

## Method to Simulate Design Earthquake Motions

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### Earthquake motions for structure design

- Using observed motion
- Stochastic model of amplitude and phase spectra
- Based on the dynamics of elastic body
- Empirical simulation model
- Design response spectrum compatible EM
- EM phase using nonlinear structural design

### Introduction of Fourier analysis and stochastic modeling of earthquake motions

Modeling of amplitude and phase

### Introduction of Fourier analysis

- Using inverse Fourier transformation

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} Y(\omega) d\omega \frac{1}{2\pi} \int_{-\infty}^{\infty} A(\omega) \exp(i\phi(\omega)) e^{i\omega t} d\omega$$

$Y(\omega)$ : Fourier transform of  $y(t)$

$A(\omega)$ : amplitude spectrum

$\phi(\omega)$ : phase spectrum

## Fourier Inverse Transform

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} A(\omega) \exp(i\phi(\omega)) e^{i\omega t} d\omega$$

$$= \int_{-\infty}^{\infty} A(\omega) \cos(\omega t + \phi(\omega)) df + i \int_{-\infty}^{\infty} A(\omega) \sin(\omega t + \phi(\omega)) df$$

Taking into account the facts that the amplitude spectrum is symmetric and the phase spectrum is asymmetric with respect to , we can get

$$y(t) = \int_{-\infty}^{\infty} A(\omega) \cos(\omega t + \phi(\omega)) df$$

## Discretization

It is necessary for numerical analyses to use finite sampling function given by

$$G(\omega) = \delta(\omega) + \sum_{l=1}^{N/2} \{\delta(\omega - \omega_l) + \delta(\omega + \omega_l)\}$$

And considering the following formula

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} A(\omega) e^{i(\omega t + \phi(\omega))} \{\delta(\omega - \omega_l) + \delta(\omega + \omega_l)\} 2\pi df$$

$$= 2A(\omega_l) \cos(\omega_l t + \phi(\omega_l))$$

## Discretization

Substituting these formula into the inverse transformation formula we can obtain

$$y(t) = A(0) + \sum_{l=1}^{N/2} 2A(\omega_l) \cos(\omega_l t + \phi(\omega_l))$$

Any time histories can be approximated by a finite sum of cosine time functions

## Amplitude and phase spectra of earthquake motion

$$y(t) = A_1 \cos(2\pi f_1(t + t_1)) + A_2 \cos(2\pi f_2(t + t_2)) + \dots$$

$$+ A_n \cos(2\pi f_n(t + t_n)) + \dots$$

$f_n$  : nth frequency

$A_n$  : nth amplitude  $\rightarrow$  amplitude spectrum

$t_n$  : nth time lag

$2\pi f_n t_n$  : nth phase  $\rightarrow$  phase spectrum :  $\phi_n$

## Simple case examples

$$y(t) = A_1 \cos(2\pi f_1(t + t_1)) + A_2 \cos(2\pi f_2(t + t_2))$$

case 1:  $A_1 = A_2 = 1.0$ ,  $f_1 = f_2 = 1\text{Hz}$       [c1](#)  
 $t_1 = 0.25$ ,  $t_2 = -0.25\text{ sec}$

case2 :  $A_1 = A_2 = 1.0$ ,  $f_1 = 1.0$ ,  $f_2 = 1.1$       [c2](#)  
 $t_1 = 0.25$ ,  $t_2 = -0.25$

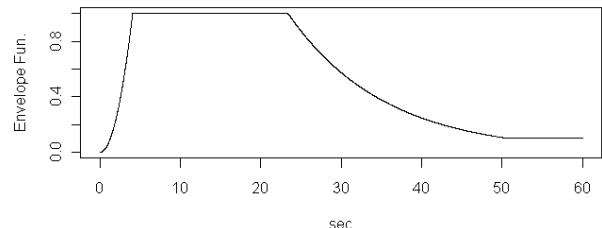
## Complicated example

- Amplitude is defined by normal distribution with mean=0 and standard deviation=5gal
- In the phase  $2\pi f_n t_n$ ,  $f_n t_n$  is assumed to be expressed by uniform random number between 0 to 1
- Number of summation terms is change from 10 to 1000
- Time interval is 0.01 sec and duration is 10 sec

