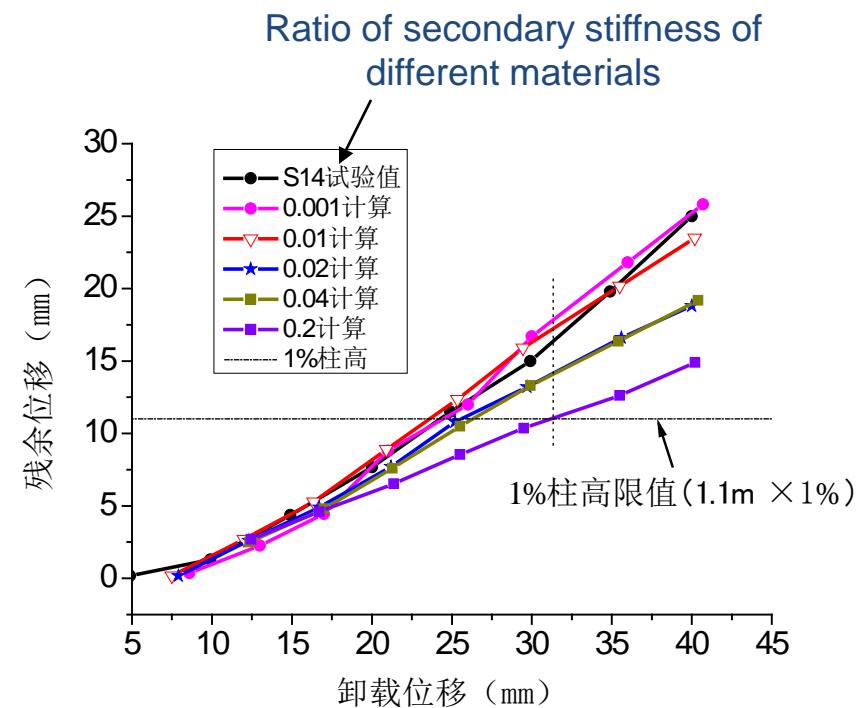


New type damage-control aseismic structure

Theoretical calculation of residual deformation of SFCB reinforced RC column



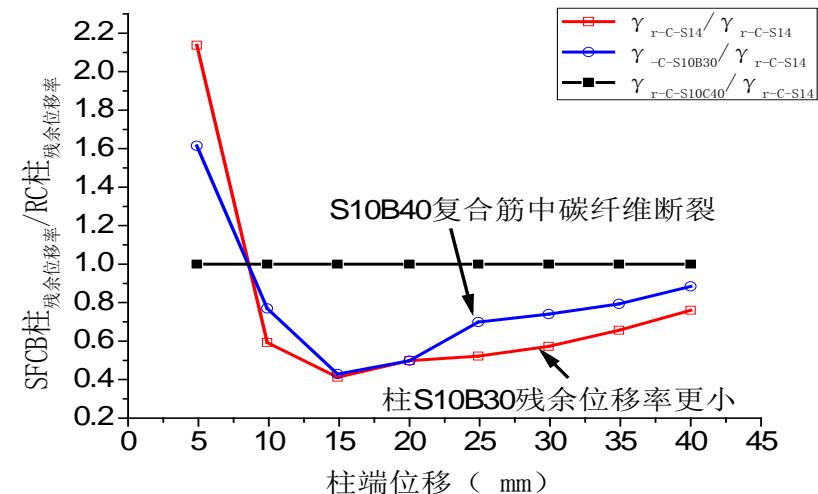
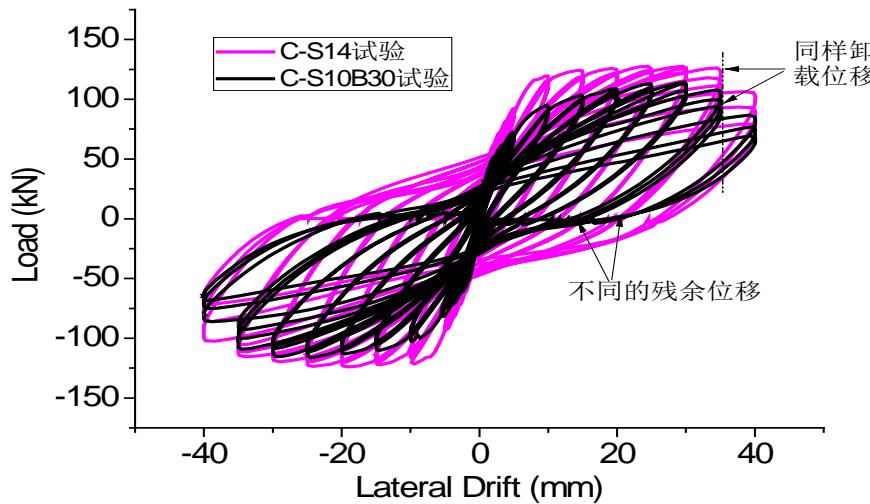
Experimental and theoretical hysteresis curves of common RC beams



Comparison of residual deformation of SFCB reinforced column

New type damage-control aseismic structure

Comparison of residual deformation of SFCB column and normal RC column



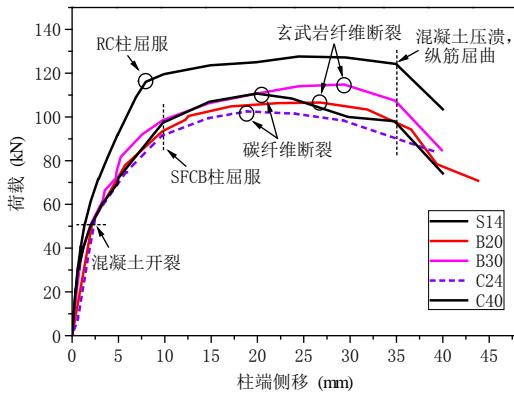
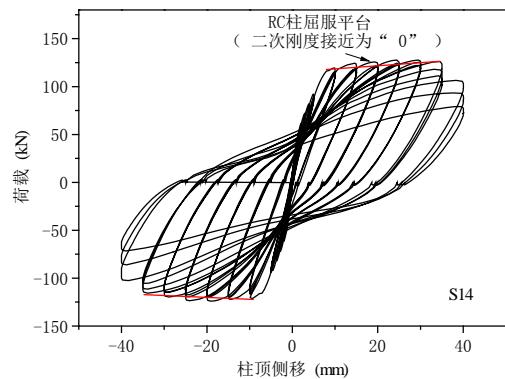
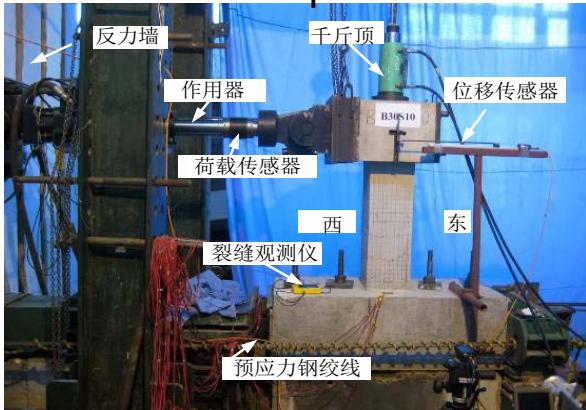
In small deformation, residual deformation of SFCB column is larger than that of RC column

In large deformation, residual deformation of SFCB column is smaller than that of RC column

In ultimate stage, with the fracture of FRP, similar residual deformation is shown for SFCB and normal RC column.

Experiment of SFCB strengthening RC column

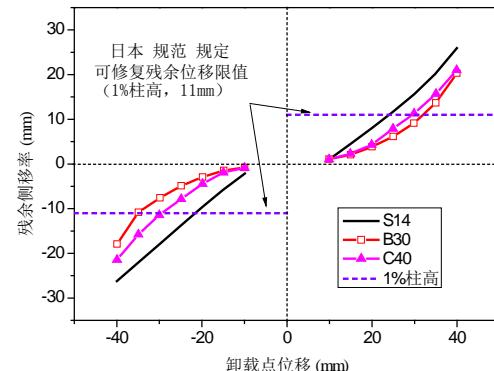
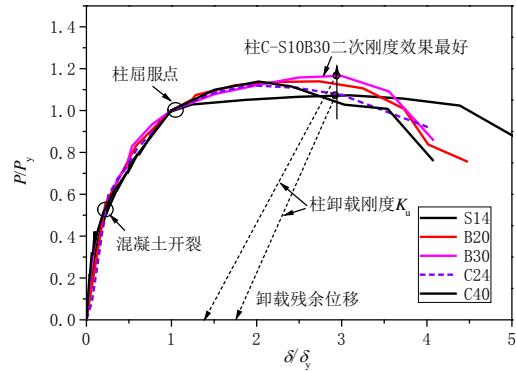
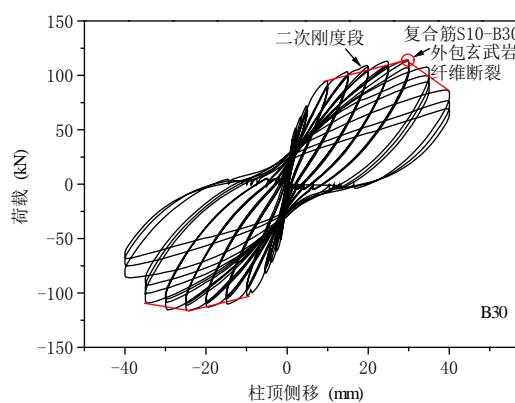
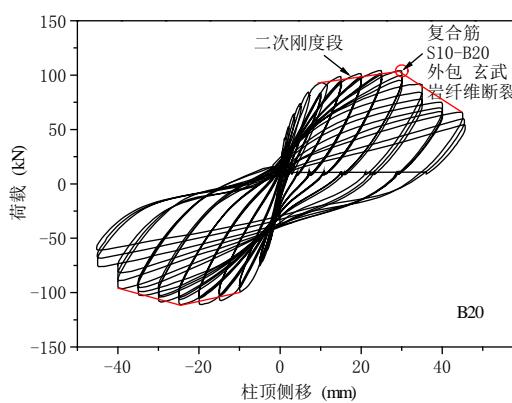
Test set-up



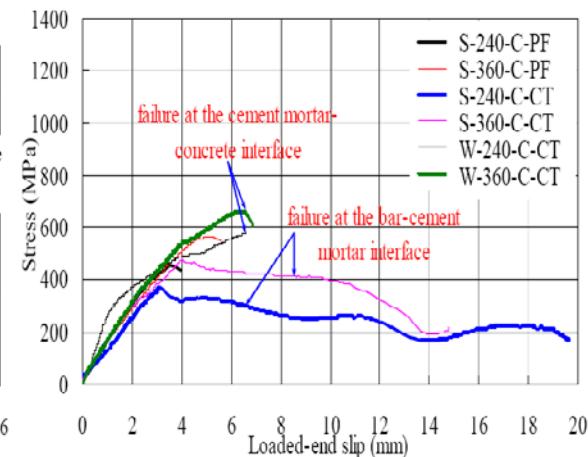
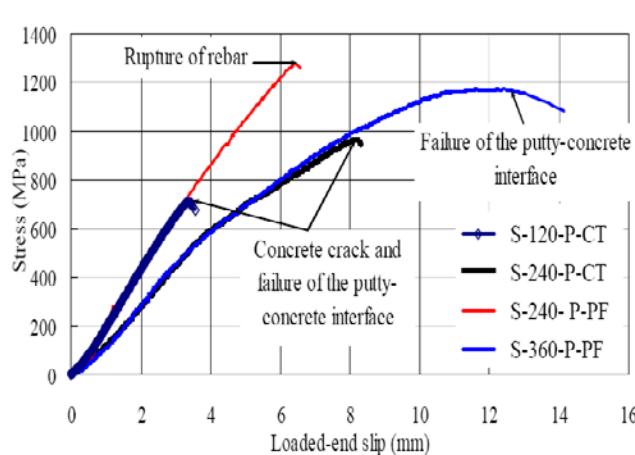
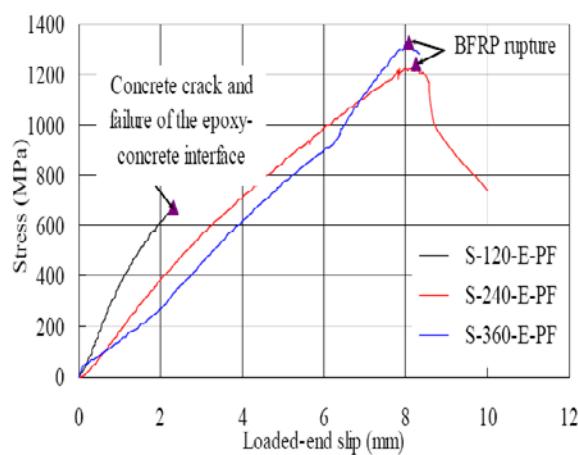
Concrete crush, rebar yield



Partial fracture of fibers



Bonding test of NSM BFRP bar in the column base



S-120-E-PF



S-240-E-PF



S-360-E-PF



S-120-P-CT



S-360-P-PF



S-240-C-PF

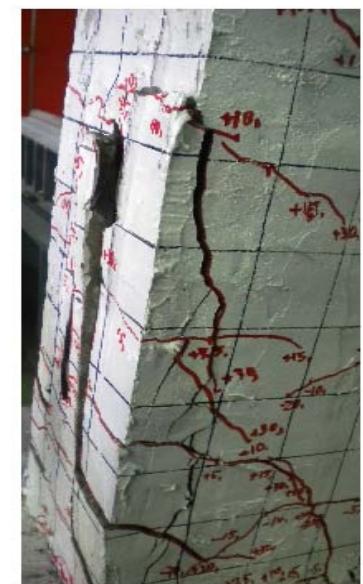
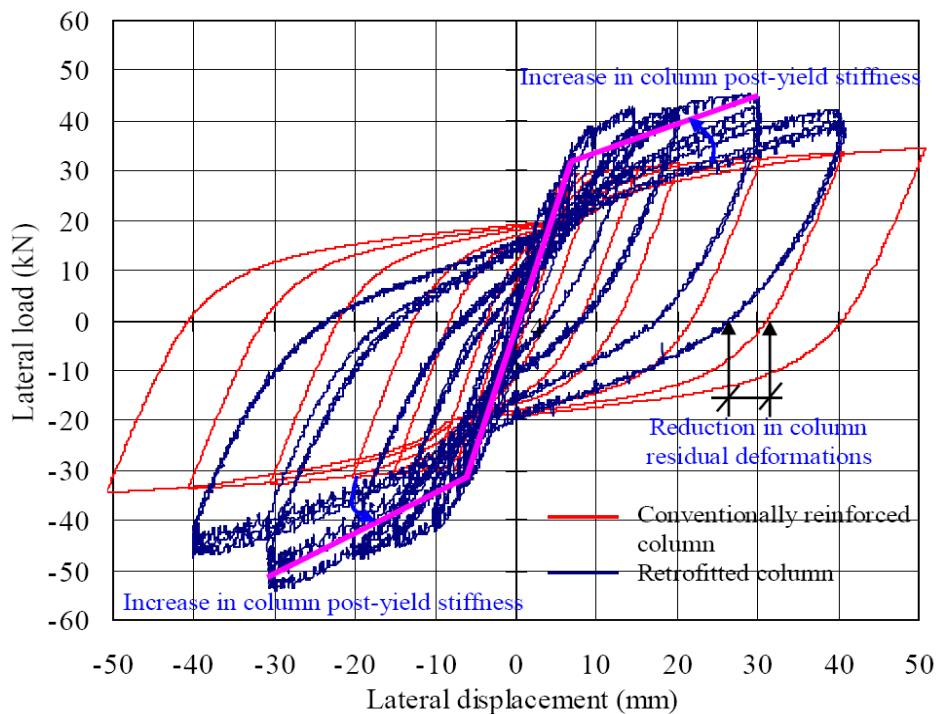


W-240-C-CT



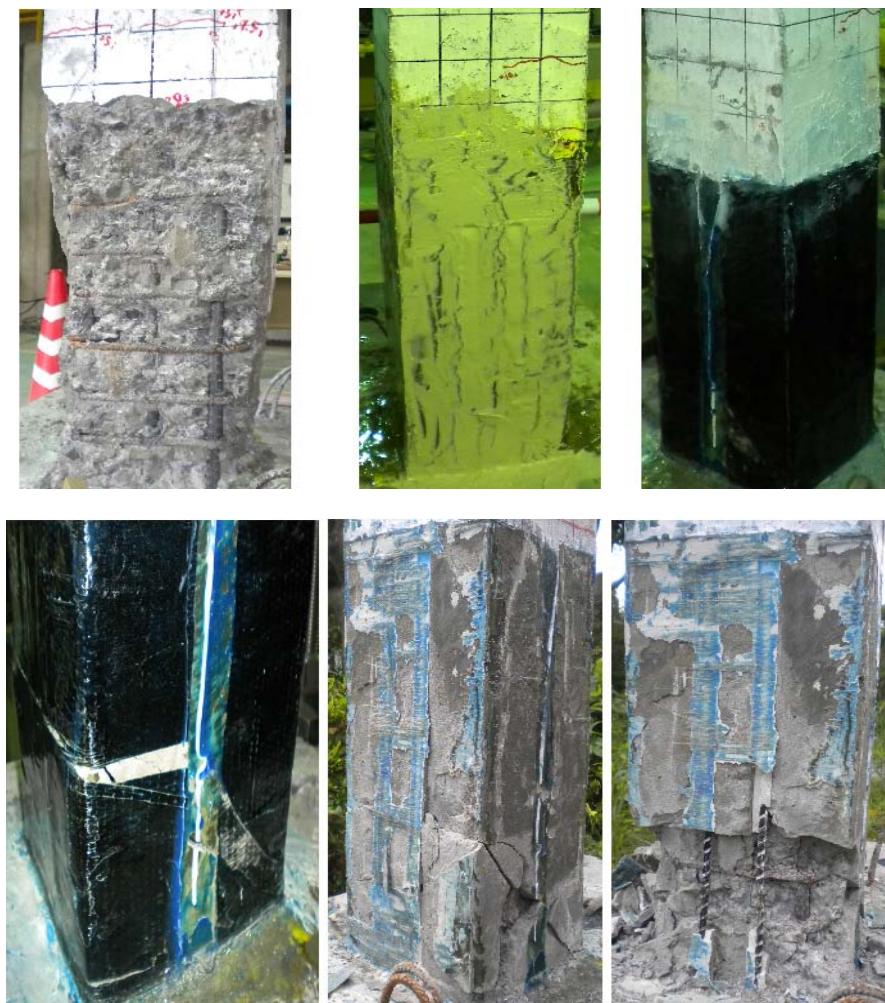
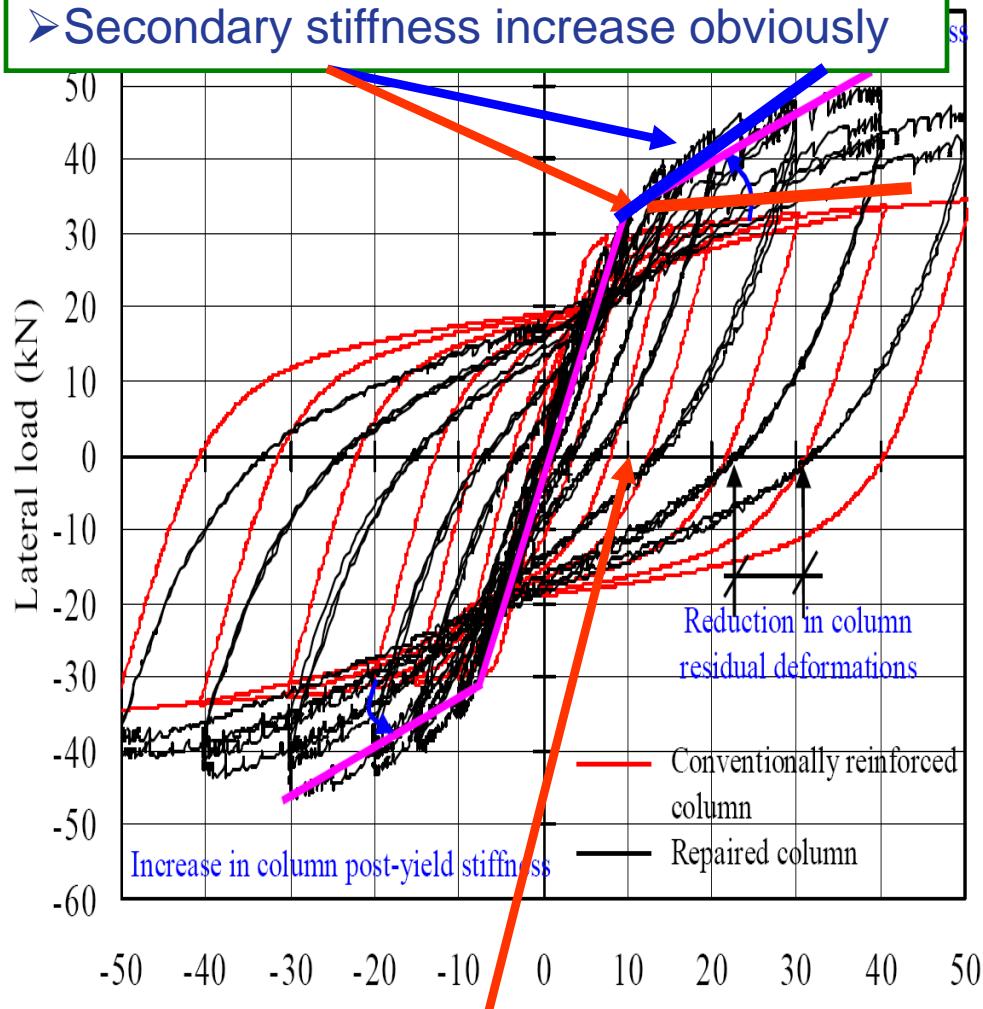
W-360-C-CT

Strengthening effect of NSM BFRP bar in column base



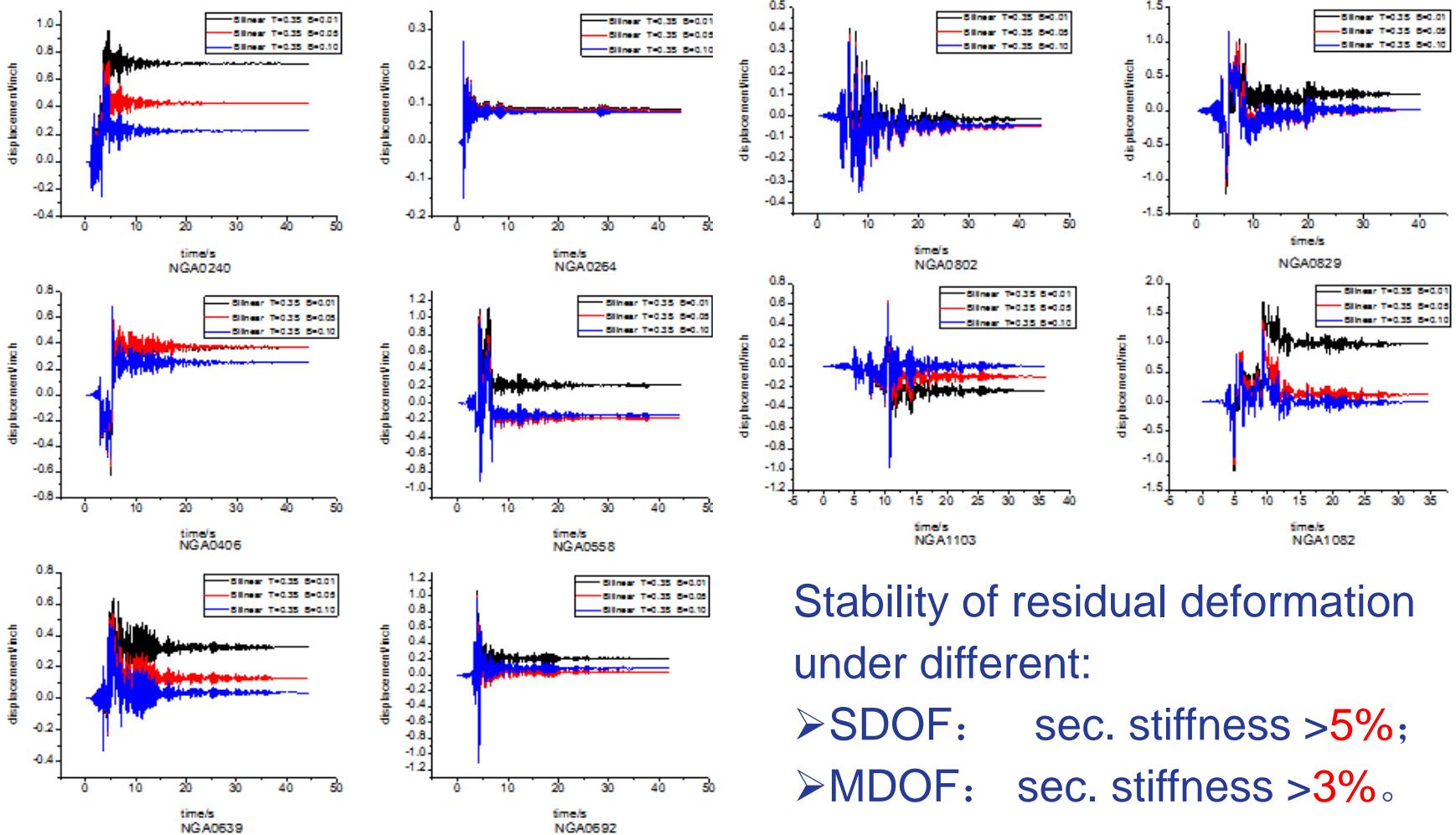
Strengthening of damaged RC column

- Small secondary stiffness of RC column
- Secondary stiffness increase obviously



- Small residual deformation

Dynamic response stability of different secondary stiffness structures



Stability of residual deformation under different:

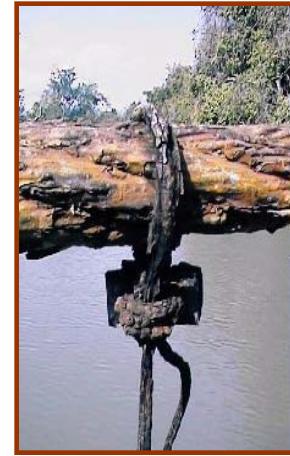
- SDOF: sec. stiffness >**5%**;
- MDOF: sec. stiffness >**3%**.