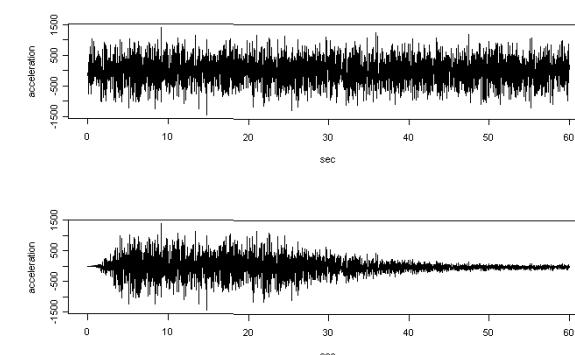
Sample 3

## Shape function

|                            |                            |                                 |
|----------------------------|----------------------------|---------------------------------|
| $0 \leq t \leq T_b$        | $E(t) = (t/T_b)^2$         | $T_d = 10^{0.31M - 0.774}$      |
| $T_b < t \leq T_c$         | $E(t) = 1$                 | $T_b = (0.12 - 0.04(M - 7))T_d$ |
| $T_c < t \leq T_d$         | $E(t) = \exp(-a(t - T_c))$ | $T_c = (0.50 - 0.04(M - 7))T_d$ |
| $T_d < t$                  | $E(t) = 0.1$               | $a = -\ln(0.1)/(T_d - T_c)$     |
| $M$ : Earthquake Magnitude |                            |                                 |



## Stationary and Non-stationary time history of accelerations

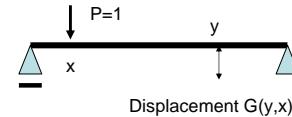


## Introduction of simulation of earthquake motions based on elasto dynamics

Similarity law and derived simple formula

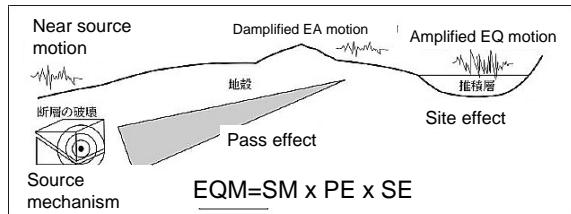
Based on the dynamics of elastic body

- Partial differential equation controlling wave propagation in elastic medium
- Green function of this equation



Displacement  $u(t)$  at  $y$  for a given time history of force  $P(t)$  at  $x$  is calculated by  
 $u(t)=G(y,x)P(t)$

## Mechanism of wave propagation



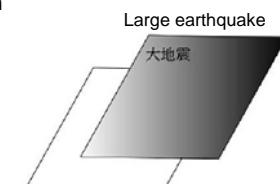
## Source mechanism

### Green function

Small earthquake



Small movement of a small area



Large movement of a large area

## Similarity Law

$$M_0 = \mu D_0 A$$

$$M_0 \sim A^{3/2} \quad L \approx 2W \quad D_0 \sim L$$

Large Event:  $L_L \ W_L \ D_{0L}$

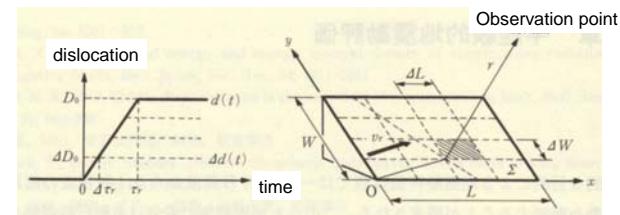
Small Event:  $\Delta L \ \Delta W \ \Delta D_0$

$$L_L / \Delta L = W_L / \Delta W = D_{0L} / \Delta D_0 = n_L = n_S = n_D = n$$

$$n = \left( \frac{M_L}{M_s} \right)^{\frac{1}{3}}$$

## Uniform rupture of faults

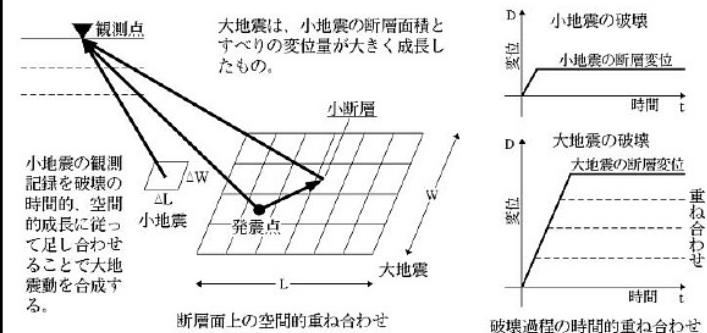
$$u_L(t) = \sum_{i=1}^n \sum_{j=1}^n \sum_{k=1}^n \frac{r_s}{r_{ij}} u_S \left( t - t_{ij} - (k-1) \frac{\tau_r}{n} \right)$$