Outline

1. **Background**
2. **Introduction of FRP and research status**
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4. **Prestressing FRP technology**
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6. **Integrated high performance FRP structures**
7. **Intelligent infrastructures**
8. **Summary and future work**

Advanced FRP cables for integrated high performance long-span cable-stayed bridge

- ✓ Disadvantages of conventional steel cable:
large sag effect, durability, etc



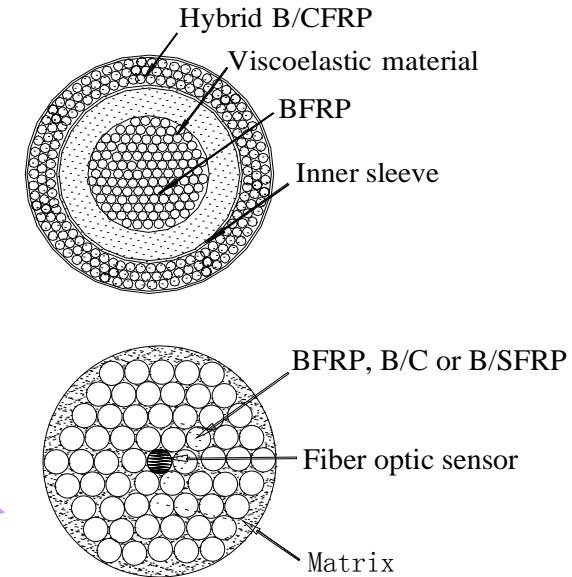
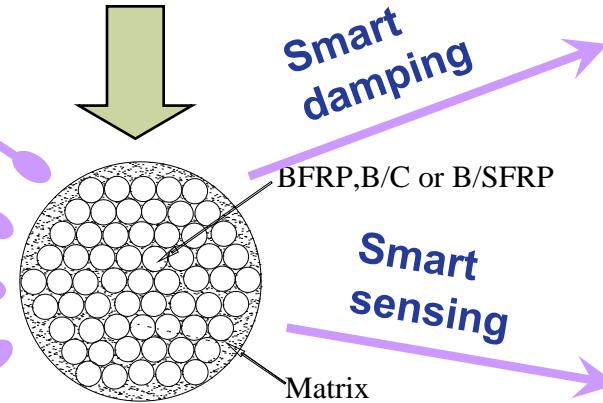
- ✓ Limitations of current CFRP cables:
high cost, aerodynamic stability, etc



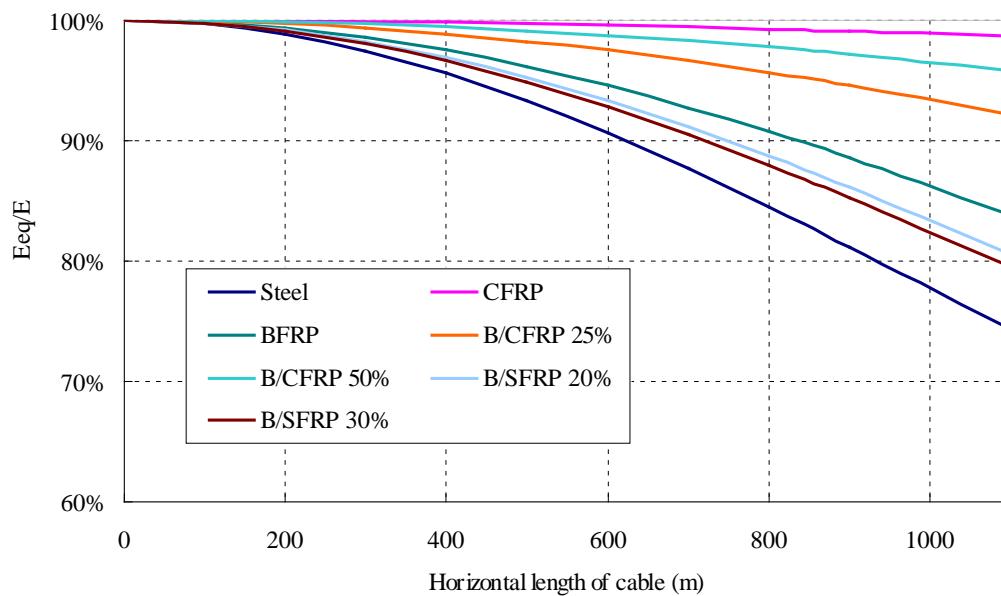
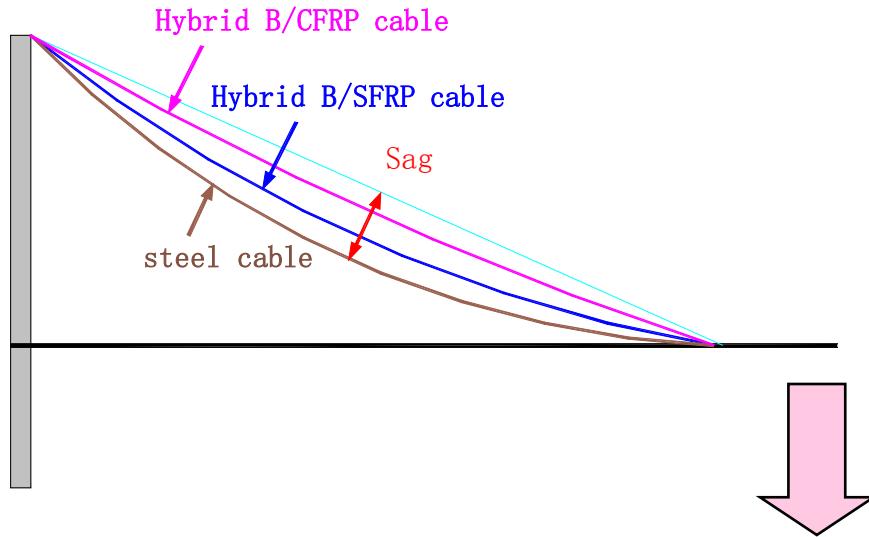
Solution

BFRP, hybrid basalt/carbon FRP, hybrid basalt/steel-wire FRP cables

- High strength
- Light weight
- Fatigue and corrosion resistance
- Relative low cost



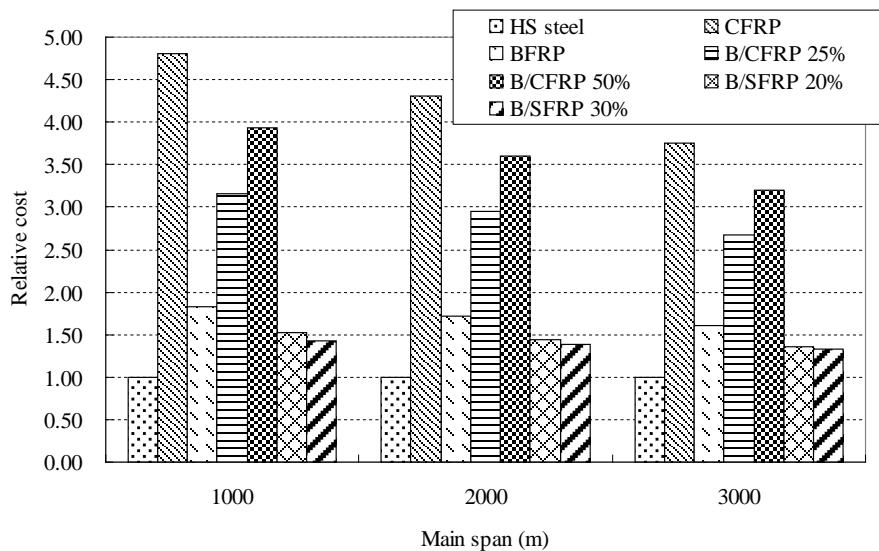
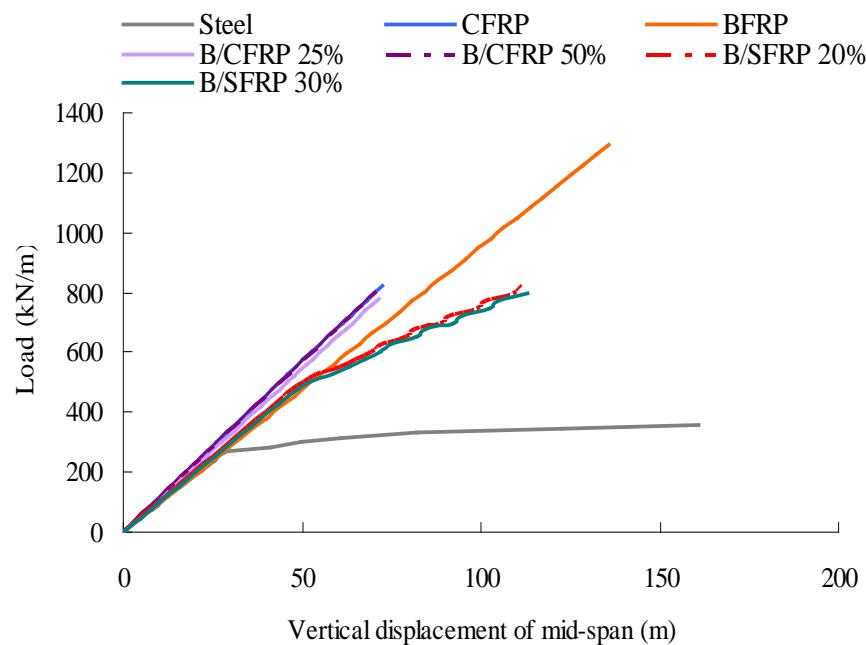
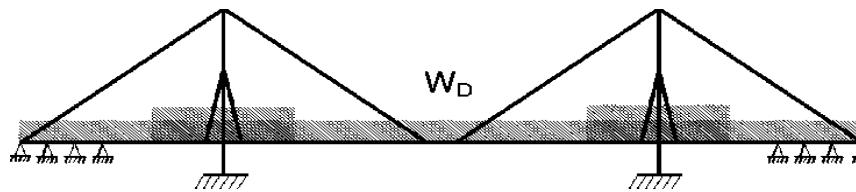
Superior static and dynamic behavior in long-span cable-stayed bridge



Reduce sag effect,
increase efficiency

Equivalent modulus
increase suitable for
long span bridges

Superior static behavior in long-span cable-stayed bridge

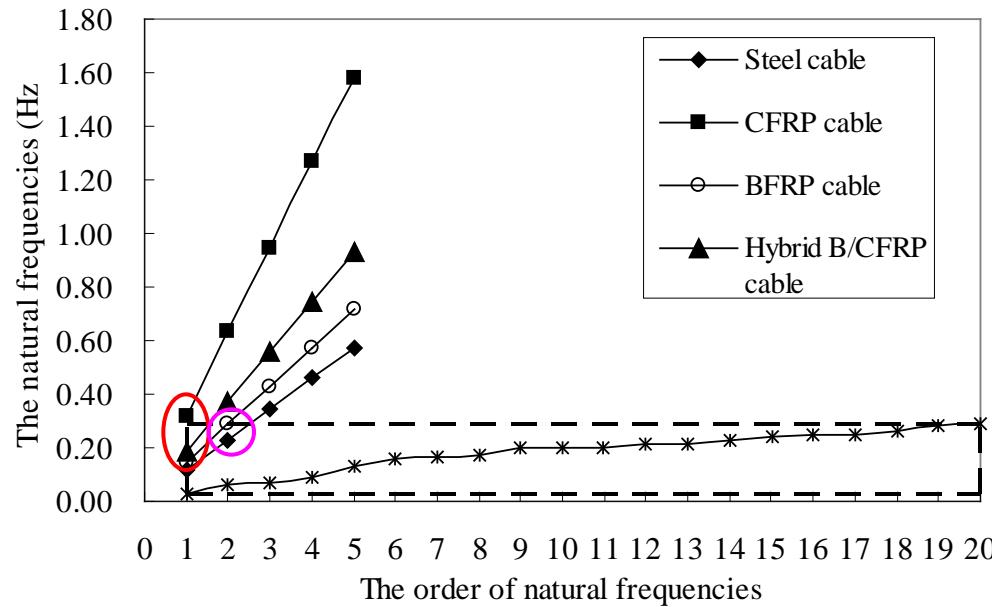
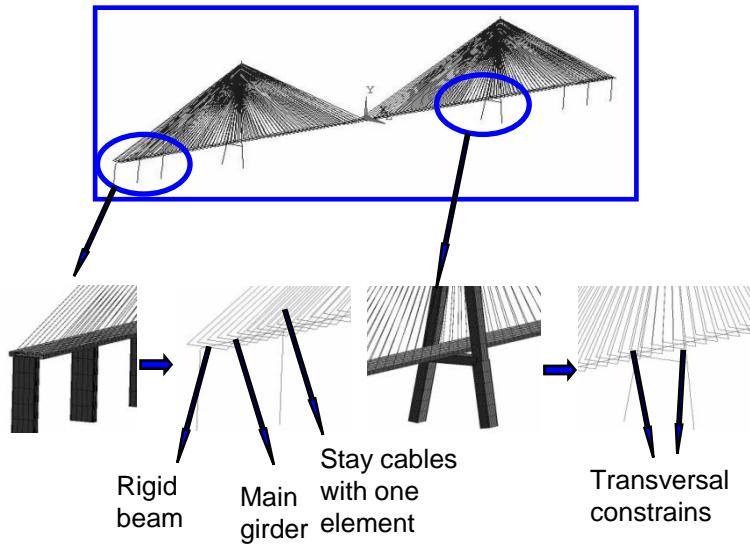


Superior static behavior
compared with steel cable-
stayed bridge

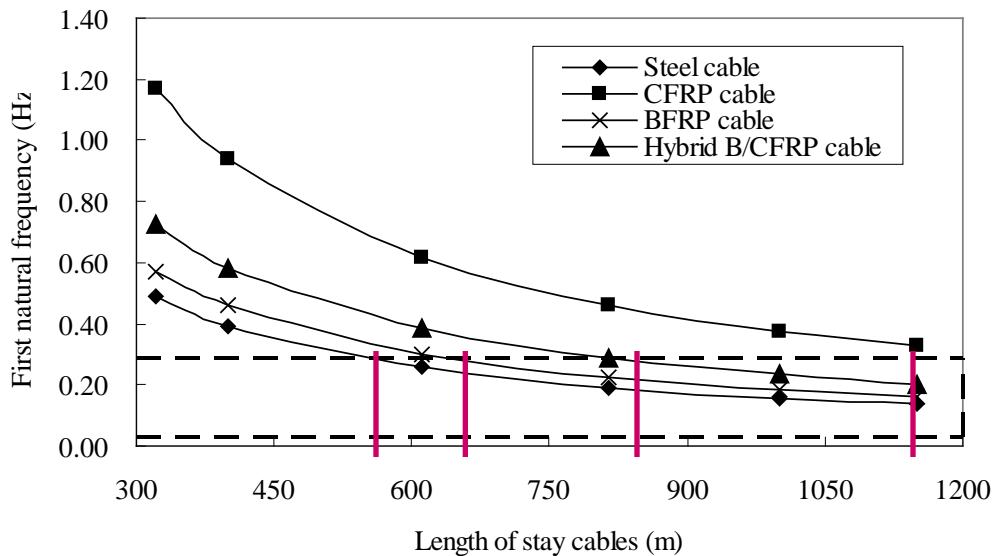
Cost comparable to steel
cable-stayed bridge

Superior dynamic behavior in long-span cable-stayed bridge

Lower risk of resonance between cables and bridge



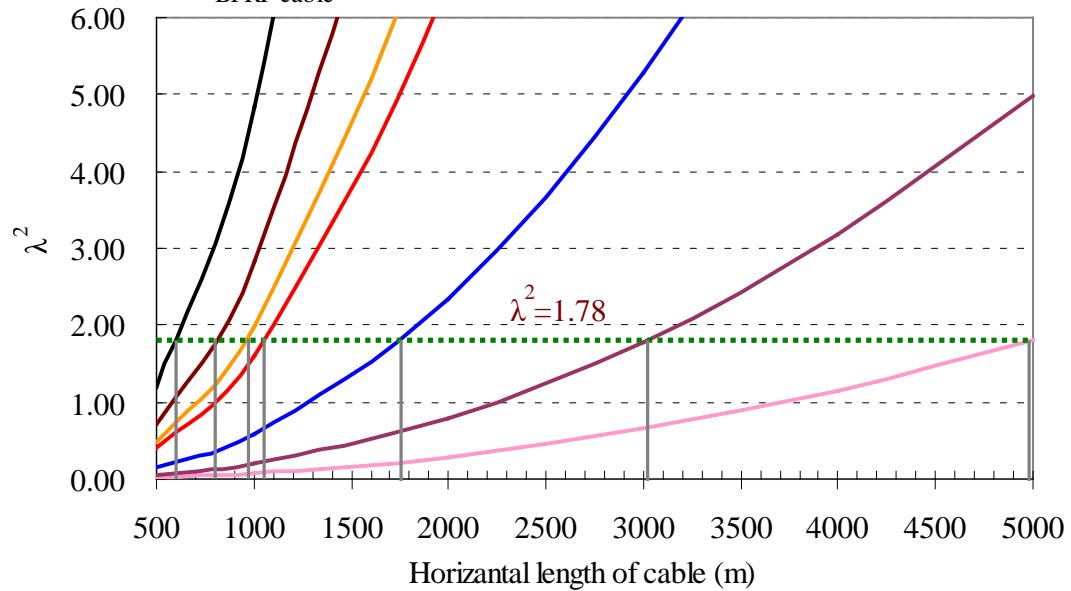
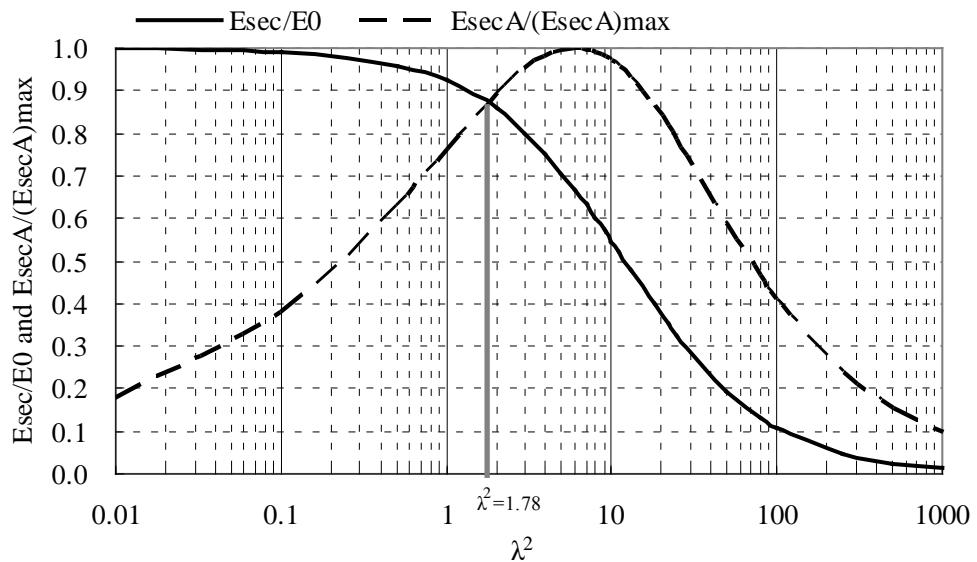
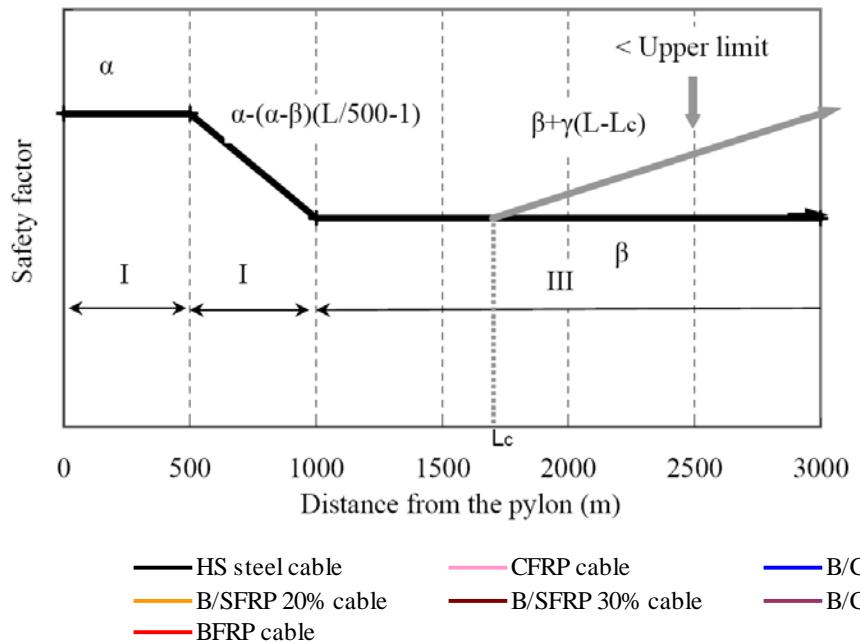
Possibility of resonance between bridges and the longest cables in different orders



Possibility of resonance between bridges and cables in different lengths

Advanced FRP cables

applicable length for each kind of cable

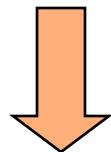


Three-stage design method
based on strength and stiffness
efficiency optimization

Applicable length of
different kinds of cables

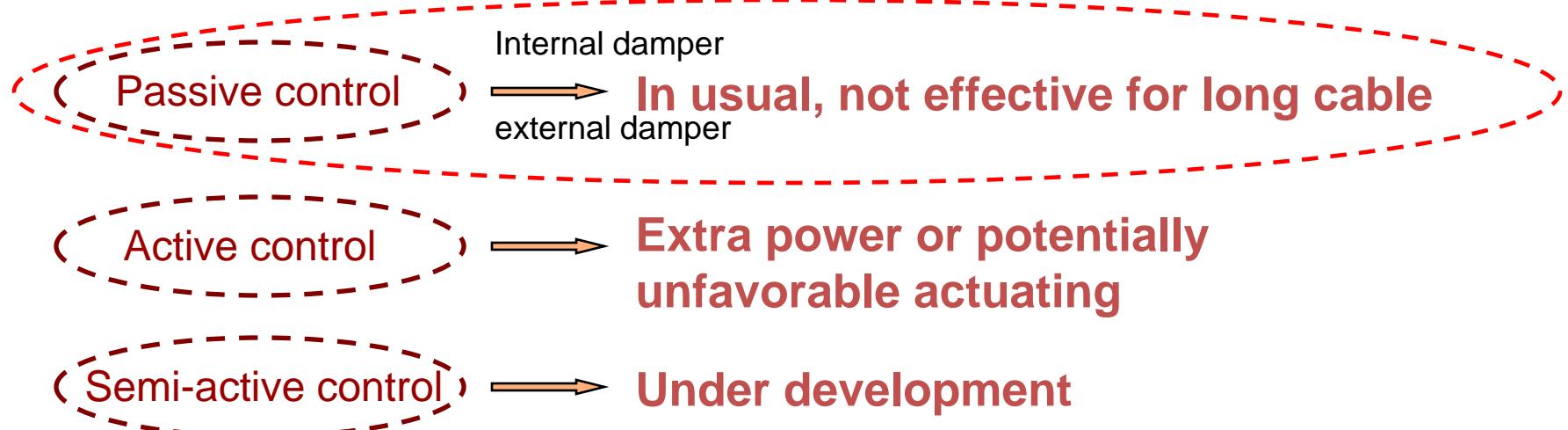
A critical issue for FRP cables in long-span cable-stayed bridge

Cable length increase	Scruton number	$S_c = \frac{2\delta m_e}{\rho D^2}$	Aerodynamic stability
	Wind effect		Larger load
	Natural freq		Easier resonance

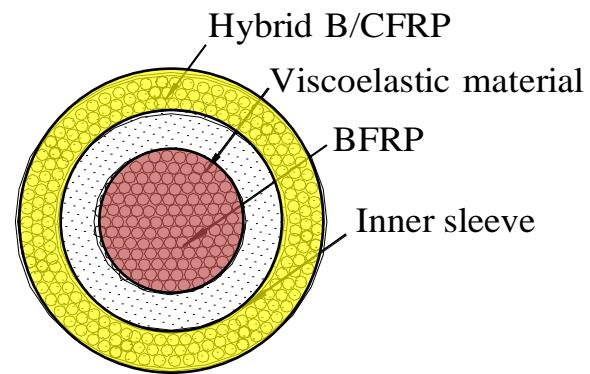
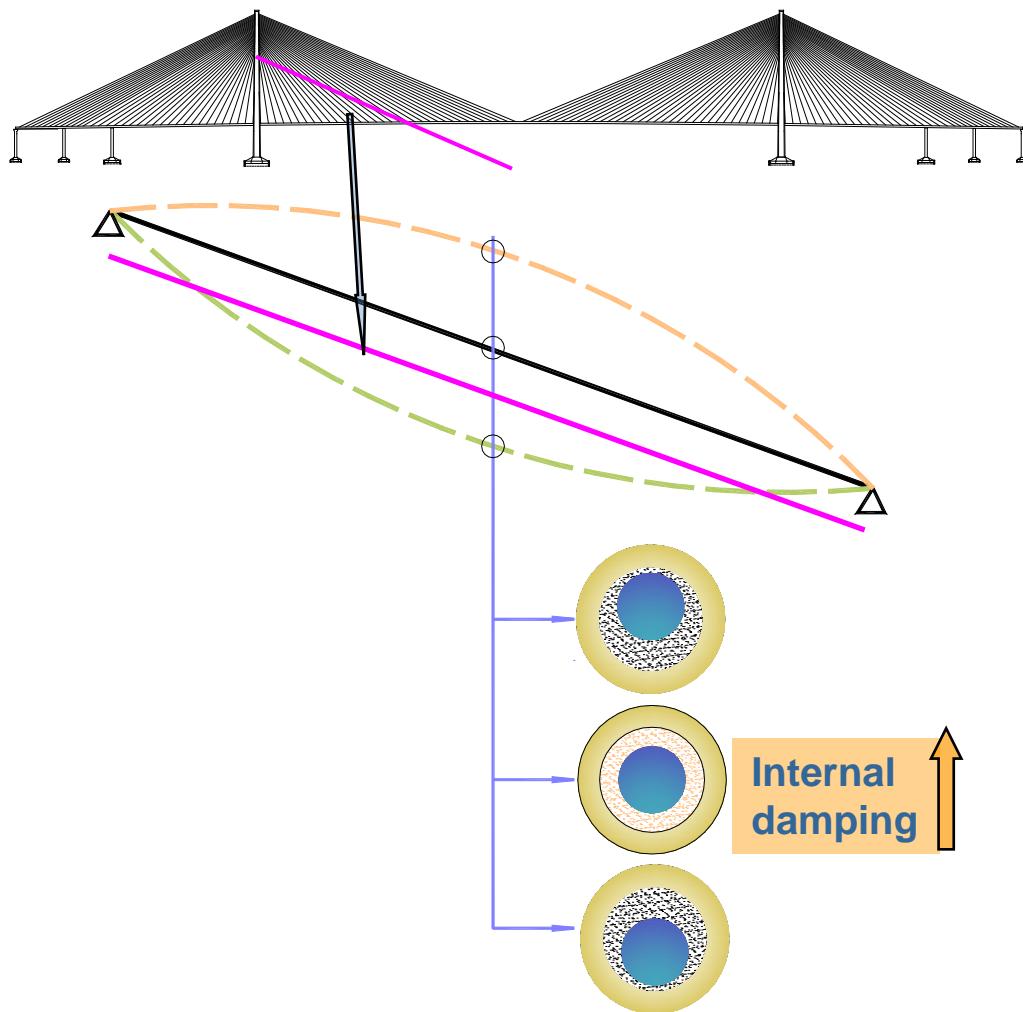


Thus, vibration will be a problem

Damping treatments are necessary



Principle and Design along cross-section of cable



Smart damper design

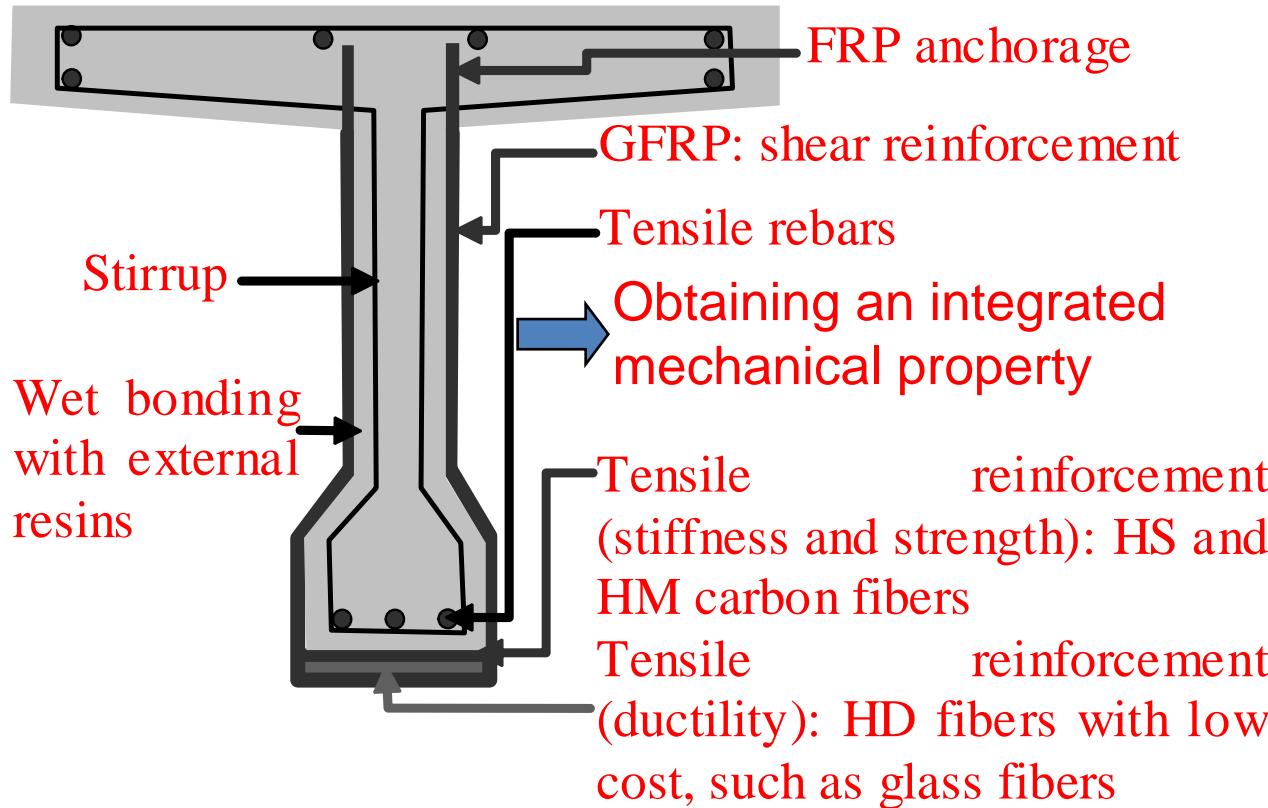
Inner cable
Outer cable

Different
natural freq.

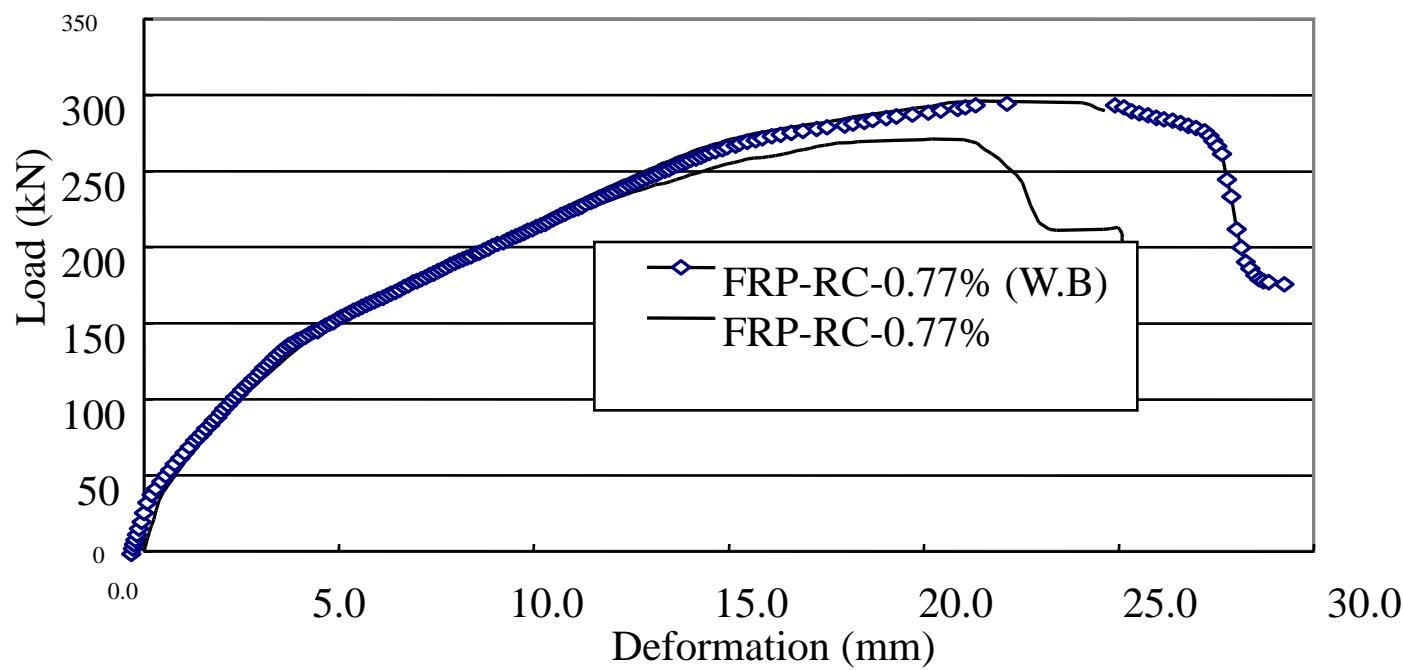
Dissipating vibration energy by interaction
between inner and outer cables

Compression of
viscoelastic material

Integrated high performance composite beam



Performance confirmation of wet-bonding technique



FRP-RC composite structure

Vacuum assisted resin infusion (VARI) for FRP profiles



Fiber laying

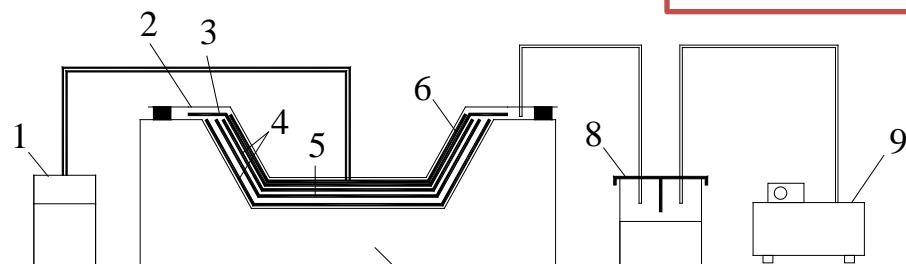
Demould sheet

Diversion medium

Seal bag

Pipe for vacuum

Production procedure



1-resin; 2-vacuum bag; 3-demould sheet
; 4-fibers; 5-core material; 6- Diversion
medium; 7-mould; 8-resin collector; 9-
vacuum pump



FRP-RC composite structure

Wet-bonding composite beam

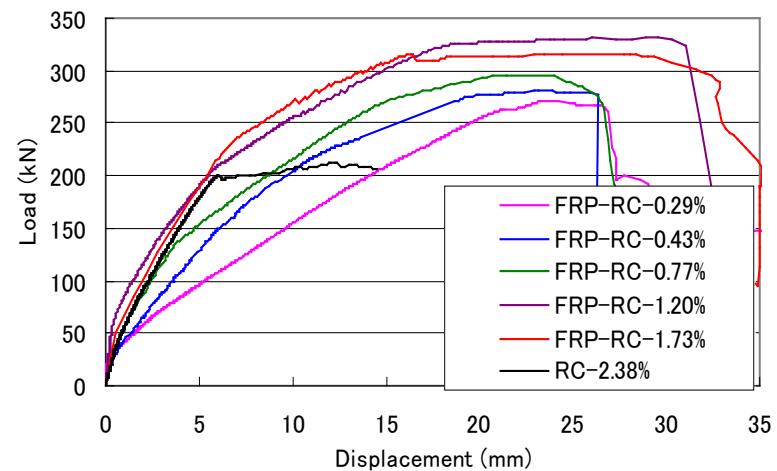
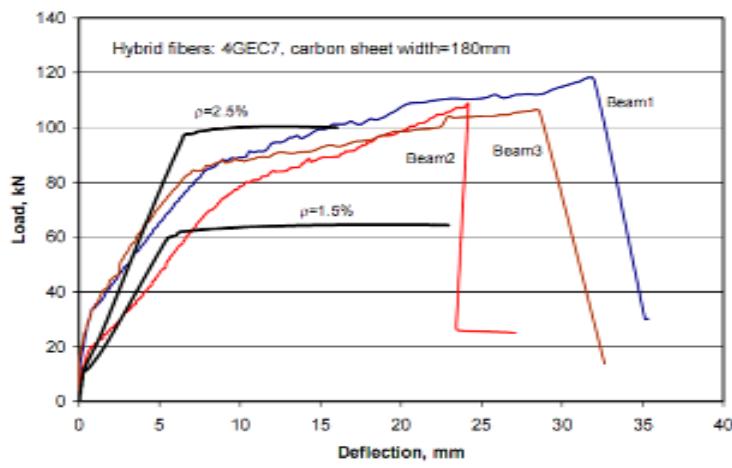
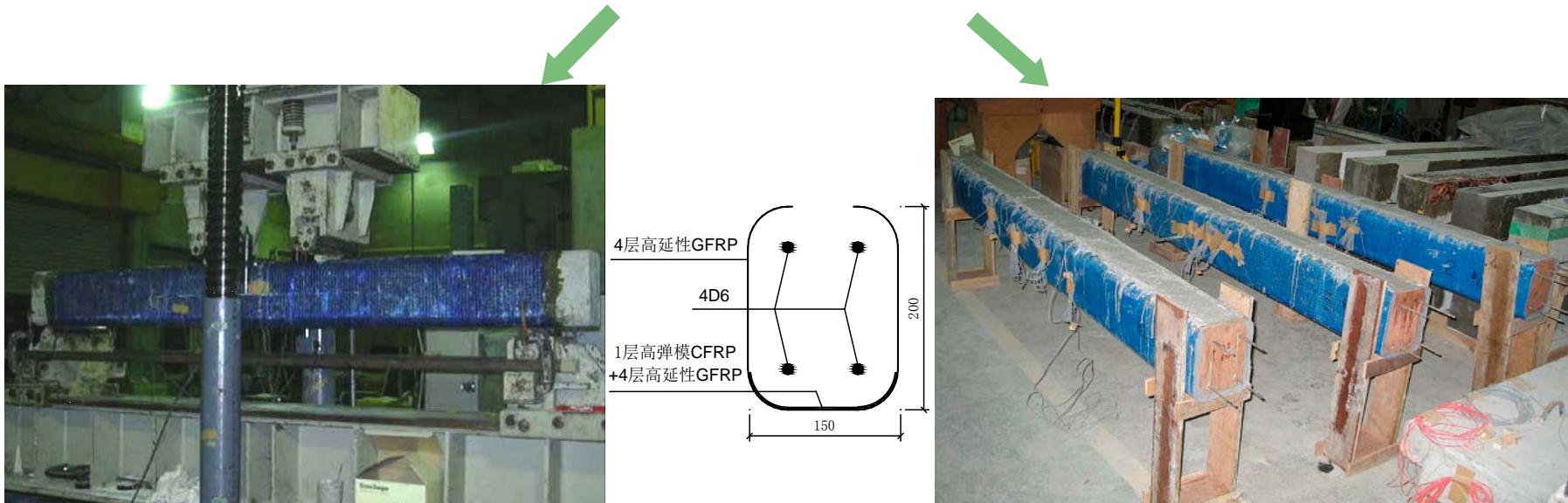
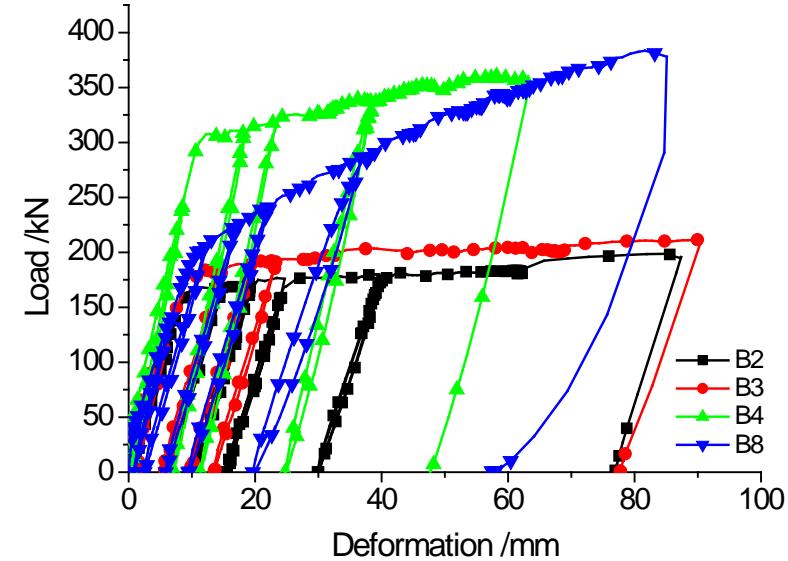
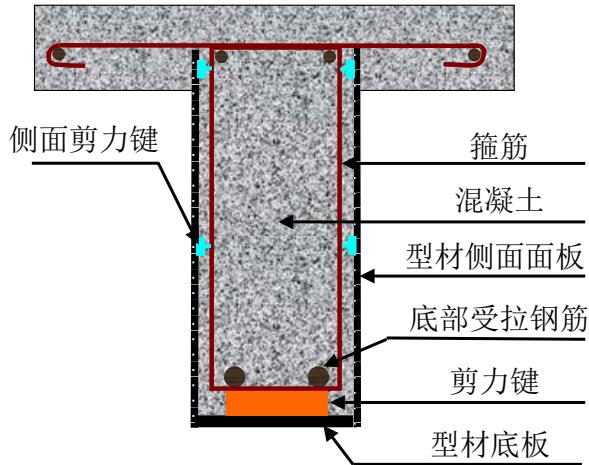


Fig. 5: Typical load – deflection curves of FRP-concrete composite beams

FRP-RC composite structure

Wet-bonding plus shear studs composite beam

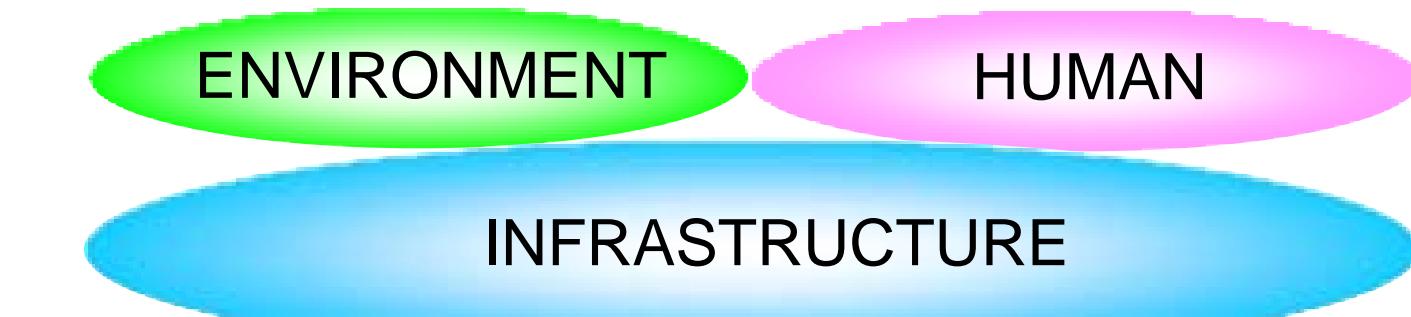


- reliable bonding of interface between concrete and FRP
- superior flexural behavior under fatigue loads

Outline

1. **Background**
2. **Introduction of FRP and research status**
3. **Hybrid FRP technology**
4. **Prestressing FRP technology**
5. **Damage-controllable FRP structures**
6. **Integrated high performance FRP structures**
7. **Intelligent infrastructures**
8. **Summary and future work**

WHY INTELLIGENT INFRASTRUCTURES?



SUSTAINABILITY

- Structure
- Strong and Ductile
- Healthy and Durable
- Sensing and Inspections
- Reduction of Life Cycle Cost
- Unexpected Failures or Disasters
- Ecology and Environment
- Smart

建 (けん ken)
堅 (けん ken)
健 (けん ken)
検 (け ken)
儉 (けん ken)
険 (け ken)
圓 (けん ken)
賢 (けん ken)

建 • 堅 • 健 • 検 • 儉 • 険 • 圓 • 賢

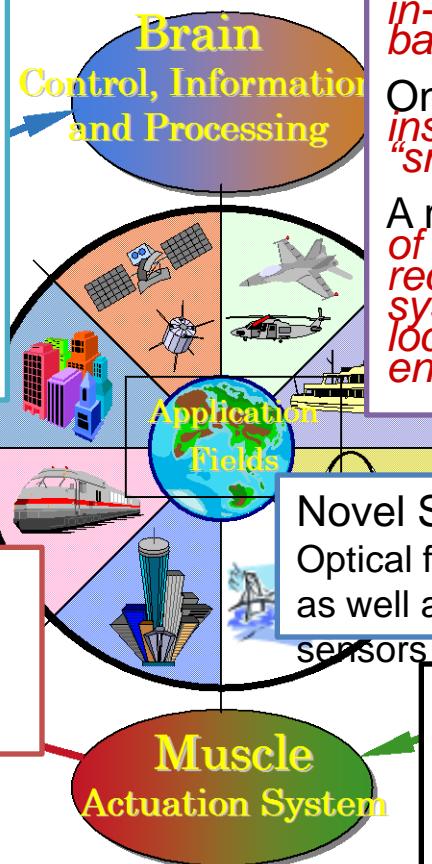
Intelligent Infrastructure System(What?)

(Intelligent Infrastructure+Secure Space)

Intelligent Infrastructure will be made of multi-functional materials integrated with smart sensors, actuators, electronics, intelligent compute control and processing software, which can minimize the life-cycle costs prolong the service life, and prevent or mitigate the disasters

Composite material and Structures

Smart manufacturing Tech.
a. Smart Processing Technology
b. Structure-Sensor-Actuator integrated system manufacturing technology



Actuator materials and elements
a. Ceramic, fiber actuators
b. High-performance shape memory alloy

Active and Adaptive Structural System
.Adaptive control system for smart large-scale and complex structures

Structural Health Monitoring(SHM)

The essence and definition of SHM:*measurement, inspection, and assessment of newly constructed and/or in-service structures on a continuous basis with minimum labor requirement*

One of the ideal scenarios:*real-time inspection and damage detection through "smart" devices*

A reliable SHM :*innovative improvement of instrumentation for sensing and recording, data acquisition technology, system identification technique, damage localization algorithms and civil engineering technology*

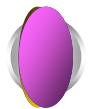
Novel Sensors

Optical fibers, acoustic, MEMS, PZT, composite fibers as well as magnetic and magnetostrictive type sensors

Damage Control Techniques

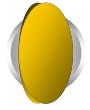
a. Self diagnosis, prognosis, healing, repair and rehabilitation
b. Damage prevention and mitigation

Issues and challenges in infrastructure



Seismic behavior

Reparability under moderate earthquake
No collapse under strong earthquake



Durability

Steel structures, concrete structure
due to cracks



Fire resistance

Steel structures

Advanced
FRP

Conventional construction without self-diagnosing and self-monitoring



Difficulty in long-distance distribution of conventional SHM methods

Advanced
FOS

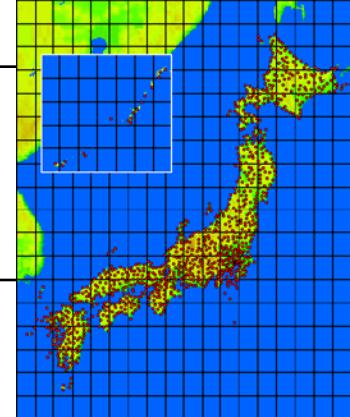
Safety + Durability



Urban scale expansion・High density
= Vulnerability↑

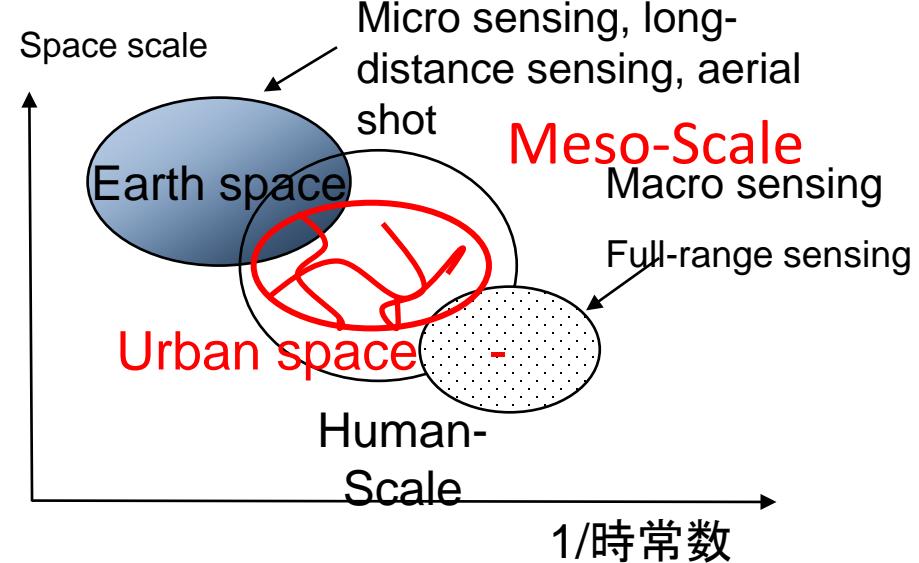


Earthquake, typhoon, torrential rain,
extreme temperature, terrorism.....