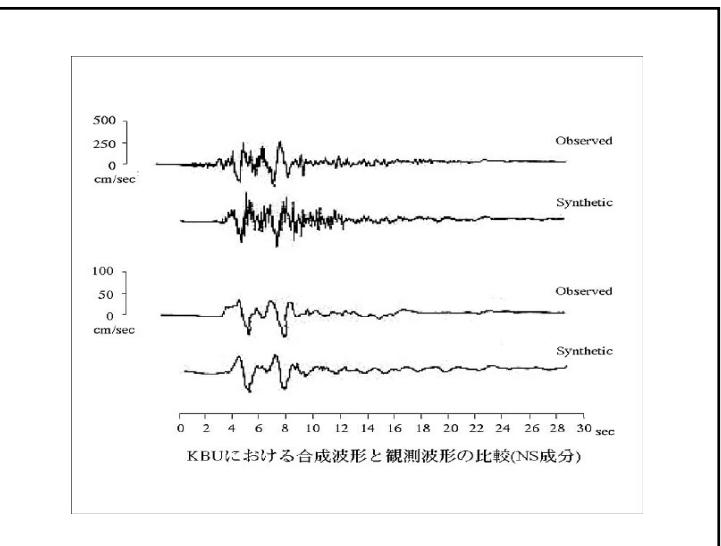


## Simulation of earthquake motion for a large event

- Calculate Green function based of wave propagation equation in elastic medium
- Sum up Green function taking into account similarity rule between the samll event and a large event
- Difficult to obtain Green function taking into account complex path and local site effect

## Simulation of earthquake motion using observed small event motion



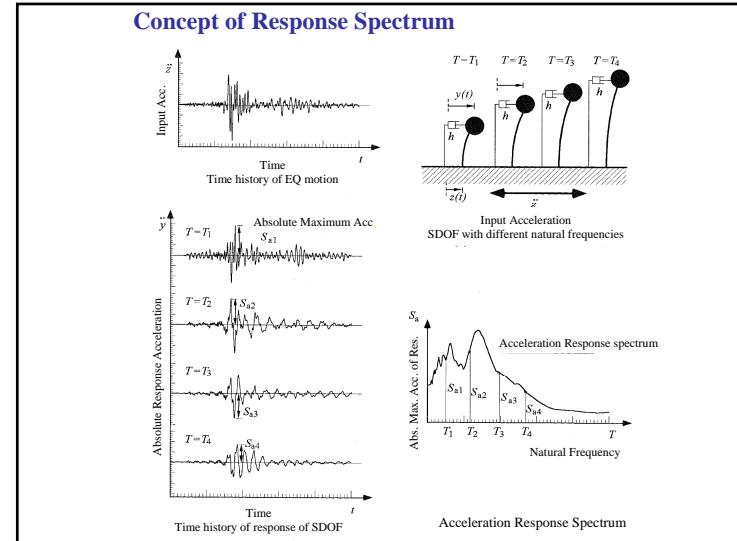


## Concept of Seismic Design

For the case of Elastic design

## Introduction of seismic design

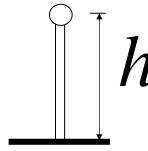
- Concept of response spectra
- How to use response spectra for earthquake proof design of structures
- Concept of yield strength demand spectrum
- How to use the yield strength demand spectrum for earthquake proof design of structures



## Concept of aseismic design for a linear structure

$$F = mS_a(T, h)$$

*m*



*Bending moment at column foot*

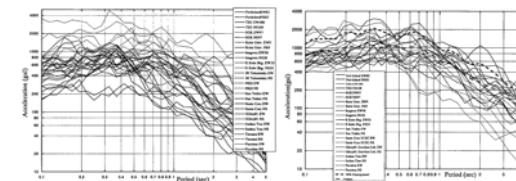
$$M = Fh = mhS_a(T, h)$$

$$M \leq M_{\max}$$

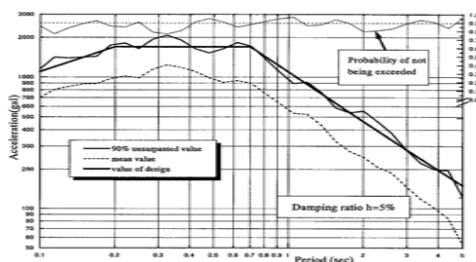
## Earthquake data and calculated acceleration response spectra for near source region