K-net
Earthquake
detection

$$\text{Risk} = \text{Danger} \times \text{Vulnerability}$$

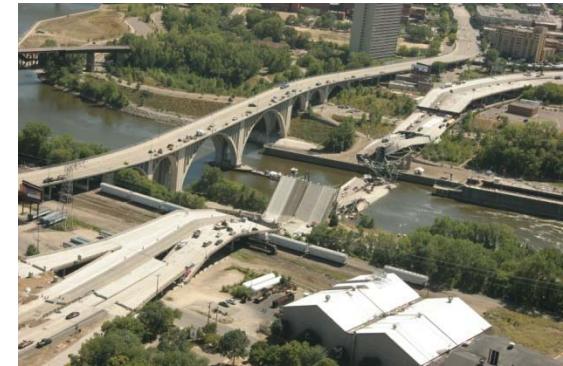


Sensing and monitoring of risk, danger and vulnerability

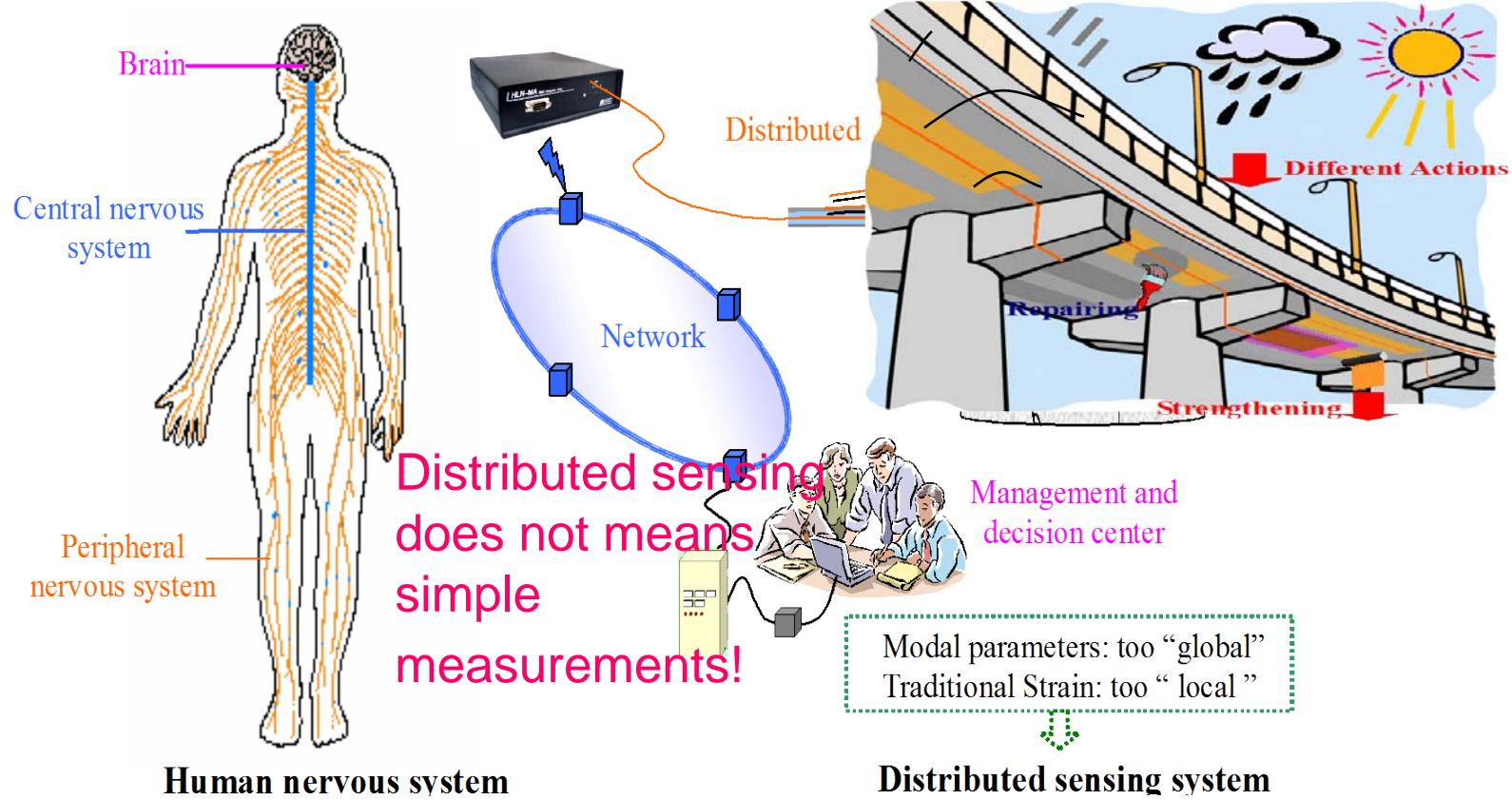
Evaluation of urban system in terms of assumptions



Safety



CHALLENGES IN Early Diagnosis and Long-term Prognosis Solution: DISTRIBUTED SENSING TECHNOLOGIES



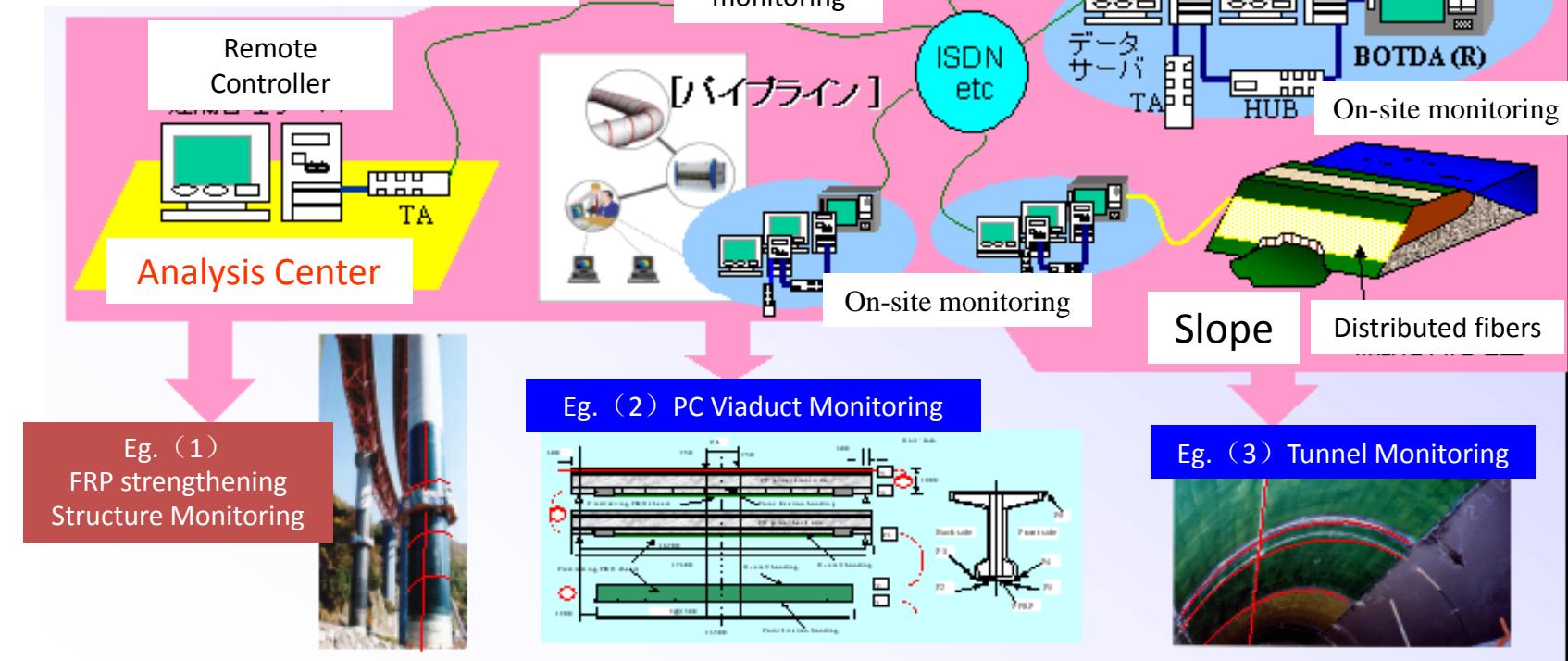
How to realize a distributed sensing for damage detection

1. Very dense distribution of using smart point sensors –useful ?
2. *Continuous or partially continuous wiring of using line Macro strain sensors including long –gauge sensors – natural !*

Distributed Remote Monitoring for Urban Systems

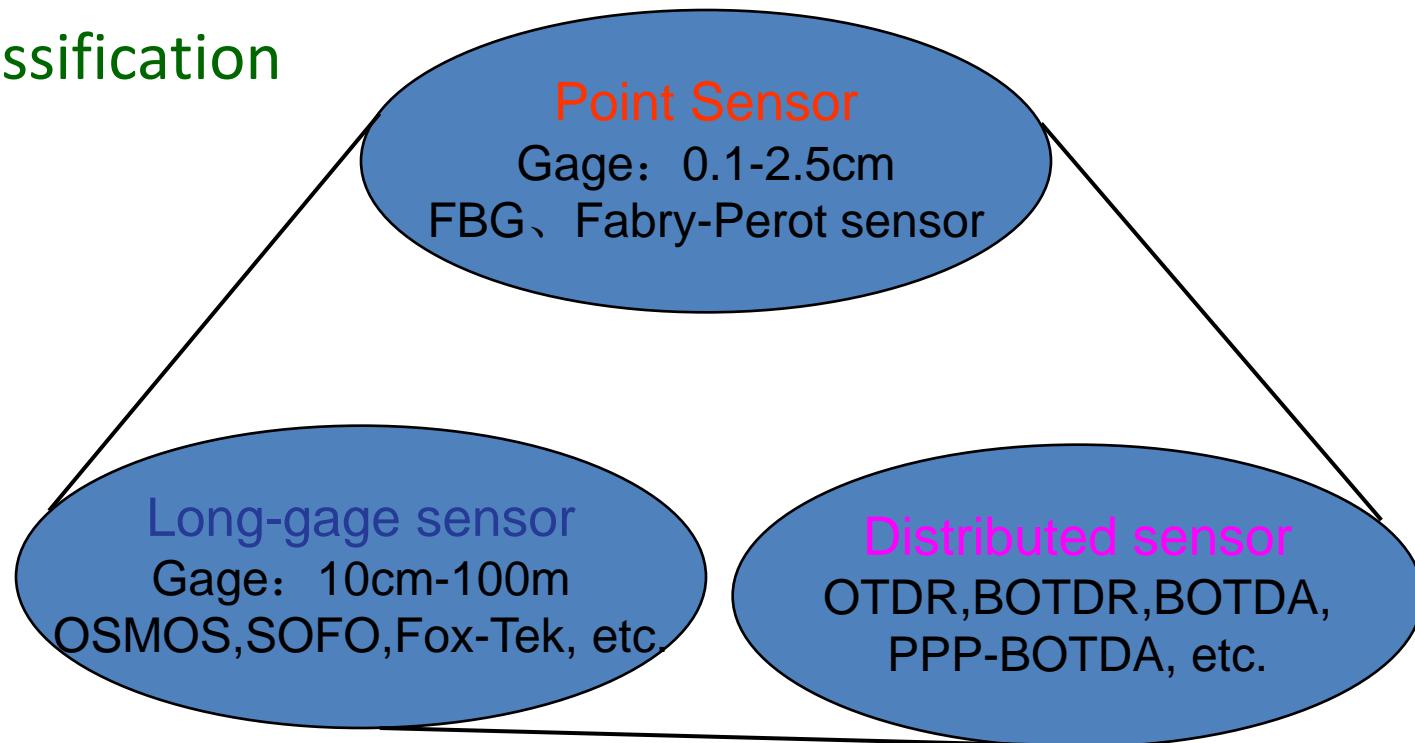
Characteristics

- Long time monitoring
- Distributed
- Remote sensing
- Self-diagnose
- Early warning



High Resolution Fiber Sensing Technology

■ Classification



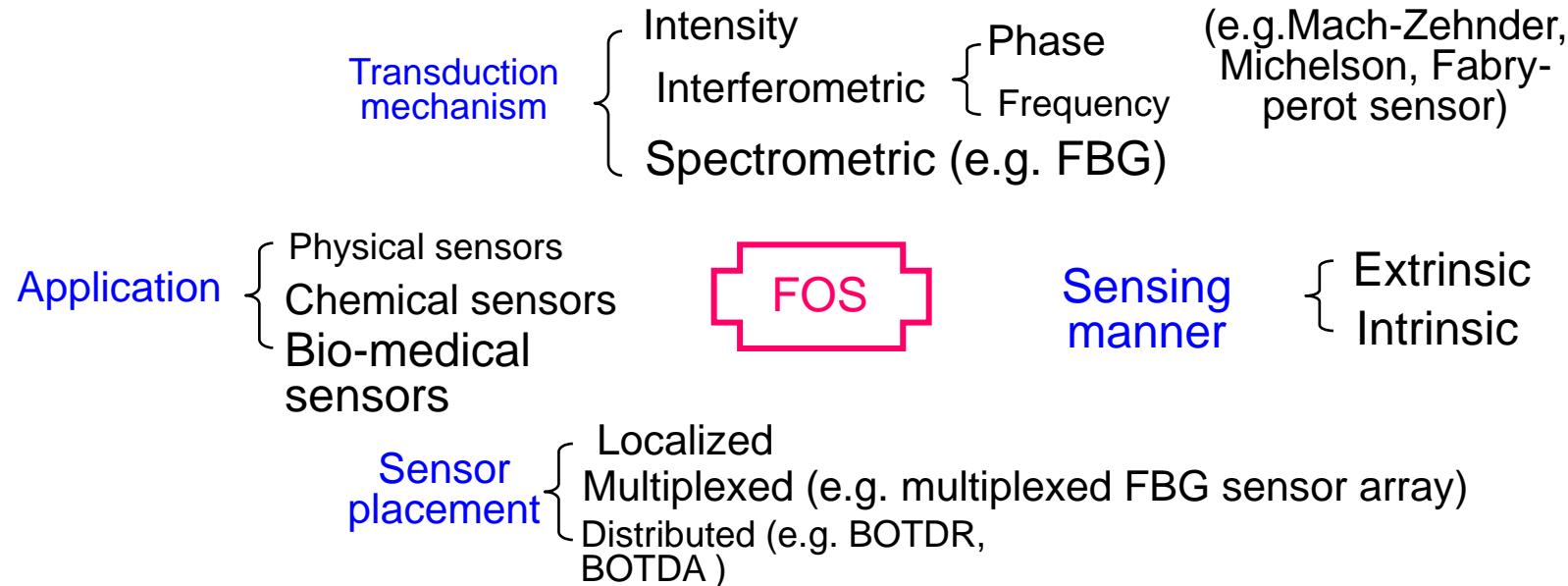
■ Characteristics

- ❖ Robust to noises
- ❖ Easy for deployment
- ❖ Fast transmission

■ Quantities to be monitored

- ❖ Structural stress, displacement
- ❖ temperature, humidity
- ❖ Frequency • dynamic stress spectra
- ❖ Crack • plastic stress • damage
- ❖ dynamic and static loads
- ❖ Chemistry quantities such as PH

Fiber optic sensors



	FBG	Brillouin	FP	FOPS	LCDS
Linear response	yes	yes	yes	yes	yes
Absolute measurement	yes	no	yes	yes	yes
Range to resolution	high	low	high	low	high
Mechanical strength	high	high	low	high	High
Multiplexing/Distributing	M	D	M	M	M
Dynamic sampling rate	high	low	high	low	low
Potential cost	low	high	low	low	low

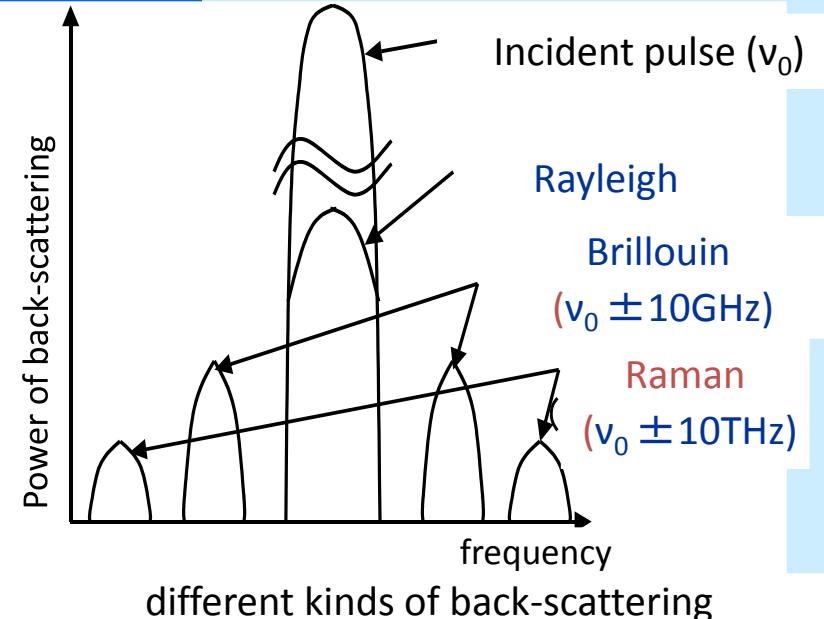
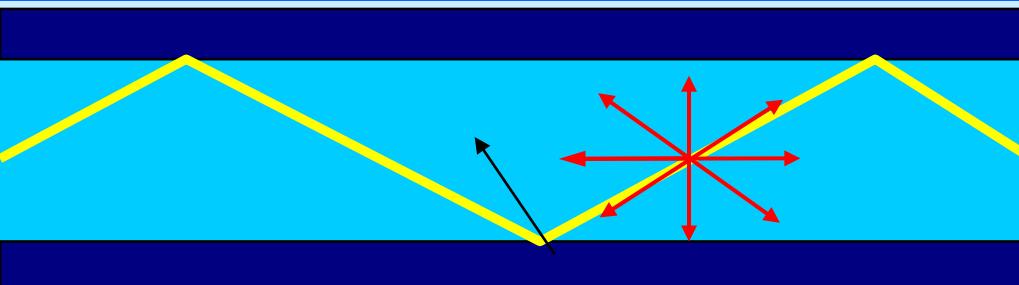
Distributed Fiber Optics Sensing

BOTDR:Brillouin Optical Time Domain Reflectometry

BOCDA:Brillouin Optical Correlation Domain Analysis

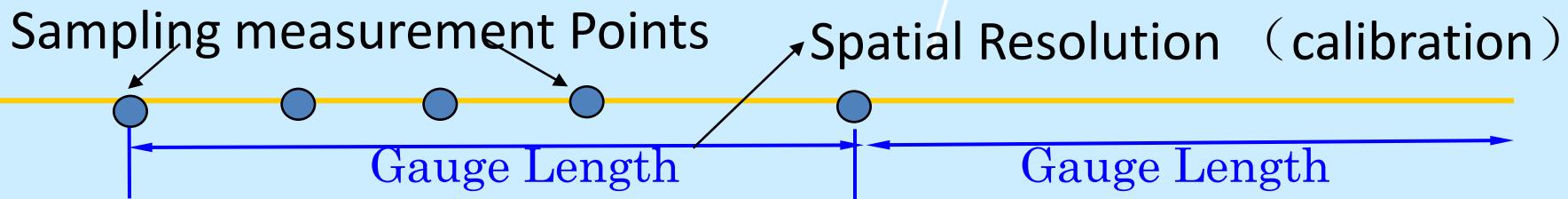
PPP-BOTDA: Pulse Pre-pump Brillouin Optical Time Domain Analysis

Back-Scattering (reflected signal)



1.Thousands of measurement points along a long-distance cable

2.Static measurement only



Distributed Fiber Optic Sensing Based on PPP-BOTDA

(Sub-PI: Zhishen Wu, Professor at Ibaraki University)

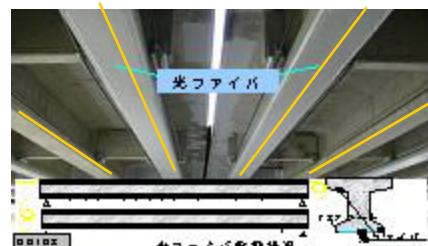
- To realize distributed, long-distance and real-time measurements in high-resolution and high-accuracy with direct frequency modulation and frequency stabilization techniques
- To promote applications of Brillouin-based distributed sensing technique in civil engineering and other large-scale structures

Type	Spatial resolution	Accuracy	Sampling rate
Pre-present	B-OTDR	100cm	$\pm 50\mu$ Several minutes
	PPP-BOTDA	10-20cm	$\pm 30\mu$ Several minutes
Target	10cm	Under $\pm 10\mu$	Real-time(3~10Hz)

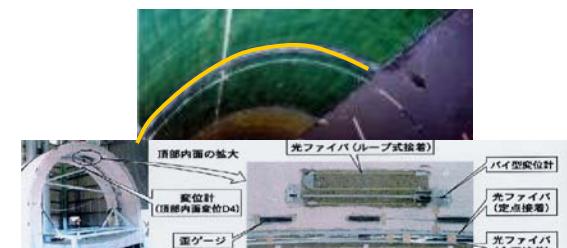
PPP-BOTDA: Pre-pump pulse-Brillouin Optical Fiber Time Domain Analysis

Measures: strain and temperature distributions and other environmental factors

Example 1 : long-term monitoring for highway viaducts



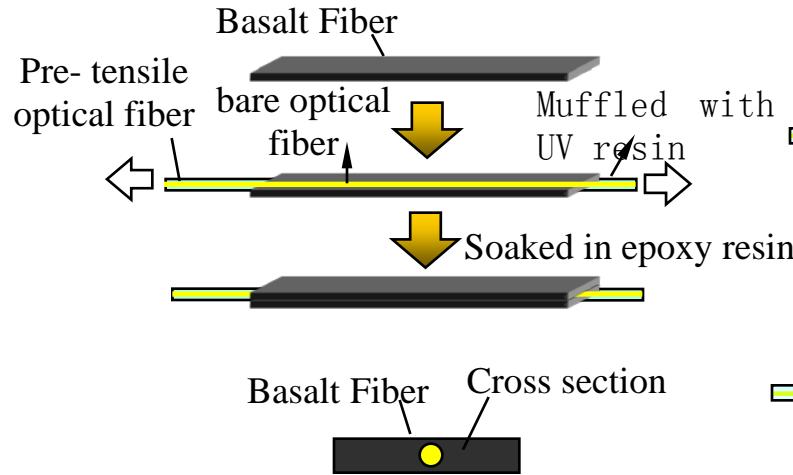
Example 2 : long-term monitoring for railway tunnels



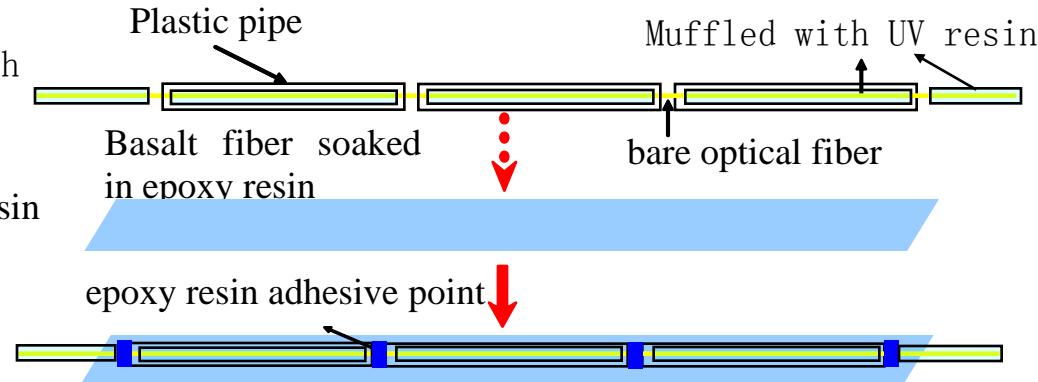
Pilot tests with real structures

Key Technologies for Intelligent Structures

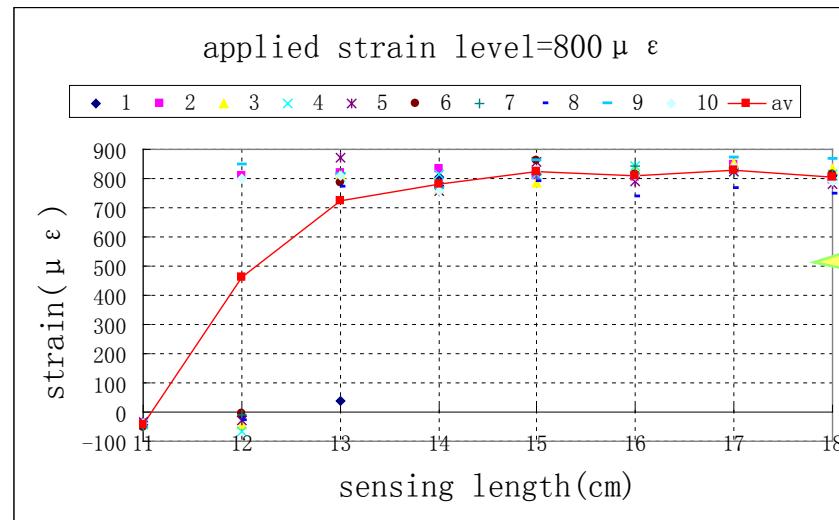
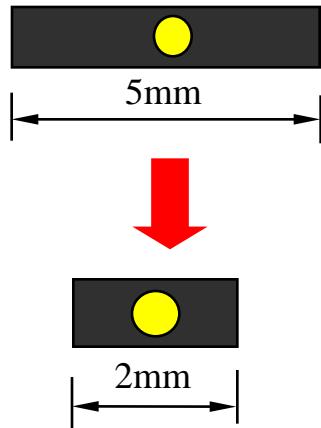
- Non-slip grating



Overall bonding Package



Point bonding Package



Critical testing length can be as short as 13cm

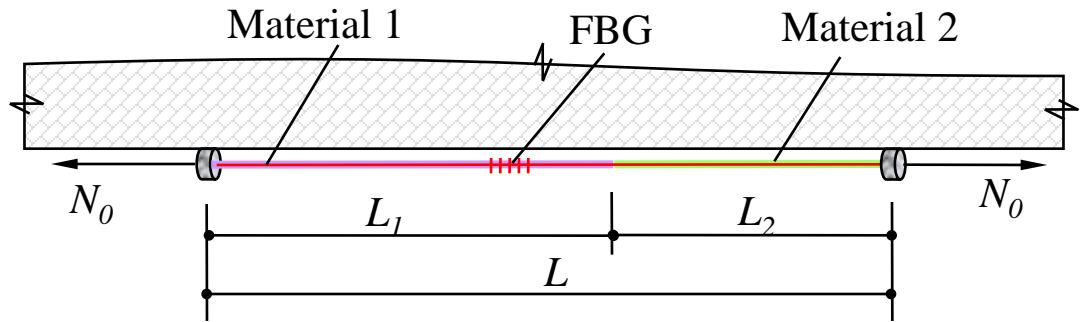
High Sensitivity FBG Sensor

Why to develop

- Stress usually is small
- Heavy noises
- Crack due to corrosion
- Ambient environment vibration testing

Basic Principal

- FBG measured stress: ε_1
- Average stress within the gage length L : $\bar{\varepsilon}$



Suppose:

$$\alpha_E = \frac{E_1 A_1}{E_2 A_2}$$
$$\alpha_L = \frac{L_1}{L}$$

$$\varepsilon_1 = \eta \cdot \bar{\varepsilon}$$

$$\eta = \frac{1}{\alpha_L + \alpha_E - \alpha_L \alpha_E}$$

Sensitivity
Increment
Coefficient

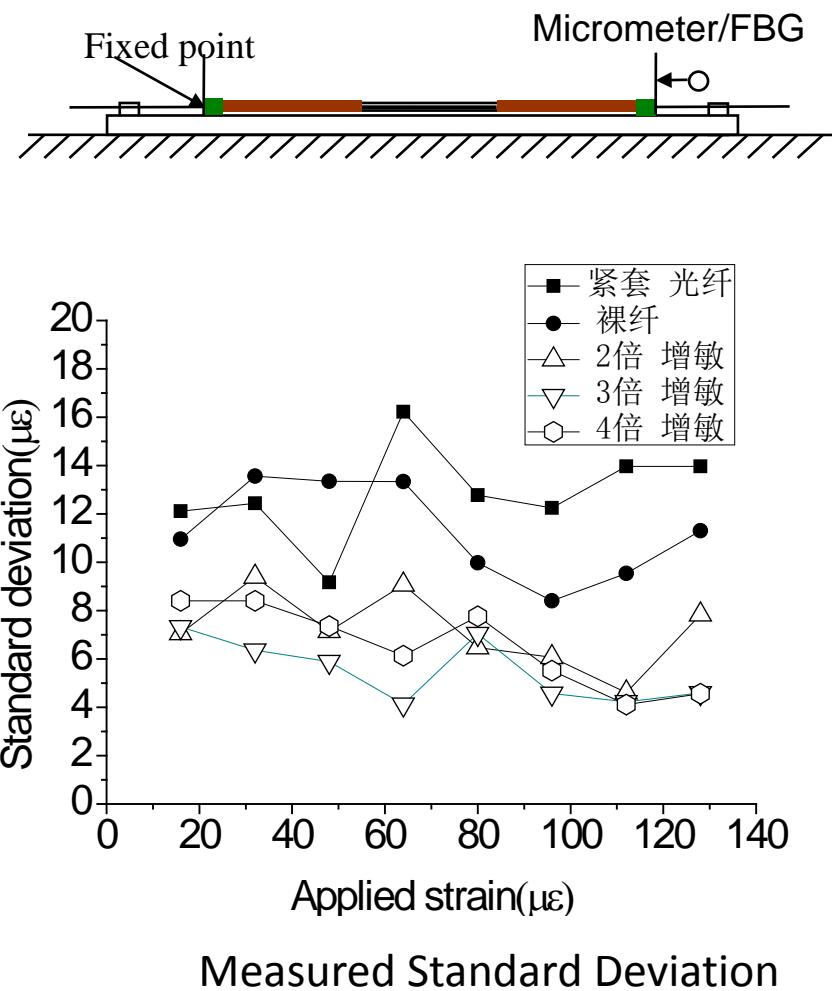
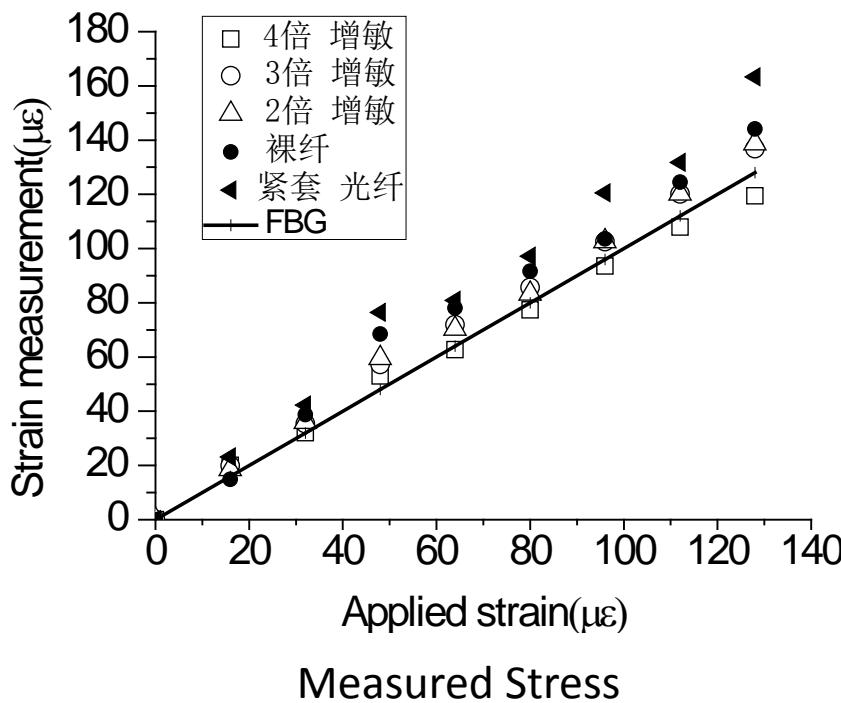
When $\alpha_E = 1$ $\varepsilon_1 = \bar{\varepsilon}$

When $E_1 \ll E_2$ $\alpha_E \rightarrow 0$ $\eta \approx \frac{1}{\alpha_L} = \frac{L}{L_1}$

Development of New Distributed Long Gage High Sensitivity Fiber Stress Sensor

- Verification—Stretch

1. bare optical fiber, tight buffer fiber , high sensitivity fiber ($\eta=2\sim 4$)
2. Stress step $16\mu\varepsilon$, repeat 10 times

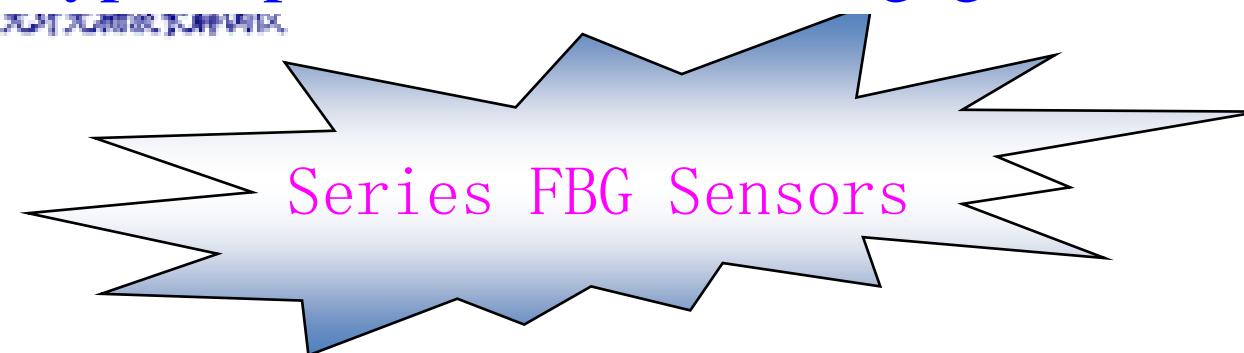


Measurement result of new fiber sensor is more closer to the real one, with smaller Standard Deviation

Measuring Principal of Long-Gage Distributed FBG Sensors

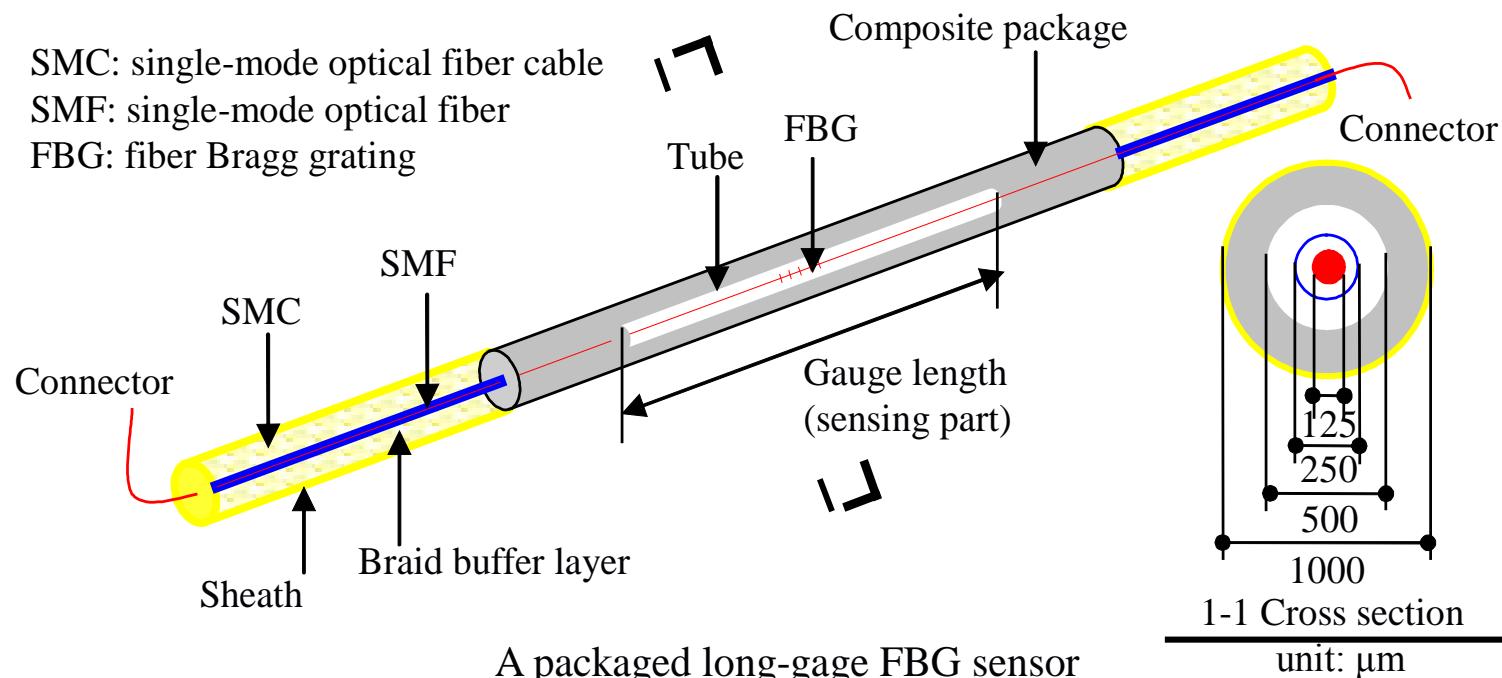
Characteristics of Traditional FBG Sensors:

- (1)High resolution;
- (2)Good dynamic performance;
- (3)Distributed measurement;
- (4)Typical point sensor, small gage

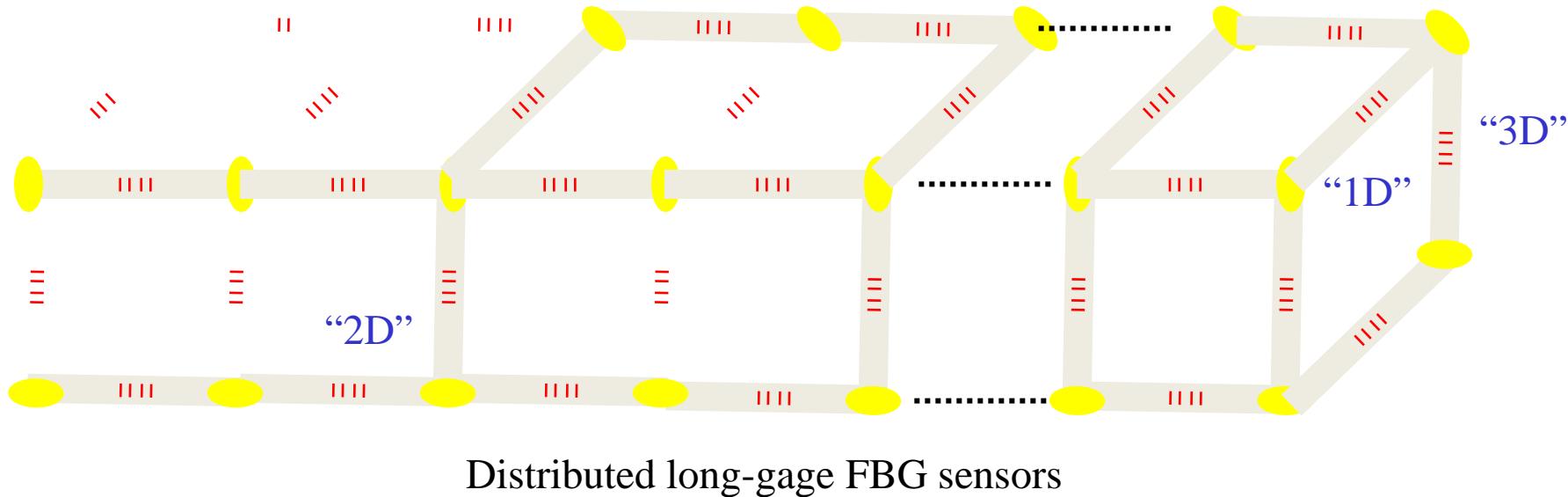


Distributed long-gage FBG sensors

SMC: single-mode optical fiber cable
SMF: single-mode optical fiber
FBG: fiber Bragg grating

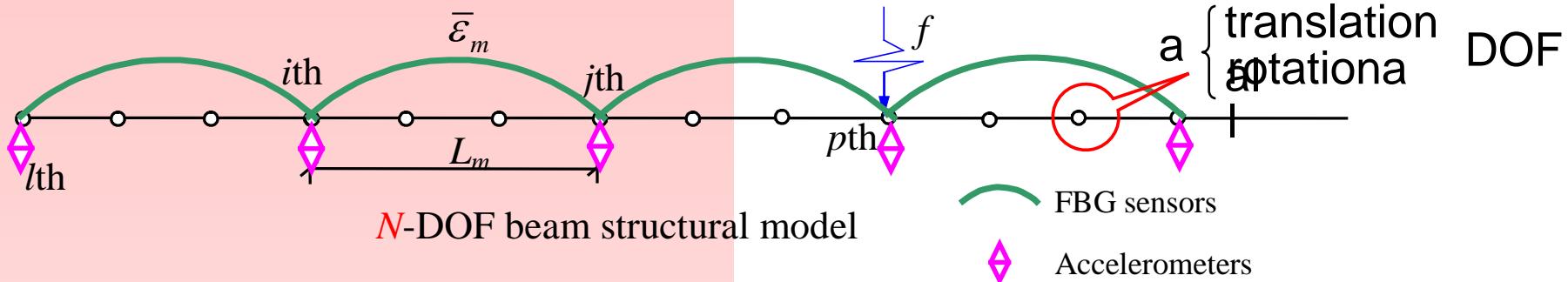


A packaged long-gage FBG sensor



Distributed long-gage FBG sensors

Dynamic measurements



The dynamic displacement measurements can be written as:

Measurements from accelerometers: $\{v_n(t)\} = \{v_1(t), v_2(t), \dots, v_{i-1}(t), \dots, v_N(t)\}^T$

$$\underline{\{a_l(t)\}} = \begin{Bmatrix} a_1(t) \\ a_2(t) \\ \vdots \\ a_l(t) \\ \vdots \\ a_L(t) \end{Bmatrix} = \begin{Bmatrix} \ddot{v}_1(t) \\ \ddot{v}_2(t) \\ \vdots \\ \ddot{v}_l(t) \\ \vdots \\ \ddot{v}_L(t) \end{Bmatrix} = [A]_{L \times N} \cdot \begin{Bmatrix} \ddot{v}_1(t) \\ \ddot{v}_2(t) \\ \vdots \\ \ddot{v}_n(t) \\ \vdots \\ \ddot{v}_N(t) \end{Bmatrix}$$

$$= [A]_{L \times N} \cdot \{\ddot{v}_n(t)\}$$

“acceleration”
“translation”
“al”

Measurements from M FBG sensors: $\{\bar{\varepsilon}_m(t)\} = \{\bar{\varepsilon}_1(t), \bar{\varepsilon}_2(t), \dots, \bar{\varepsilon}_m(t), \dots, \bar{\varepsilon}_M(t)\}^T$

$$\underline{\{\bar{\varepsilon}_m(t)\}} = \begin{Bmatrix} \bar{\varepsilon}_1(t) \\ \bar{\varepsilon}_2(t) \\ \vdots \\ \bar{\varepsilon}_m(t) \\ \vdots \\ \bar{\varepsilon}_M(t) \end{Bmatrix} = \begin{Bmatrix} \eta_1 \cdot (v_{i1}(t) - v_{j1}(t)) \\ \eta_2 \cdot (v_{i2}(t) - v_{j2}(t)) \\ \vdots \\ \eta_m \cdot (v_{im}(t) - v_{jm}(t)) \\ \vdots \\ \eta_M \cdot (v_{iM}(t) - v_{jM}(t)) \end{Bmatrix} = [B]_{M \times N} \cdot \begin{Bmatrix} v_1(t) \\ v_2(t) \\ \vdots \\ v_n(t) \\ \vdots \\ v_N(t) \end{Bmatrix}$$

$$= [B]_{M \times N} \cdot \{v_n(t)\}, \quad \eta_m = \frac{h_m}{L_m}$$

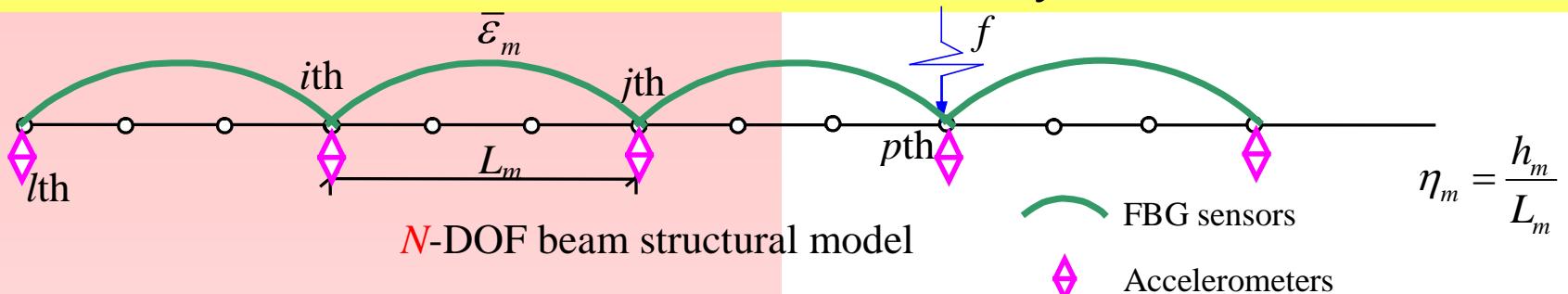
where close to “displacement”

From the view of temporal

From the view of spatial domain...

“rotational”

Theoretical modal analysis



Acceleration FRF

$$H_{lp}^a(\omega) = \frac{v_l(\omega)}{P_p(\omega)} = \sum_{r=1}^N \frac{-\omega^2 \varphi_{lr} \varphi_{pr}}{M_r (\omega_r^2 - \omega^2 + 2j\xi_r \omega_r \omega)}$$

Macro-strain FRF

$$H_{mp}^{\bar{\varepsilon}}(\omega) = \frac{\bar{\varepsilon}_m(\omega)}{P_p(\omega)} = \sum_{r=1}^N \frac{\eta_m (\varphi_{ir} - \varphi_{jr}) \varphi_{pr}}{M_r (\omega_r^2 - \omega^2 + 2j\xi_r \omega_r \omega)}$$

Considering

$$\left| {}_r H_{lp}^a(\omega) \right| = \frac{\varphi_{lr} \varphi_{pr} \text{magnitude}}{M_r \sqrt{\left(\left(\frac{\omega_r}{\omega} \right)^2 - 1 \right)^2 + \left(2\xi_r \frac{\omega_r}{\omega} \right)^2}}$$

Frequency, damping ratio

$$\left| {}_r H_{lp}^a(\omega = \omega_r) \right| = \frac{\varphi_{pr}}{2\xi_r M_r} \cdot \varphi_{lr}$$



Mode

$$\{\varphi_{1r}, \varphi_{2r}, \dots, \varphi_{lr}, \dots\}^T$$

$$\left| {}_r H_{mp}^{\bar{\varepsilon}}(\omega) \right| = \frac{\eta_m \varphi_{pr} (\varphi_{ir} - \varphi_{jr})}{M_r \sqrt{(\omega_r^2 - \omega^2)^2 + (2\xi_r \omega_r \omega)^2}}$$

same

$$\left| {}_r H_{mp}^{\bar{\varepsilon}}(\omega = \omega_r) \right| = \frac{\varphi_{pr}}{2M_r \xi_r \omega_r^2} \cdot \underline{\eta_m (\varphi_{ir} - \varphi_{jr})}$$

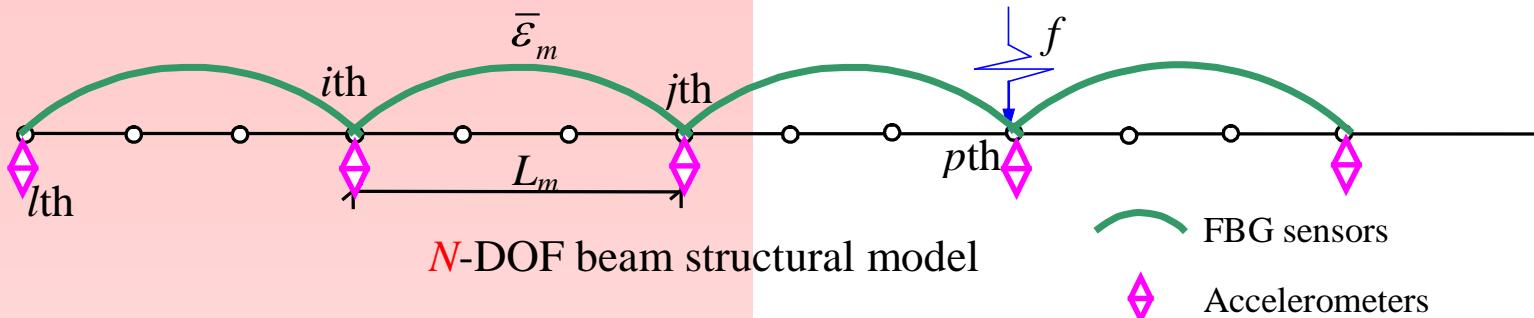


Modal macro-strain vector (MMSV)

$$\{\delta_{1r}, \delta_{2r}, \dots, \delta_{mr}, \dots\}^T$$

$$\eta_m = \frac{h_m}{L_m}$$

Modal parameters



The complete set of the r th-order mode shape (including translational and rotational DOFs) can be written as:

Mode shape based on accelerometers: $\{\lambda_{nr}\}^T = \{\lambda_{1r}, \lambda_{2r}, \dots, \lambda_{nr}, \dots, \lambda_{Nr}\}^T$
MMSV based on FBG sensors:

$$\{\varphi_l\}_r = \begin{Bmatrix} \varphi_1 \\ \varphi_2 \\ \vdots \\ \varphi_l \\ \vdots \\ \varphi_L \end{Bmatrix}_r = [A]_{L \times N} \cdot \begin{Bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_n \\ \vdots \\ \lambda_N \end{Bmatrix}_r$$

$$\{\delta_m\}_r = \begin{Bmatrix} \delta_1 \\ \delta_2 \\ \vdots \\ \delta_m \\ \vdots \\ \delta_M \end{Bmatrix}_r = \begin{Bmatrix} \eta_1 \cdot (\lambda_{i1} - \lambda_{j1}) \\ \eta_2 \cdot (\lambda_{i2} - \lambda_{j2}) \\ \vdots \\ \eta_m \cdot (\lambda_{im} - \lambda_{jm}) \\ \vdots \\ \eta_M \cdot (\lambda_{iM} - \lambda_{jM}) \end{Bmatrix}_r = [B]_{M \times N} \cdot \begin{Bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_n \\ \vdots \\ \lambda_N \end{Bmatrix}_r$$

The same mapping relations as dynamic measurements!!

MMSV: average curvature mode shape

Modal Analysis on Macro-strain Measurements from Distributed Long-gage Fiber Optic Sensors

Macro-strain Frequency Response Function (FRF)

$$\frac{{}_r H_{lp}^d(\omega)}{{}_r H_{mp}^{\bar{\varepsilon}}(\omega)} = \frac{{}_r A_{lp}^d}{{}_r A_{mp}^{\bar{\varepsilon}}} = \frac{\varphi_{lr}}{\delta_{mr}} = \frac{\varphi_{lr}}{\eta_m(\varphi_{ir} - \varphi_{jr})}$$

Macro-strain FRF is close to a displacement FRF rather than a velocity or acceleration one, more sensitive indicator at low modes

The identified resonant frequency and damping ratio from dynamic macro-strain measurements hold the same precision as those from conventional transducers

Representations of Macro-strain FRF

$${}_r H_{mp}^{\bar{\varepsilon}}(\omega) = {}^R H_{mp}^{\bar{\varepsilon}}(\omega) + j \cdot {}^I H_{mp}^{\bar{\varepsilon}}(\omega)$$

$$|{}_r H_{mp}^{\bar{\varepsilon}}(\omega)| = \sqrt{[{}^R H_{mp}^{\bar{\varepsilon}}(\omega)]^2 + [{}^I H_{mp}^{\bar{\varepsilon}}(\omega)]^2} = \frac{A_{mp}^r}{\sqrt{(\omega_r^2 - \omega^2)^2 + (2\xi_r \omega_r \omega)^2}}$$

Magnitude

$$\phi_H = \arctan \frac{{}^I H_{mp}^{\bar{\varepsilon}}(\omega)}{{}^R H_{mp}^{\bar{\varepsilon}}(\omega)} = \arctan \left[\frac{-2\xi_r \omega_r \omega}{\omega_r^2 - \omega^2} \right]$$

Phase

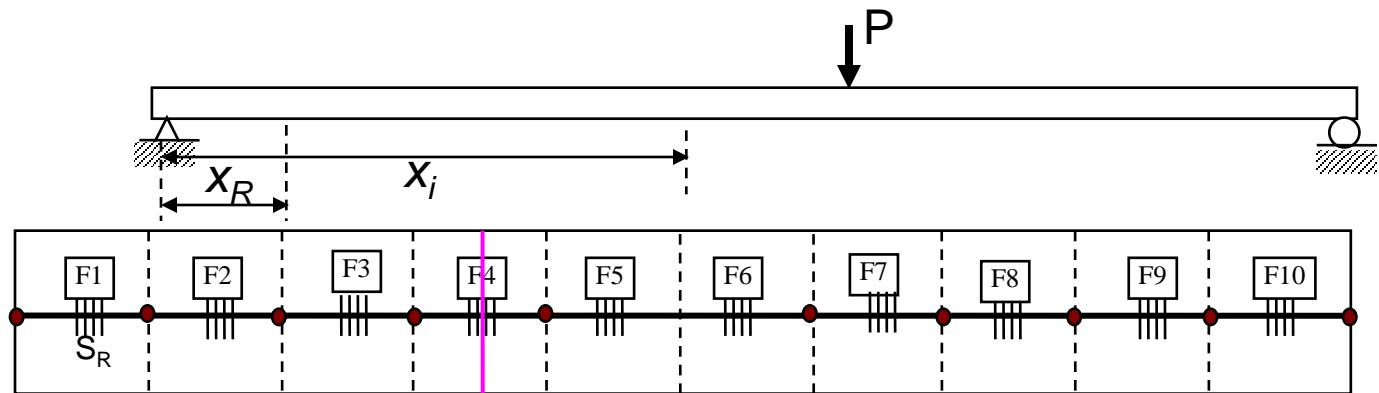
Identification based on Statistics of Relative Static Long Gage Stress

Intact

$$\gamma_i = \frac{\varepsilon_i}{\varepsilon_R} = \frac{x_i}{x_R}$$

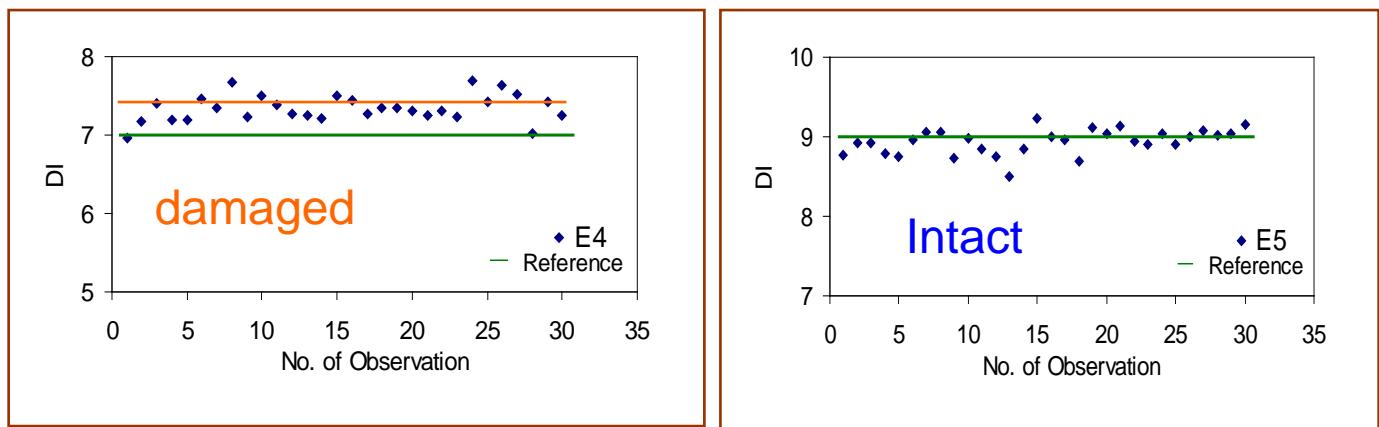
Damaged

$$\gamma_i^* = \frac{\varepsilon_i^*}{\varepsilon_R} = \frac{1}{\beta} \frac{x_i}{x_R} \quad (0 \leq \beta \leq 1)$$



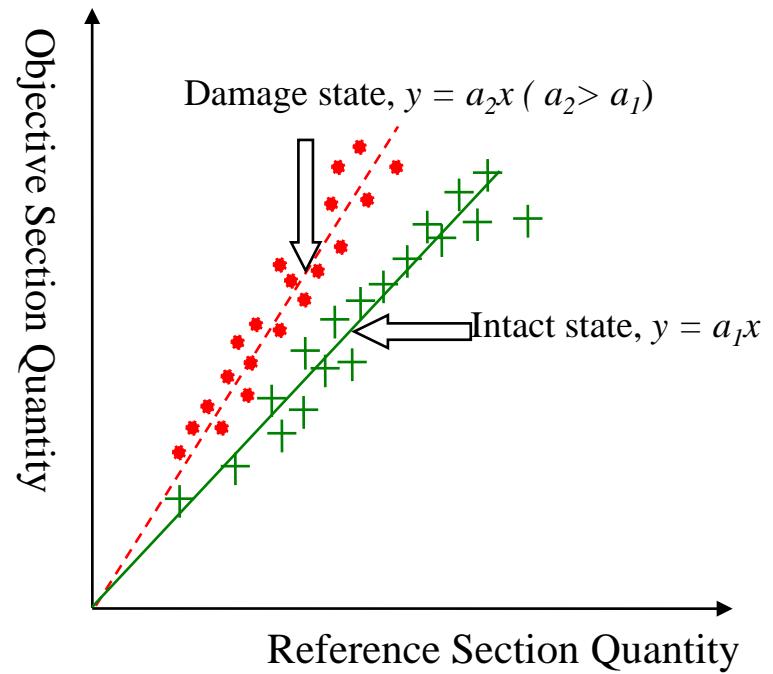
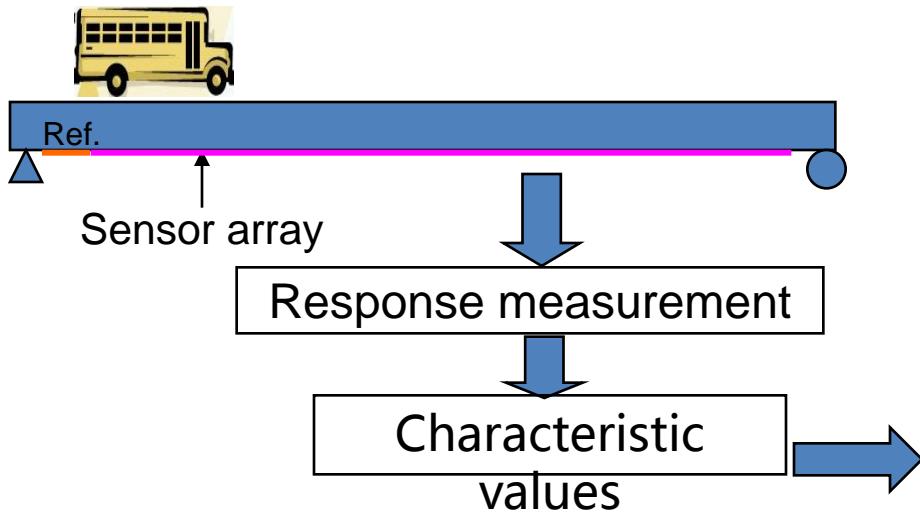
Robust to noise

Increase the identification ability

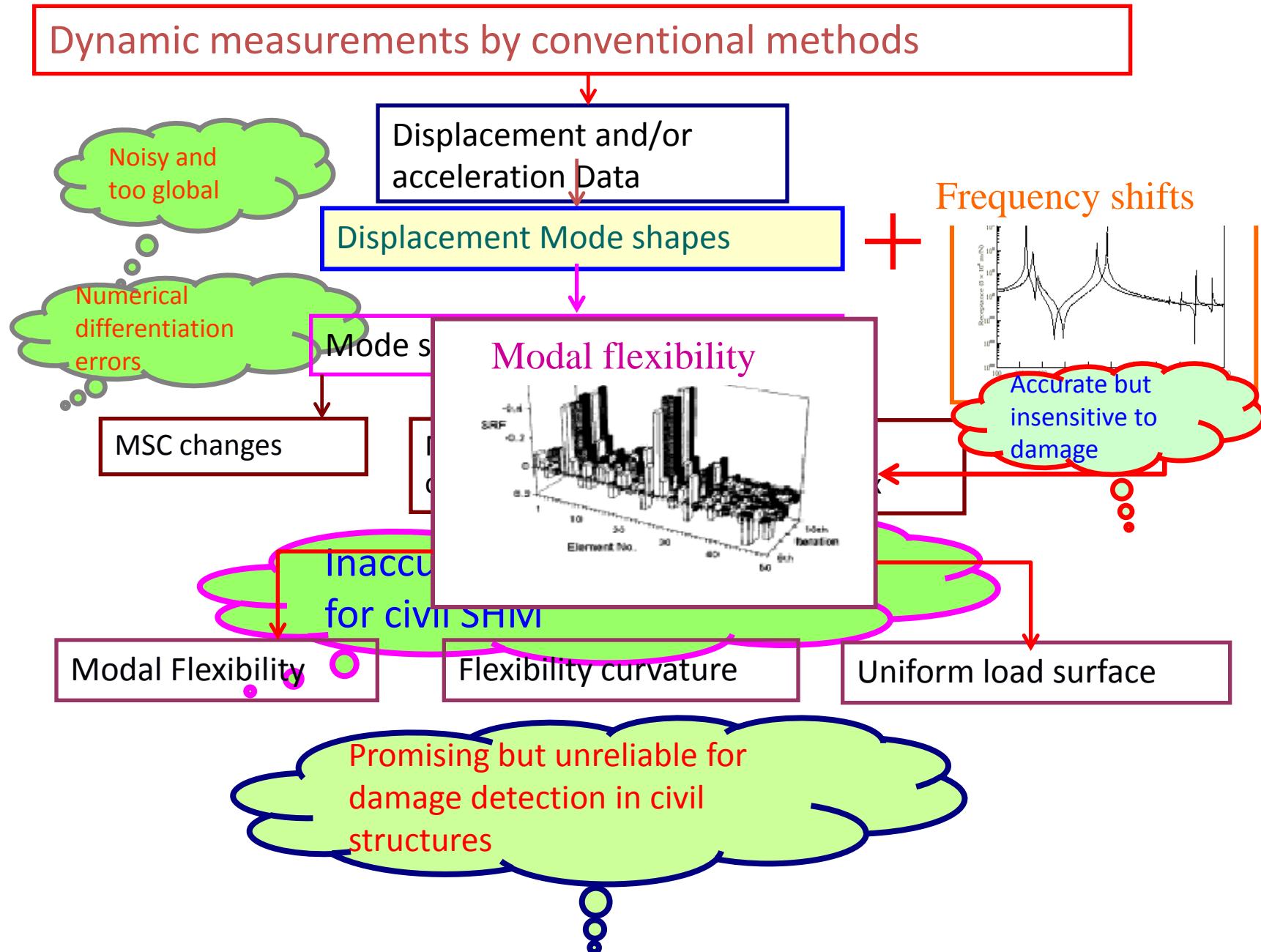


Damage Identification with Output Only

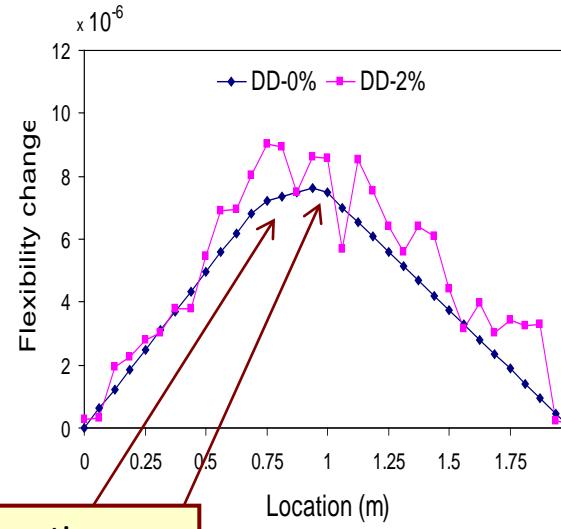
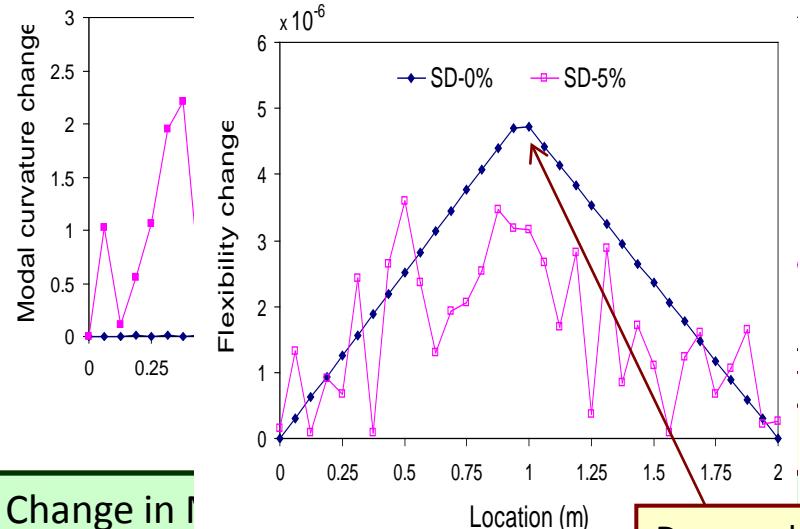
- ❖ For certain structure conditions, ratios of stress (time domain) and stress modal (frequency domain) of two monitored sections are constant
- ❖ Slopes of fitting lines will also be constant
- ❖ Damage will make the slopes change
- ❖ Robust to environment and noise



Conventional typical non-model based DI identification



Damage identification with 2% noise based on displacement measurement

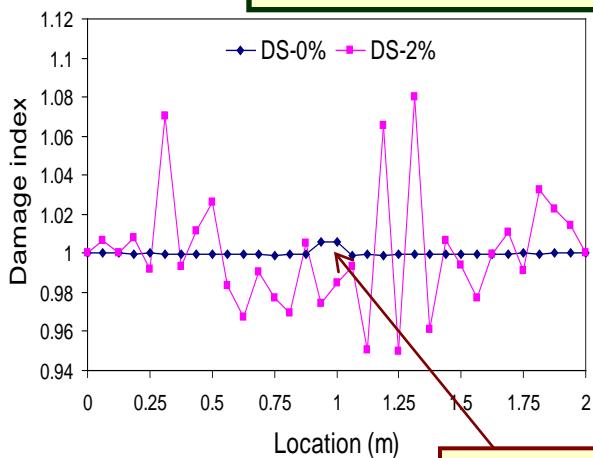


Curvature and damage index absolutely damage in 2% noise.

Change in damage index

Damage locations

Change in flexibility method from displacement data



Modal flexibility methods are also limited by 2% noise. The method is ineffective for damage localization in civil structures.

Damage locations

further magnified by numerical differentiation

Strain Energy-based damage indices from displacement data

Modified typical non-model based DI identification

Dynamic strain measurements using long-gauge FBG sensors

Sensitive to local
damages and robust
to noise

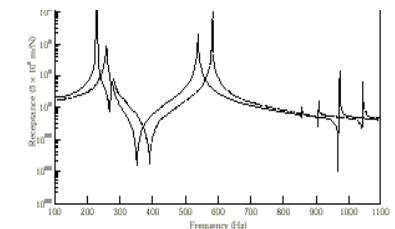
MacroStrain Data

Strain Mode Shapes

Frequency shifts

Mod

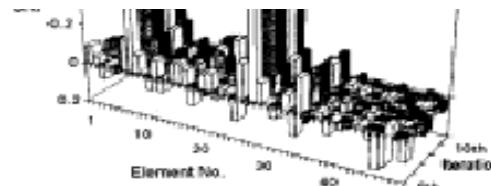
MMS-flexibility Methods



Modal curvature
changes

Energy Damage

Gran
SHM



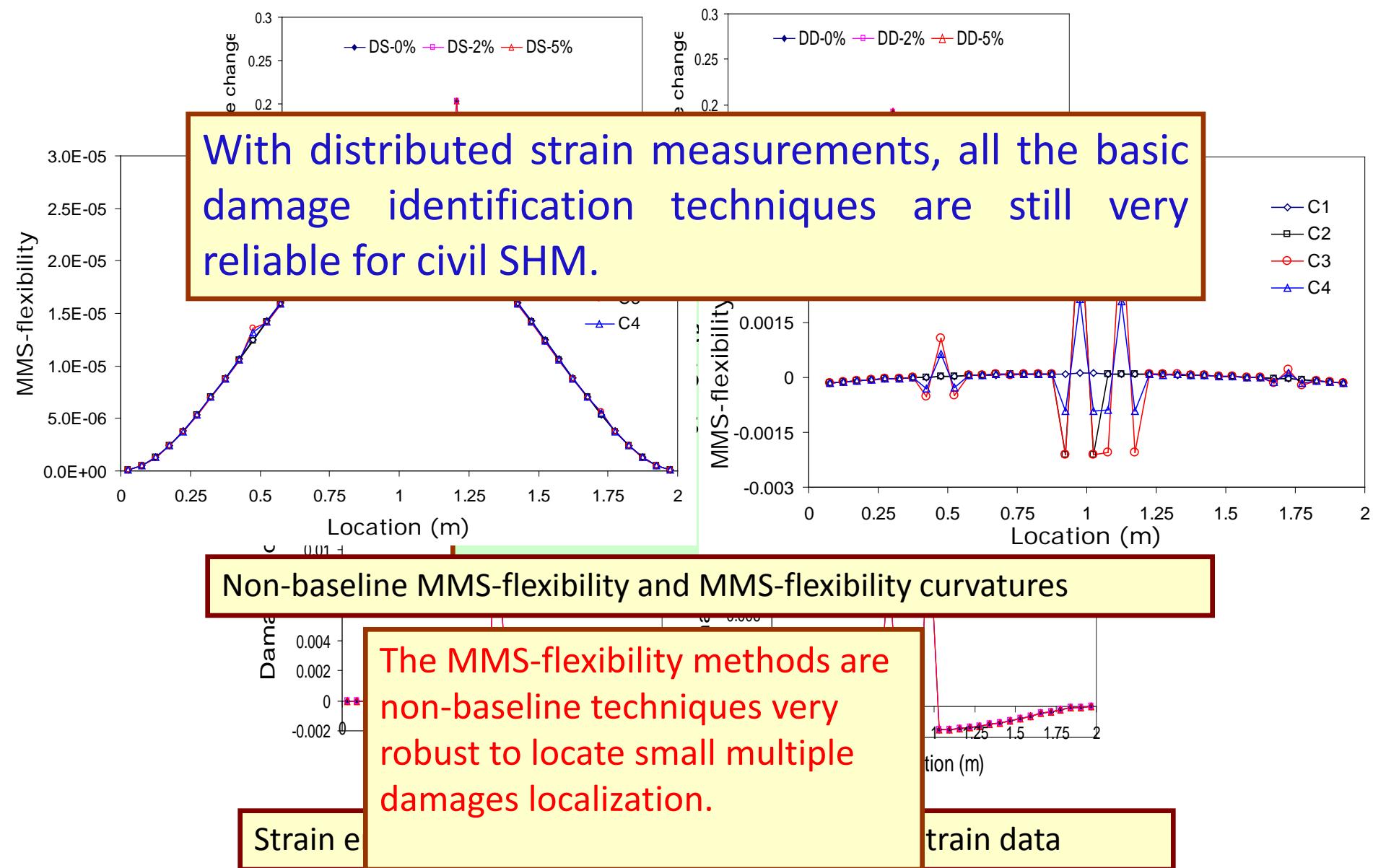
MMS-Flexibility

MMS-Flexibility
curvature

Uniform load surface

Significantly enhanced
for multiple damage
localization even without
baseline information

Damage identification with 5% noise based on distributed strain measurement



Material and Structure Intelligentization

Distributed Optical Fiber—Basalt Fiber Self-Sensing Bar



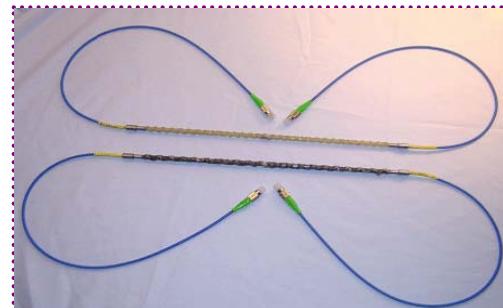
**Distributed
Optical Fiber
Sensing**

+



Basalt fiber packaged optical fiber sensor

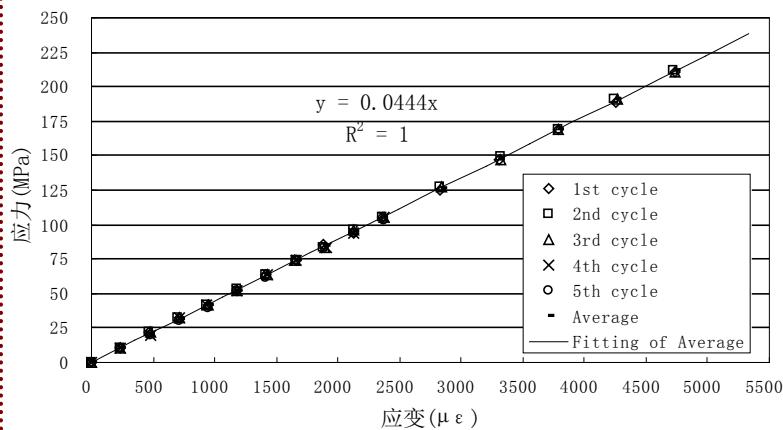
Production



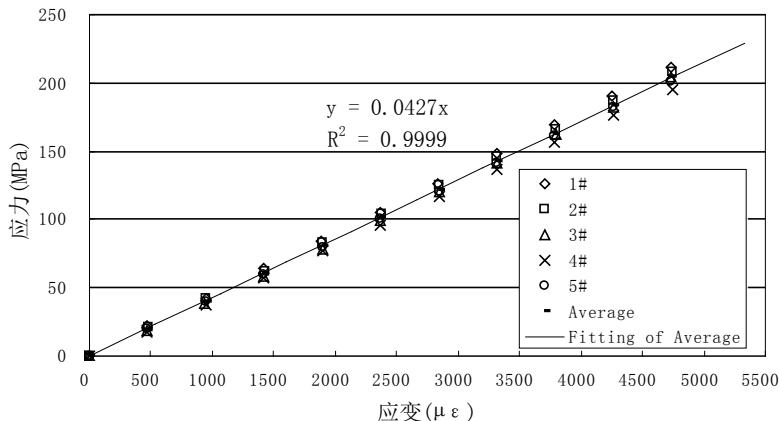
Basalt Fiber Self-
Sensing Bar

Characteristics of Self-sensing Bar

Strain-Stress (different cycle)

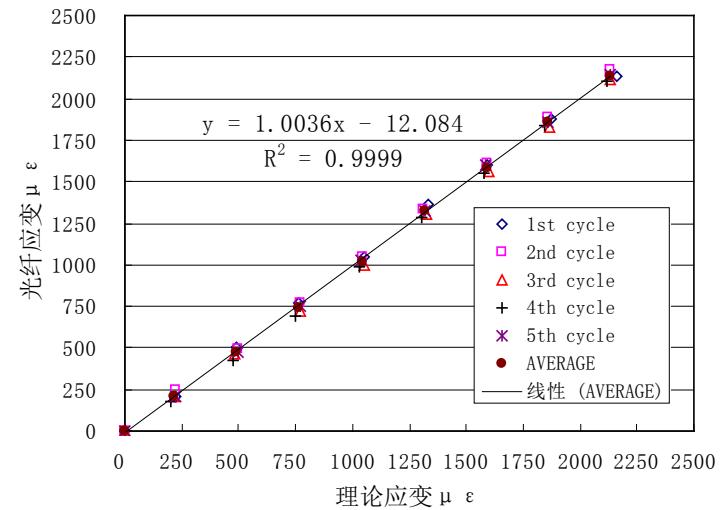


Strain-Stress (different sample)

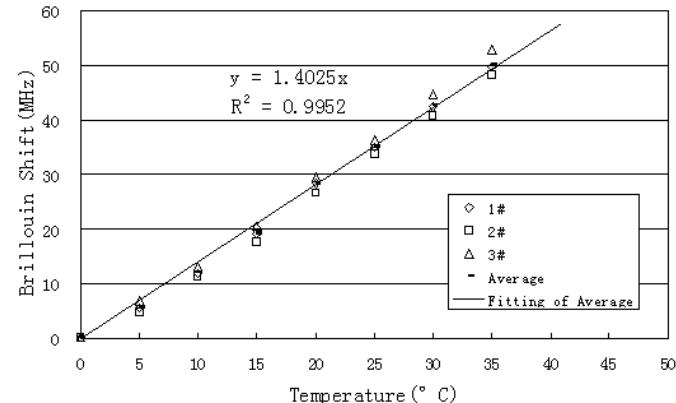


Mechanical characteristics

Stress Sensitivity Characteristics

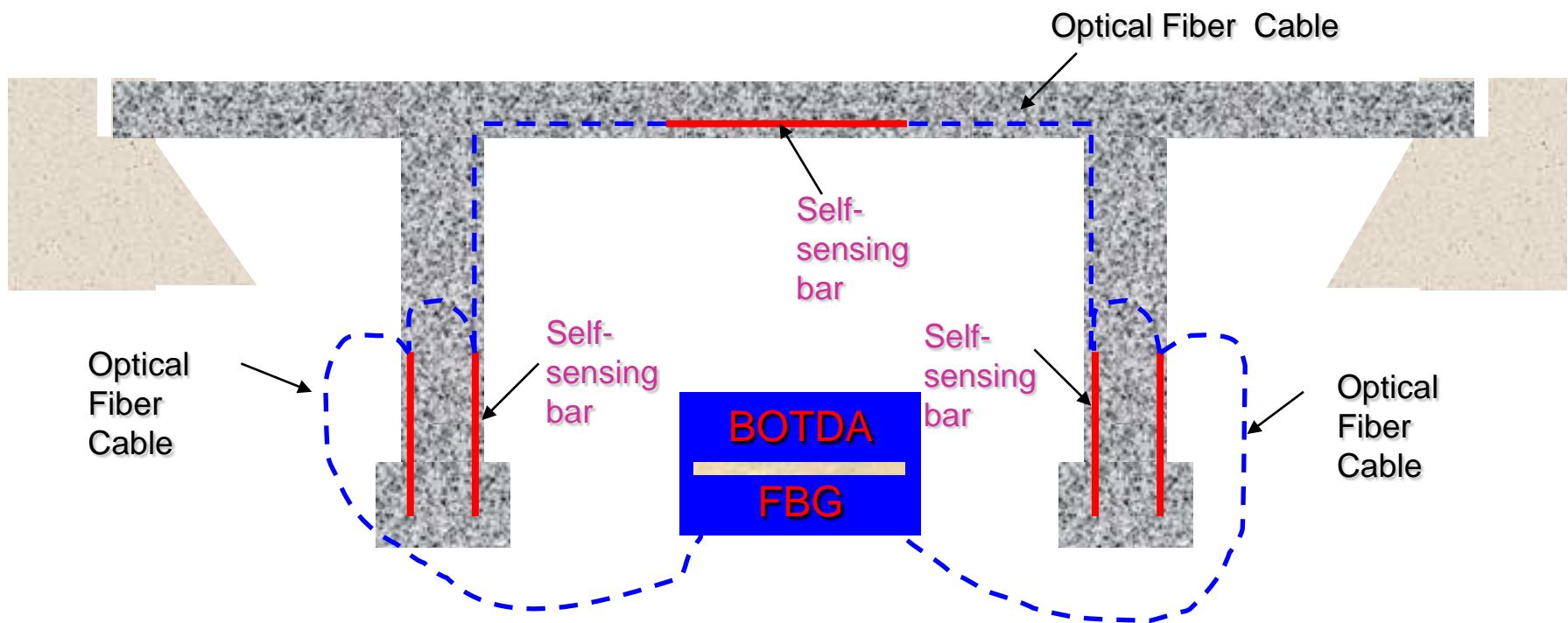


Temperature Sensitivity Characteristics

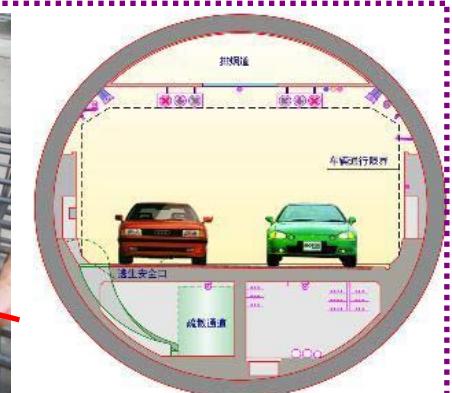
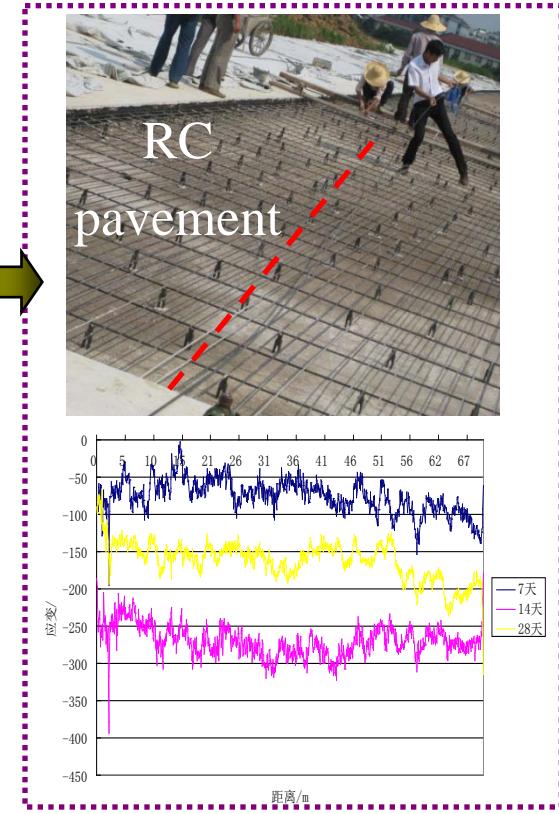
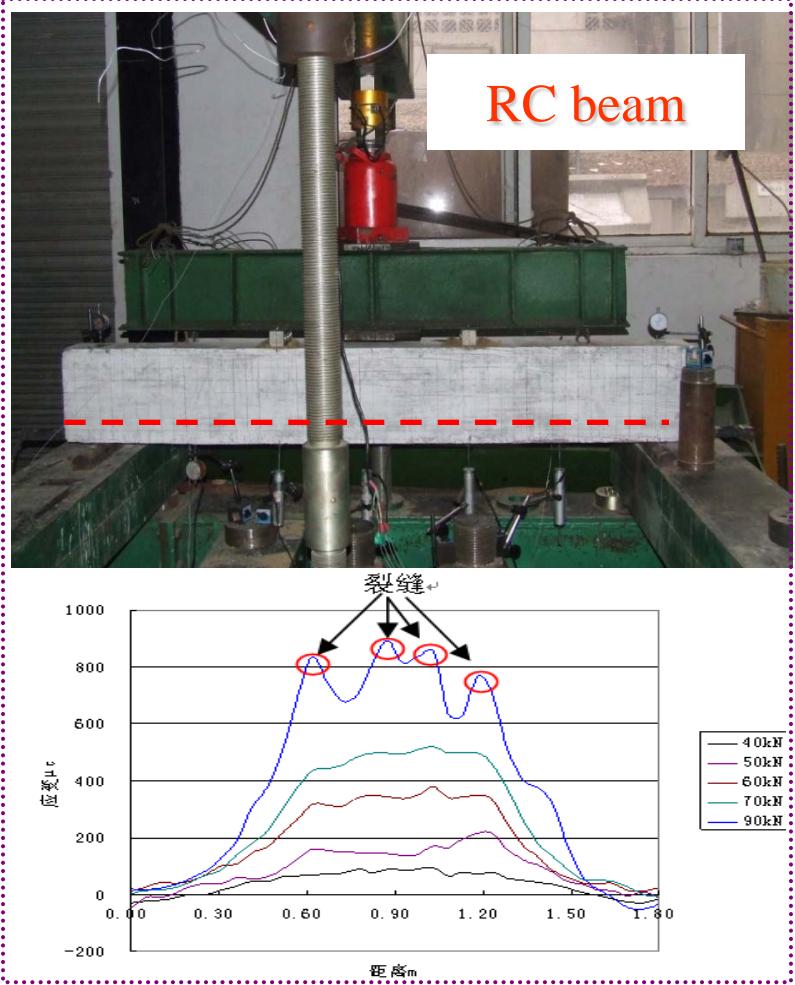


Sensing characteristics

Structural Strengthening and Health Monitoring based on Self-sensing Bar

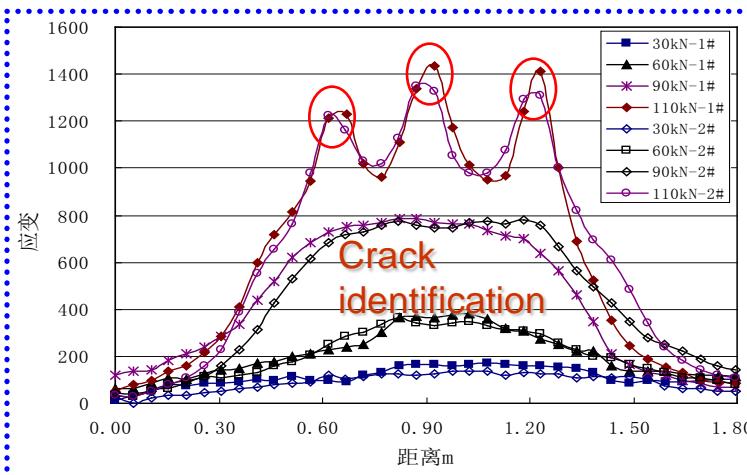


Engineering applications of smart BFRP rebar

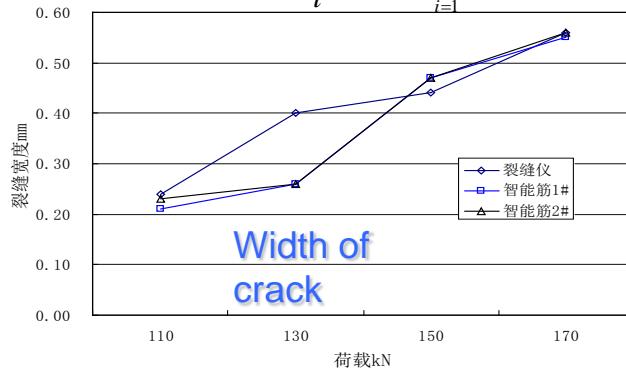




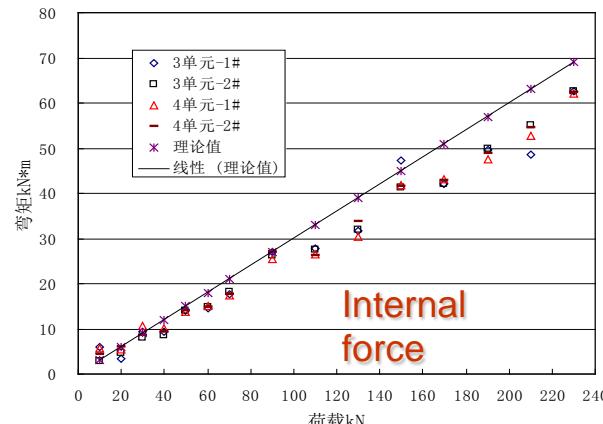
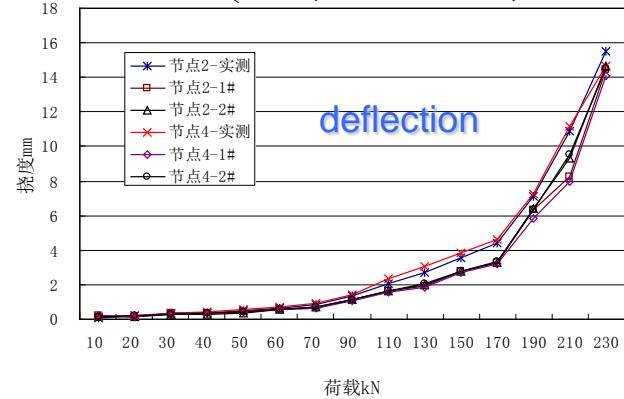
Application research of smart BFRP rebar



$$\omega = (\bar{\varepsilon}_s - \bar{\varepsilon}_c)l \approx \bar{\varepsilon}_s l = \frac{l}{l} * l = \sum_{i=1}^n 1/2 * (\varepsilon_i + \varepsilon_{i+1}) * \Delta l$$



$$v_p = M'_p = -\left(\frac{l}{6}\right)^2 * \left(\frac{p}{6} \sum_{i=1}^6 \frac{\bar{\varepsilon}_i}{y_i} \left(6-i+\frac{1}{2}\right) - \sum_{i=1}^p \frac{\bar{\varepsilon}_i}{y_i} \left(p-i+\frac{1}{2}\right) \right)$$



Application to Transportation Infrastructure

Manual checking by watching
Time consuming and laborious



Natural frequency measurement using Hammer Excitation Method (30kgf)



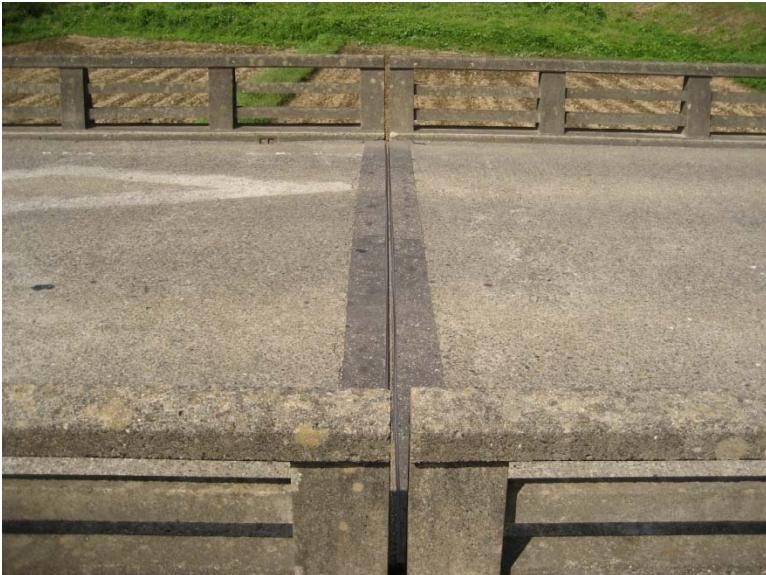
Traditional testing method is time consuming and laborious, but only “rough” testing.

With optical fiber sensing based monitoring, efficiency of monitoring and hence the safety of structure can be significantly enhanced.

SHM System of Kawane Bridge

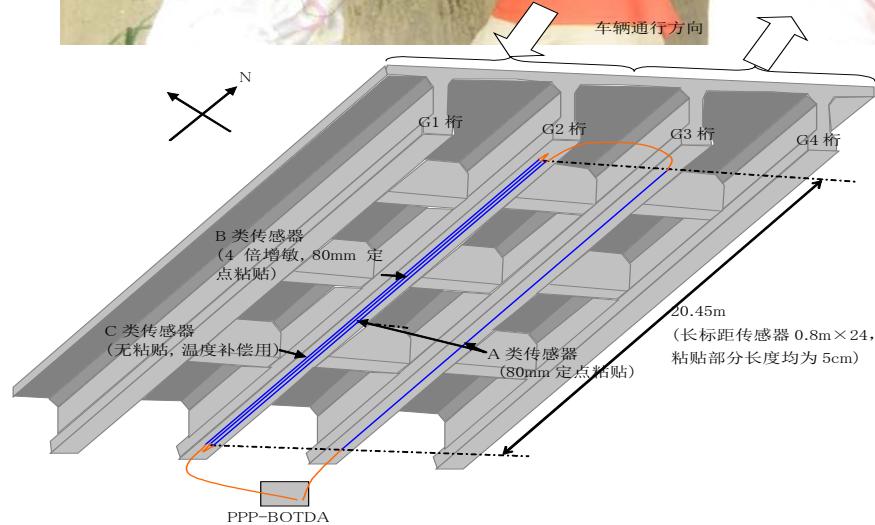
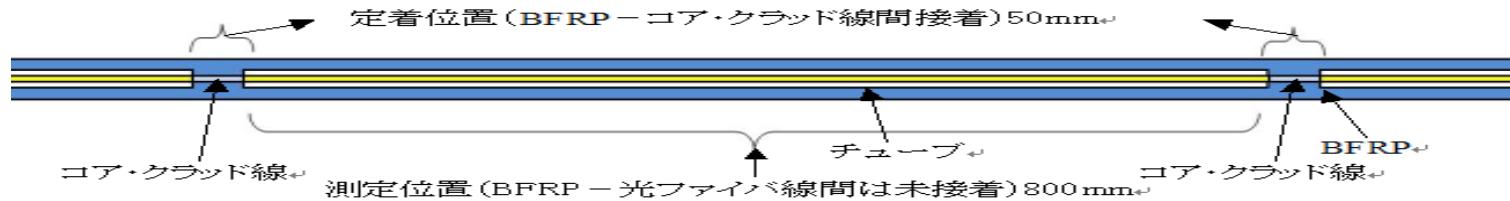
Kawane Bridge

- Type: RC Structure
- Age: 45 years
- Location: Ibaraki, Japan
- Length: about 127 m

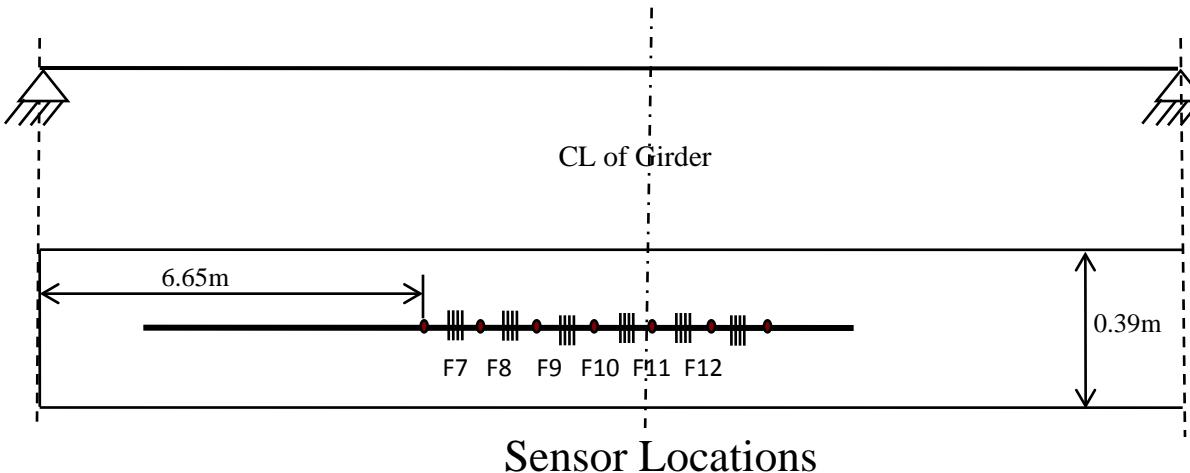


On-site Testing

Long Gage FBG sensor



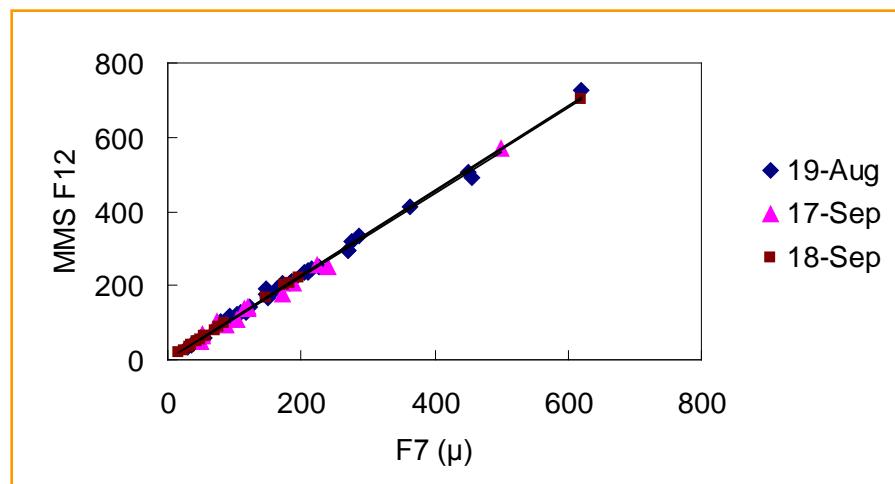
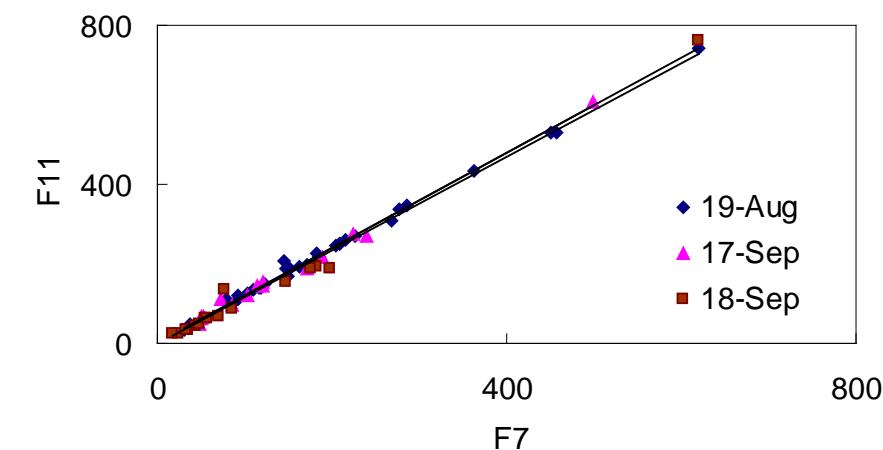
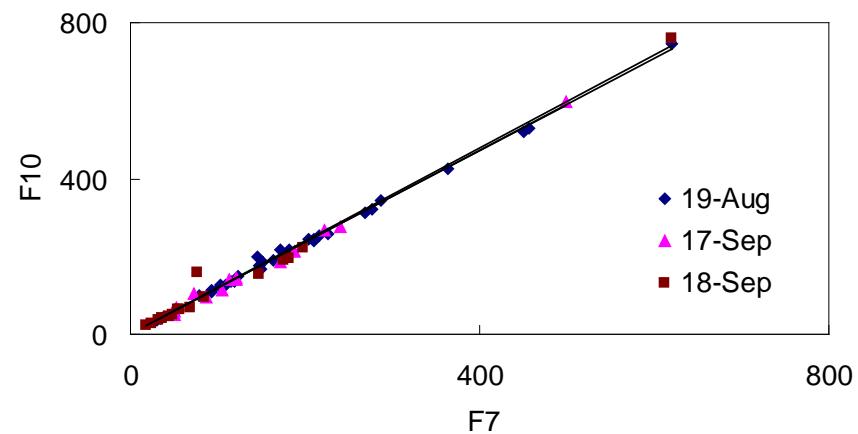
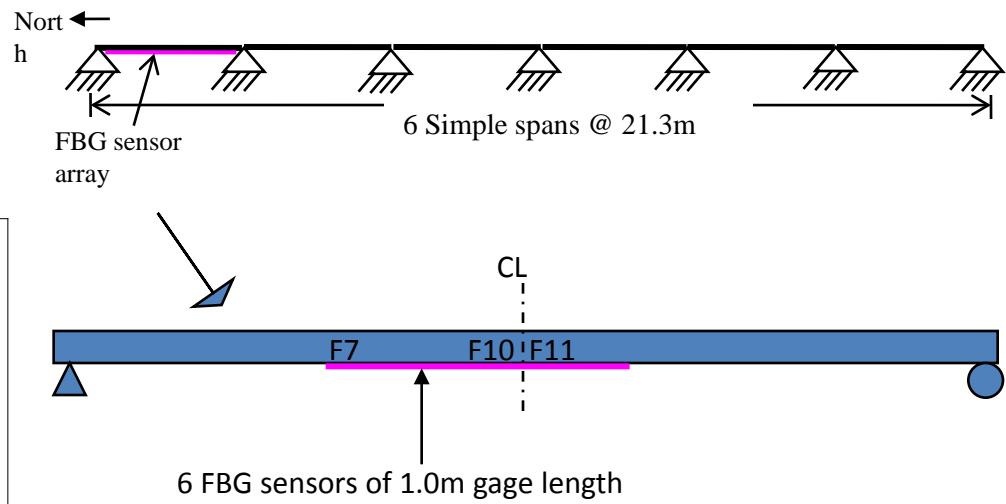
SHM System of Kawane Bridge



Monitoring Results (1)

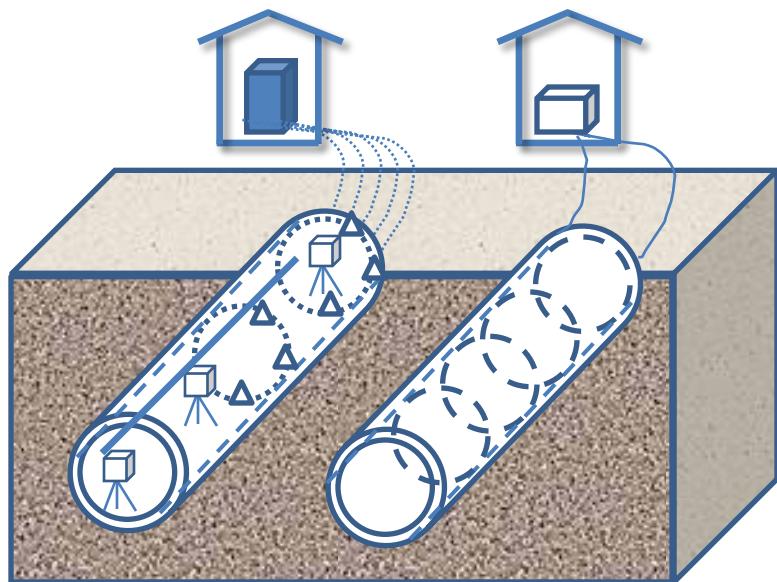
Date	Weather Condition	Average air temperature (°C)	First modal frequency (Hz)
August 19, 2008	Sunny	27.3	4.81
September 17, 2008	Sunny	26.4	4.91
September 18, 2008	Rainy	23.3	5.02

Results of monitoring



Qingchun Lu Tunnel Monitoring Using Distributed Optical Fiber Sensing Technology

• Tunnel Monitoring



全站仪 全站仪
△ 土压力计 △ 土压力计
— 水平液位计 — 水平液位计
… 应变计 … 应变计
□ 集线器 □ 集线器
光纤 光纤 分析仪 分析仪

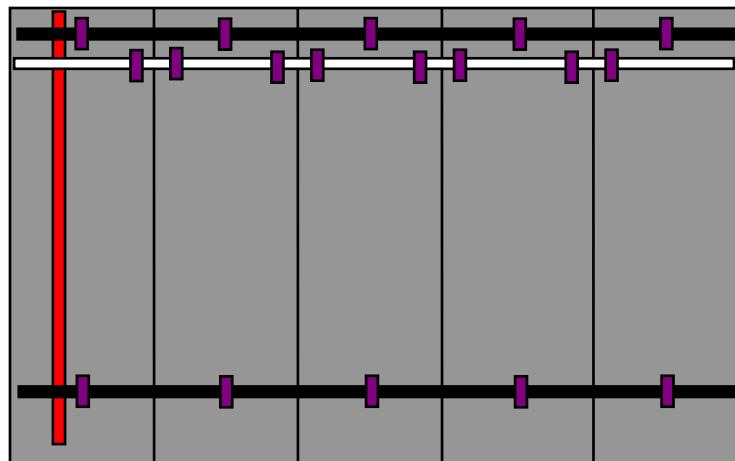
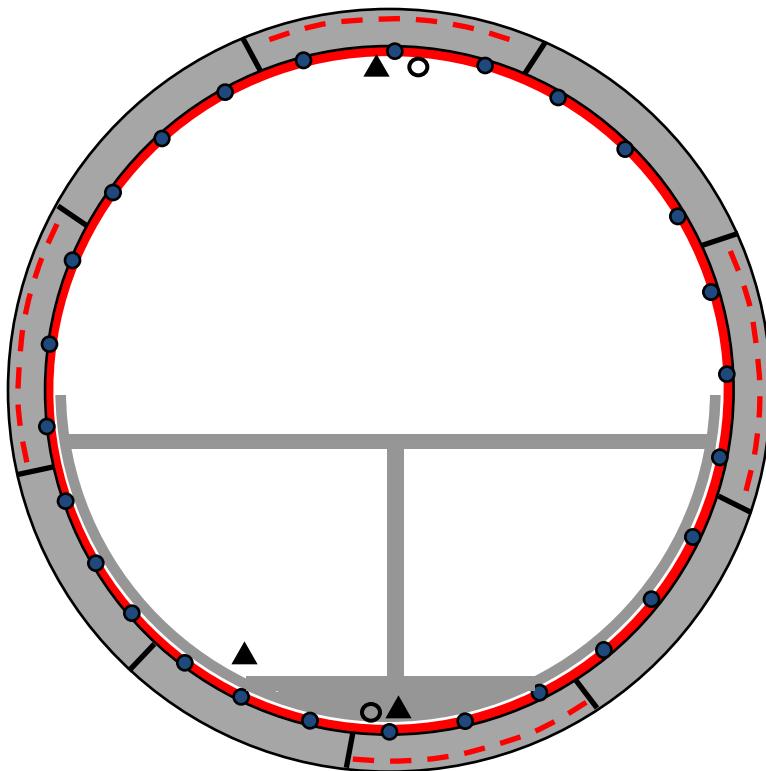
Traditional method	Optic fiber-based monitoring
<i>Test Quantity Limited</i>	<i>Test Quantity Increased</i>
Point testing	Distributed testing
<i>multiple sensor types</i>	<i>Few Types</i>
<i>Short time monitoring</i>	<i>Long time monitoring</i>
<i>Expensive for large scale monitoring</i>	<i>Cheap for large scale monitoring</i>

Applications

- Structural linear
- Key-positions unknown
- Multi-section, multi-item, synthetic monitoring
- Long time & severe environment monitoring
- Anti-Electromagnetic Interference

Qingchun Lu Tunnel Monitoring Using Distributed Optical Fiber Sensing Technology

- Overall Implementing Plan

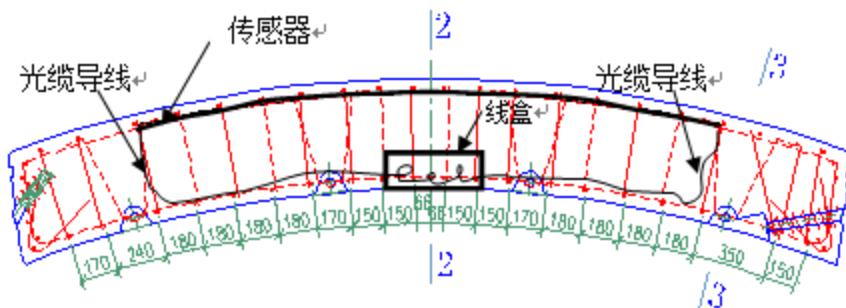
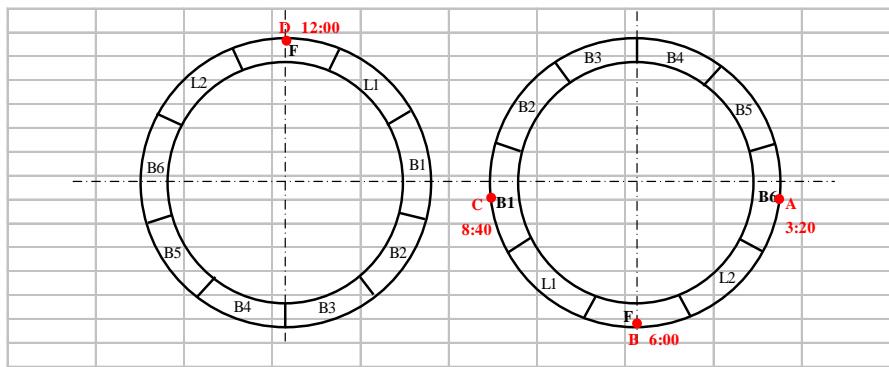


- - - : Embedded fiber sensor (concrete stress monitoring)
- - : Surface deployed fiber sensors (tunnel diameter monitoring)
- ▲ : Surface deployed fiber sensors (tunnel subsidence monitoring)
- : Surface deployed fiber sensors (seam monitoring of tunnel lining segments)
- ■ : Special clamping devices

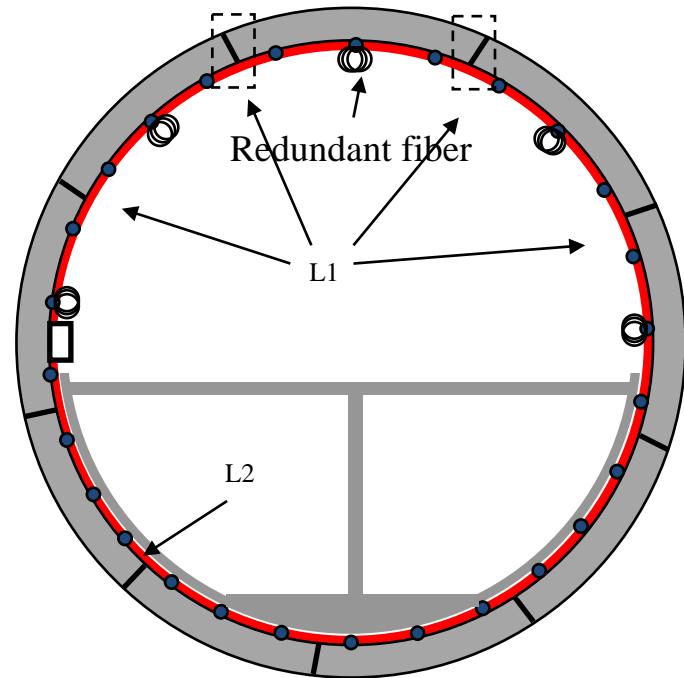
Qingchun Lu Tunnel Monitoring Using Distributed Optical Fiber Sensing Technology

- Implementing Plan

Inner-force monitoring



Diameter monitoring

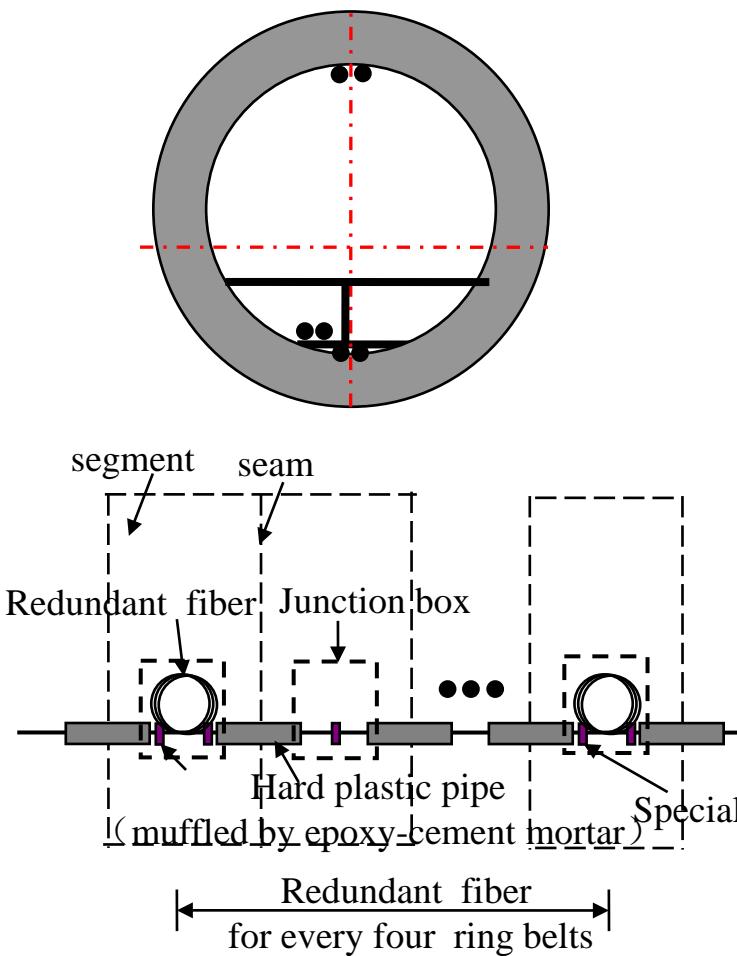


- : Optical Fiber Sensors
- : Special clamping devices
- : Junction box

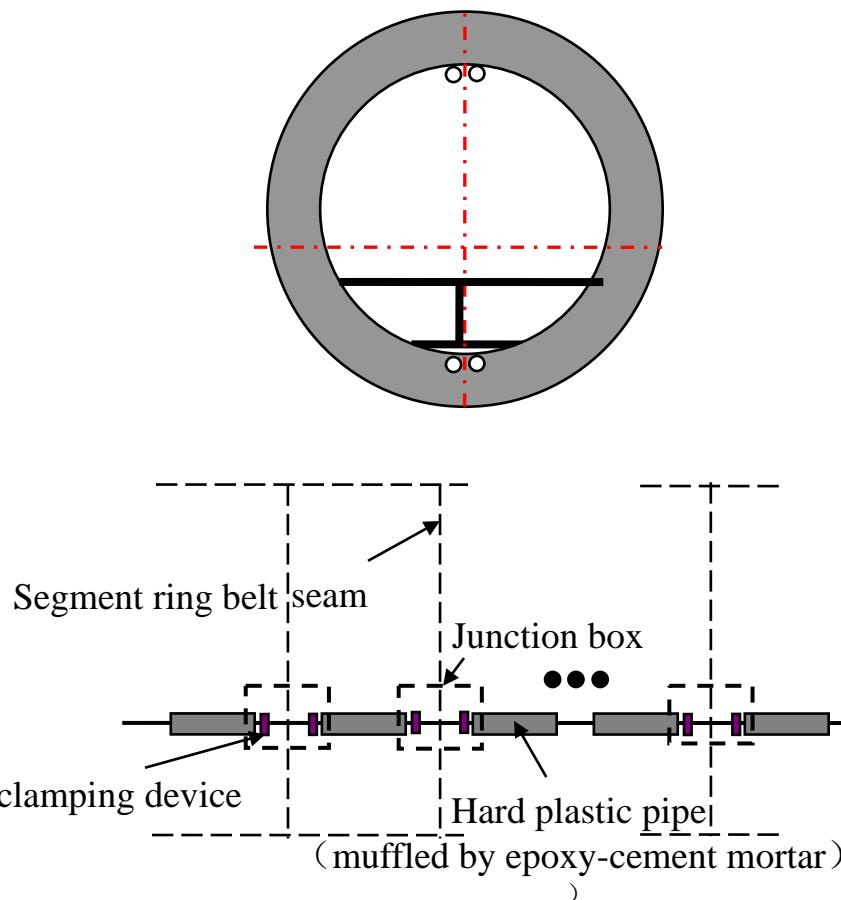
Qingchun Lu Tunnel Monitoring Using Distributed Optical Fiber Sensing Technology

- Implementing Plan

Subsidence monitoring

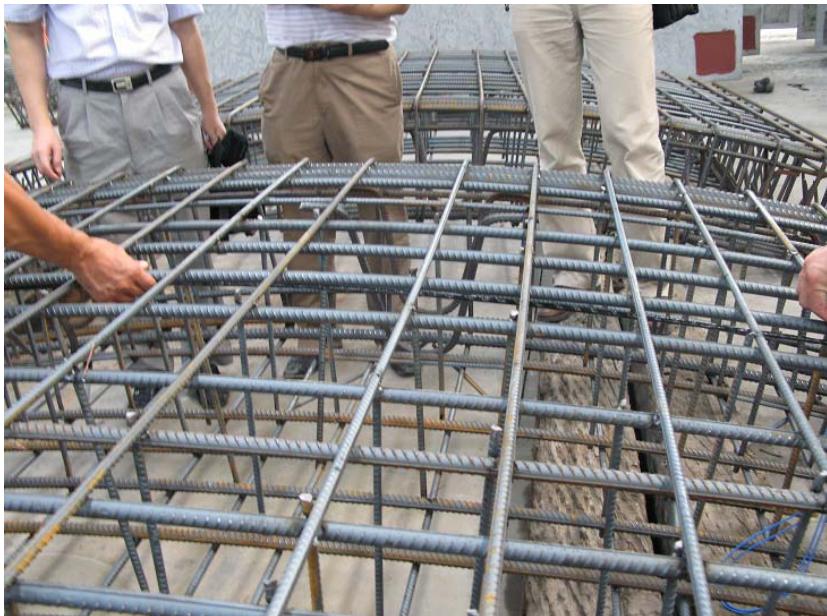


Seam monitoring of tunnel lining segments



Qingchun Lu Tunnel Monitoring Using Distributed Optical Fiber Sensing Technology

- Real Deployment of Sensors for Inner Force Monitoring



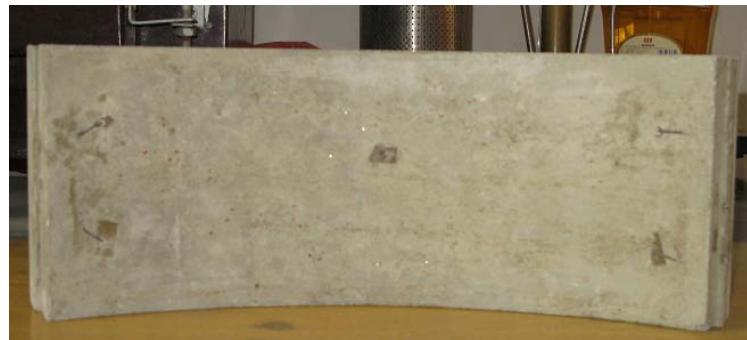
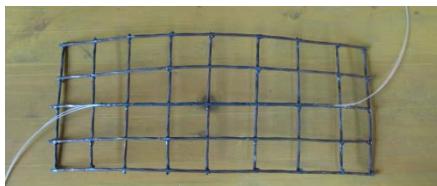
Optical sensor at the bottom of the main reinforcement

Junction box fixing



Qingchun Lu Tunnel Monitoring Using Distributed Optical Fiber Sensing Technology

- Model-based Experiments
 - Model making



- Segments assembling



Qingchun Lu Tunnel Monitoring Using Distributed Optical Fiber Sensing Technology

- Model-based Experiments
 - Optical Fiber Sensor Deployment



Loading



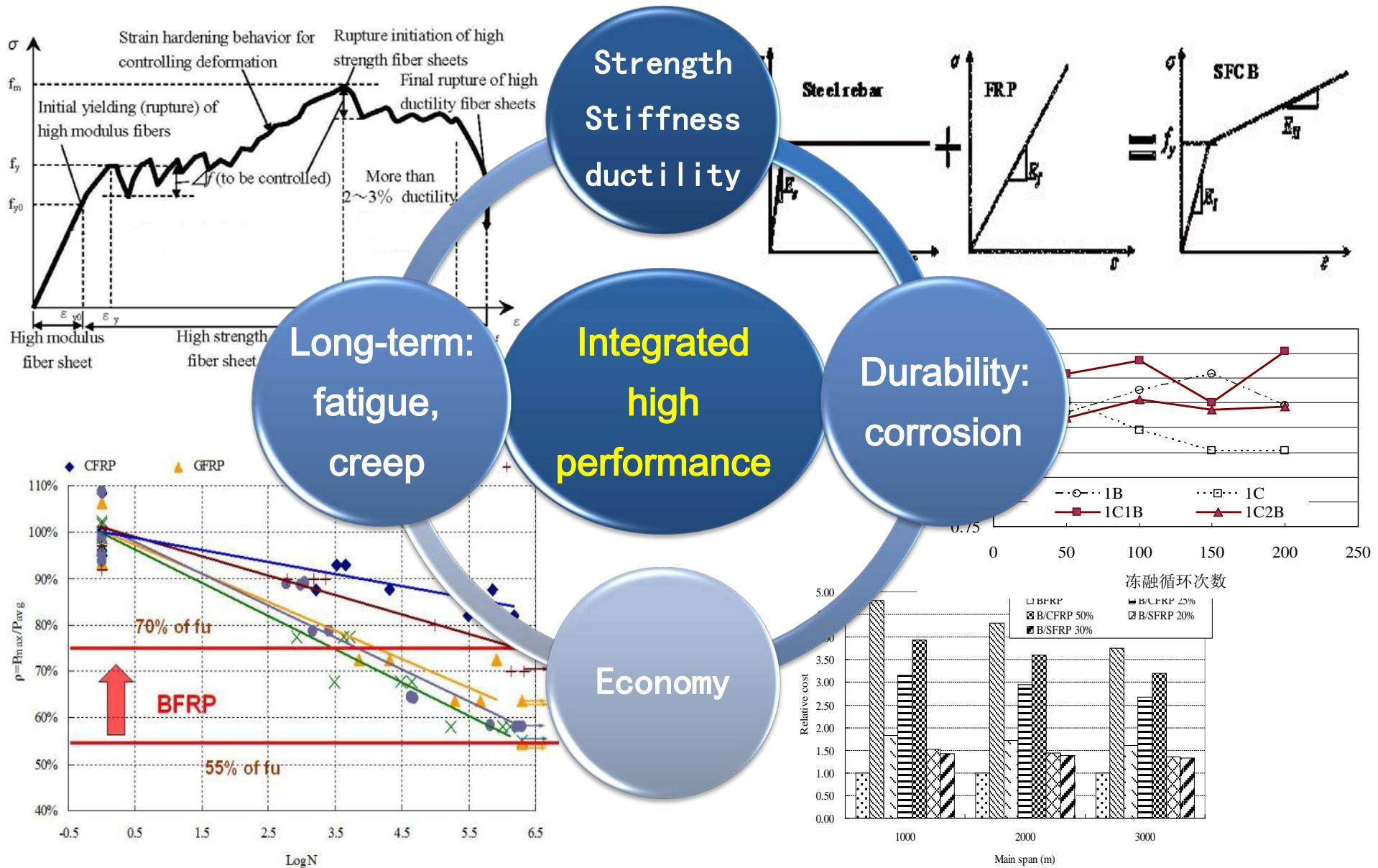
Outline

1. **Background**
2. **Introduction of FRP and research status**
3. **Hybrid FRP technology**
4. **Prestressing FRP technology**
5. **Damage-controllable FRP structures**
6. **Integrated high performance FRP structures**
7. **Intelligent infrastructures**
8. **Summary and future work**

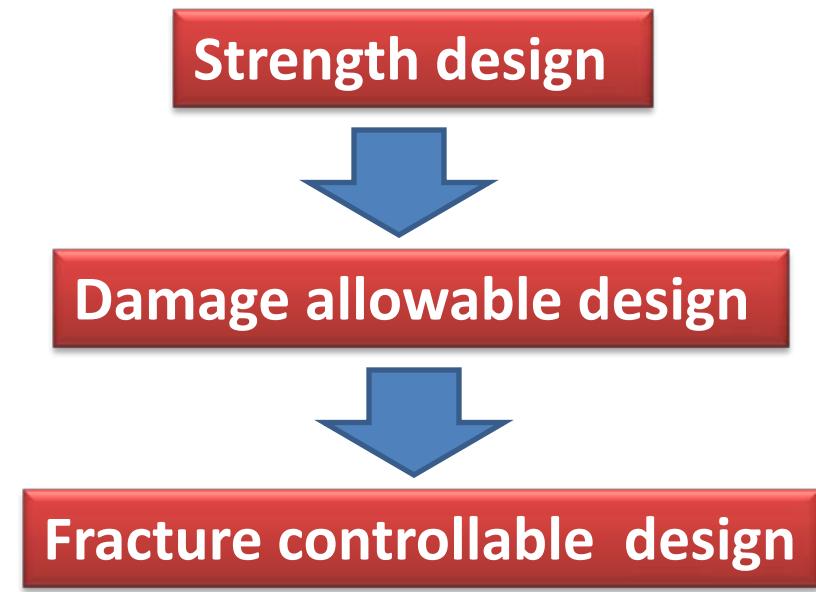
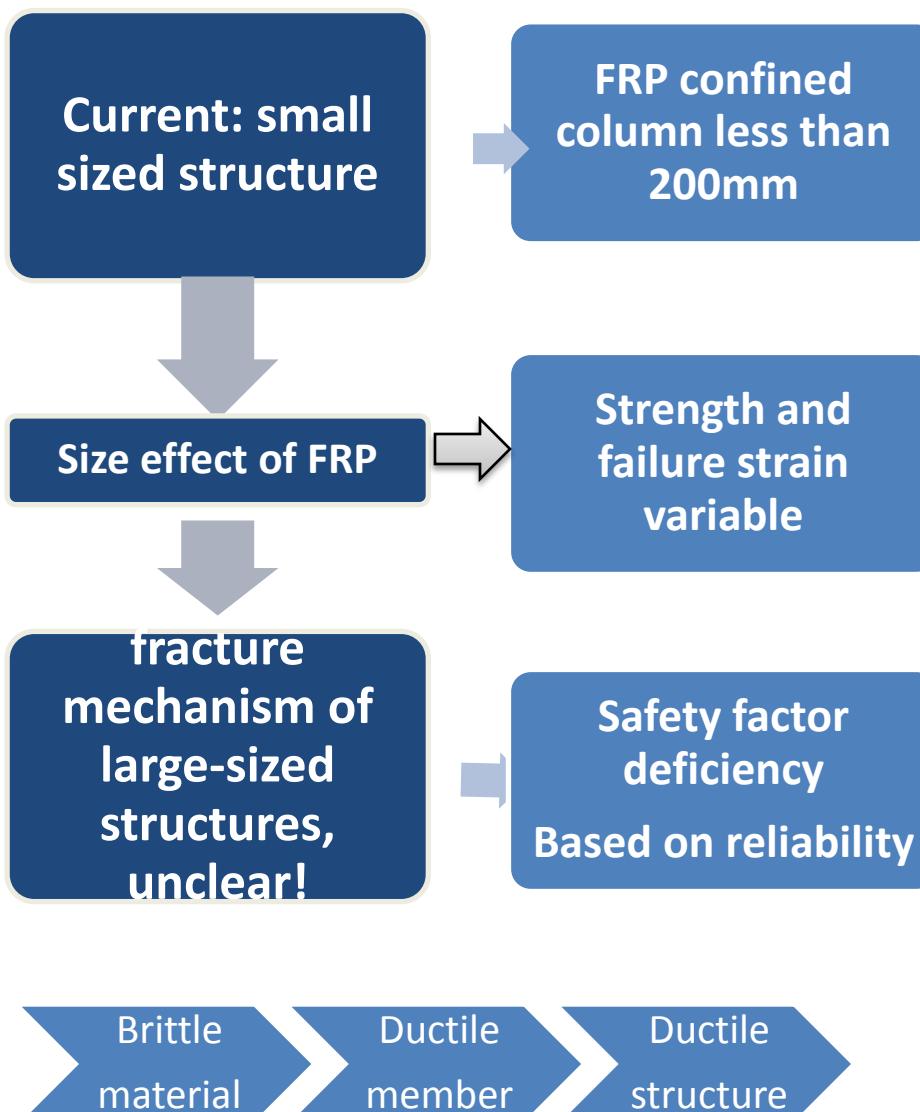
Summary

- ✓ Enhance FRP by hybridization
- ✓ Sufficiently use FRP by prestressing
- ✓ FRP realizing Damage-controllable structures
- ✓ FRP achieving integrated high performance structures
- ✓ Combining optic sensors with FRP: Self-sensing FRP bar

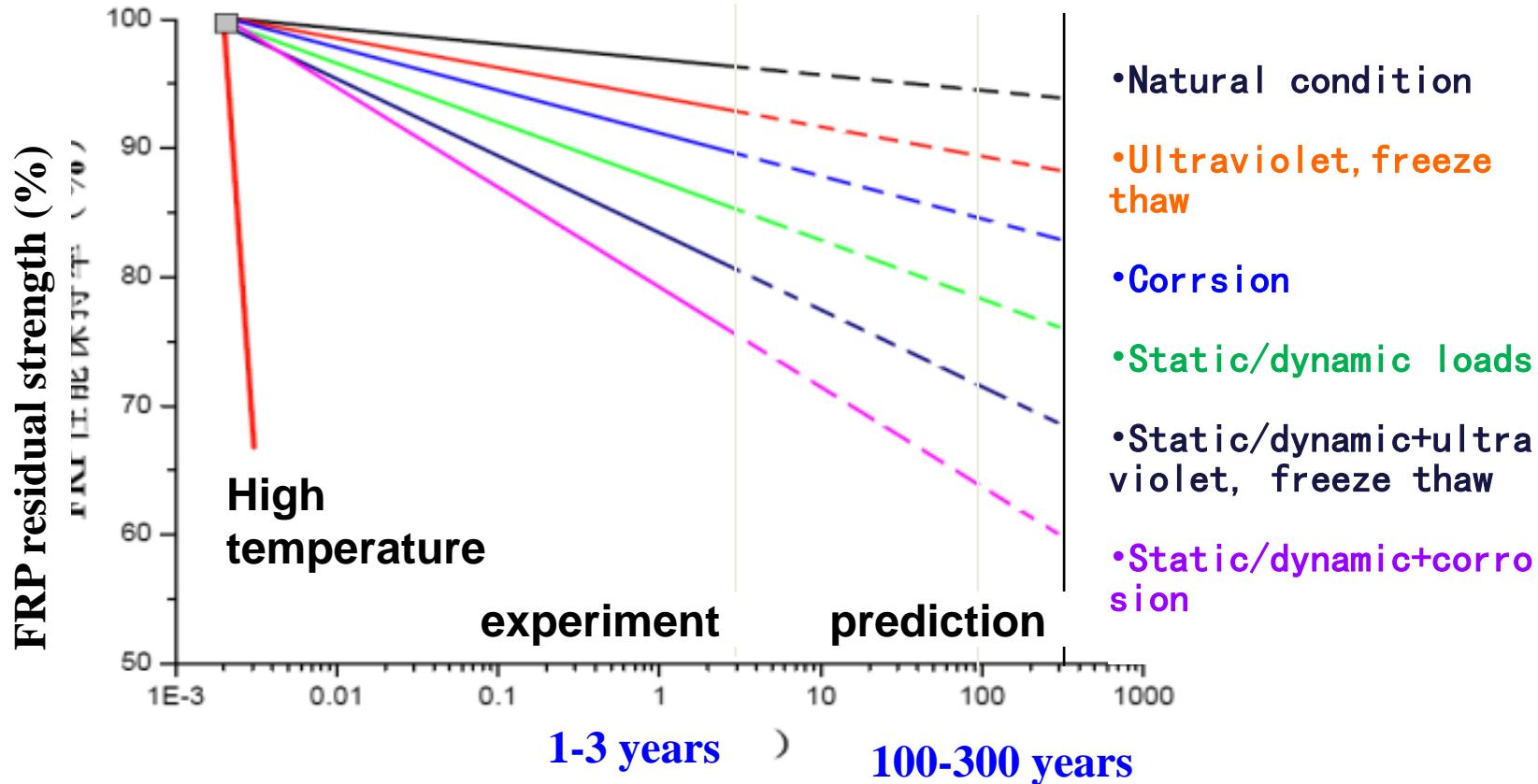
Future work: Enhancement of integrated behavior of FRP



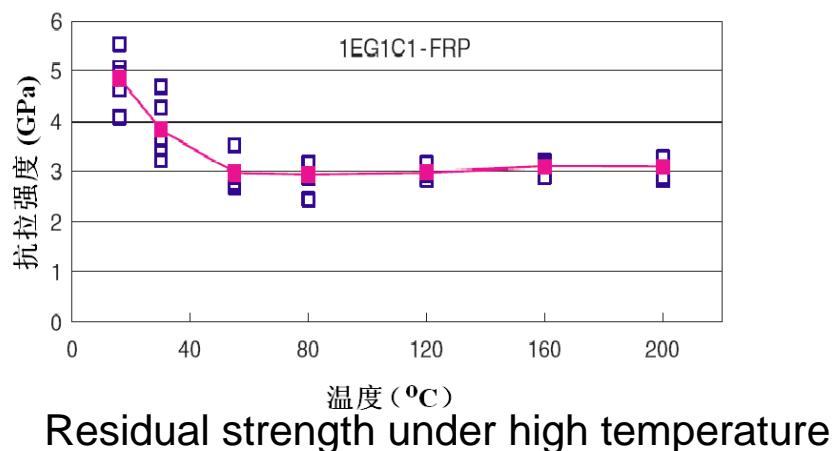
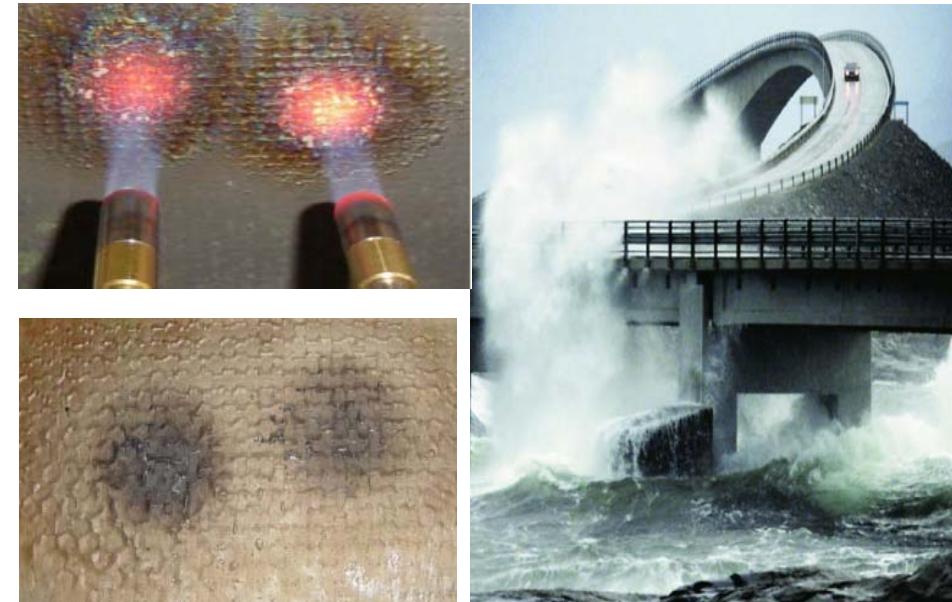
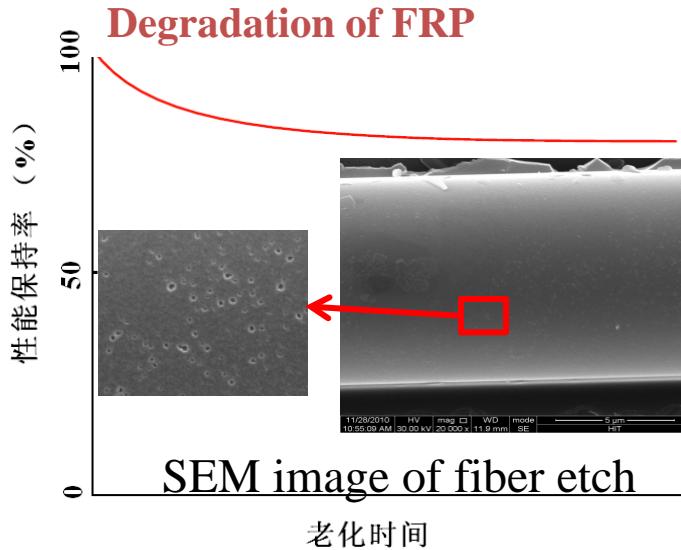
Future work: Mechanism and design method of large-sized structure with FRP



Future work: Fatigue and creep behavior FRP under muti-field coupling and life controllability



Future work: FRP under ultimate severe conditions



High temperature, such as fire, severe corrosive environments

Future work: Disaster mechanism and recoverability of FRP structures under extreme loads

Seismic behavior



RC column



RC column with FRP

Anti-blast behavior



RC wall



RC wall with FRP

Thank you for your attention

And questions?