Table1. Near-source seismic records from recent earthquakes

| No | Earthquake              | Name of seismic record   | Max. Acc. (g/s) | NS    | EW     | Latitude | Longitude | Equivalent hypocentral distance to observation | Shortest distance to observation | Ground motion level of observation |
|----|-------------------------|--------------------------|-----------------|-------|--------|----------|-----------|--|----------------------------------|------------------------------------|
| 1  | Punt Island             |                          | 679.8           | 302.6 | 34.670 | 135.308  | 11.84     | 7.32   | 3.24                             | GL-43                              |
| 2  | Daisenji Power Station  |                          | 209.9           | 319.5 | 34.743 | 134.985  | 24.37     | 24.65  | 24.65                            | GL-27.0                            |
| 3  | NSK Kariyama Co.        |                          | 272.0           | 306.5 | 34.723 | 135.040  | 16.99     | 6.80   | 6.80                             | GL-4.5                             |
| 4  | RokkoKobe University    |                          | 272.0           | 306.5 | 34.723 | 135.040  | 16.99     | 25.00  | 25.00                            | GL-27.0                            |
| 5  | Hyogoken Nambu          |                          | 272.0           | 306.5 | 34.723 | 135.040  | 16.99     | 25.00  | 25.00                            | GL-4.5                             |
| 6  | Great Hanshin-Awaji     |                          | 485.9           | 425.3 | 34.767 | 135.296  | 20.00     | 12.38  | 12.38                            | GL-33                              |
| 7  | Kobe                    |                          | 683.6           | 600.9 | 34.809 | 135.344  | 29.93     | 16.88  | 16.88                            | GL-0.0                             |
| 8  | New Zealand             |                          | 483.6           | 425.3 | 34.809 | 135.344  | 18.23     | 7.27   | 7.27                             | GL-0.0                             |
| 9  | Croton Lake             | San Ysidro               | 314.6           | 468.8 | 37.026 | 121.484  | 1.0       |  |                                  | GLD.0                              |
| 10 | San Simeon              |                          | 314.6           | 468.8 | 37.026 | 121.484  | 1.0       |  |                                  | GLD.0                              |
| 11 | Loma Prieta             | Santa Cruz               | 428.6           | 433.6 | 36.973 | 121.572  | 26.56     | 12.21  | 12.21                            | GLD.0                              |
| 12 | Landers                 | Joshua Tree fire station | 268.3           | 278.4 | 34.131 | 116.314  | 16.90     | 16.79  | 16.79                            | GLD.0                              |
| 13 | Northridge              | Tazman Coal Mill         | 434.2           | 295.3 | 34.288 | 112.575  | 18.75     | 8.98   | 8.98                             | GLD.0                              |
| 14 | Pyroclastic Vent Canyon |                          | 434.2           | 295.3 | 34.288 | 112.575  | 18.75     | 8.98   | 8.98                             | GLD.0                              |

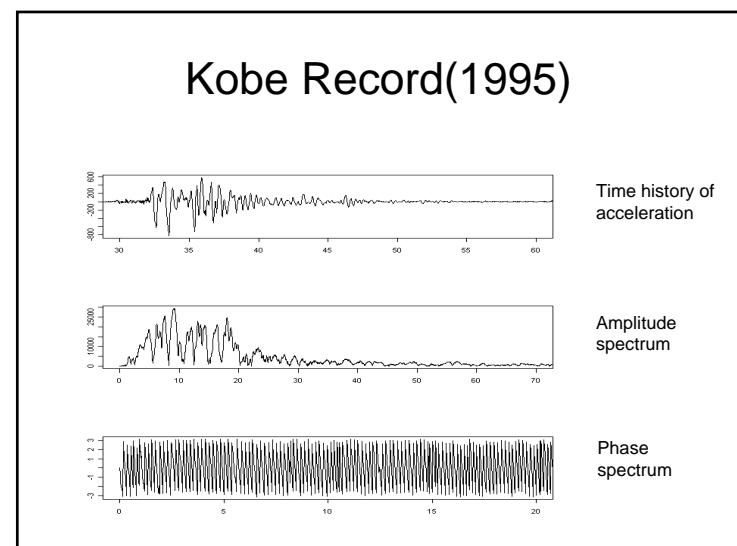
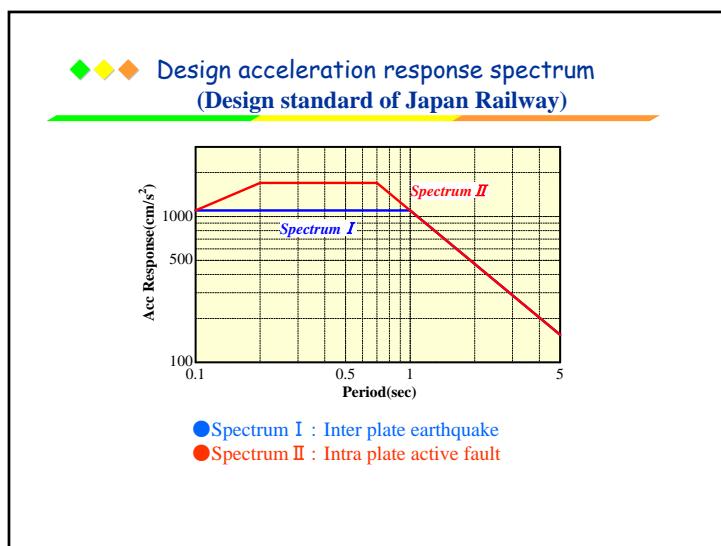
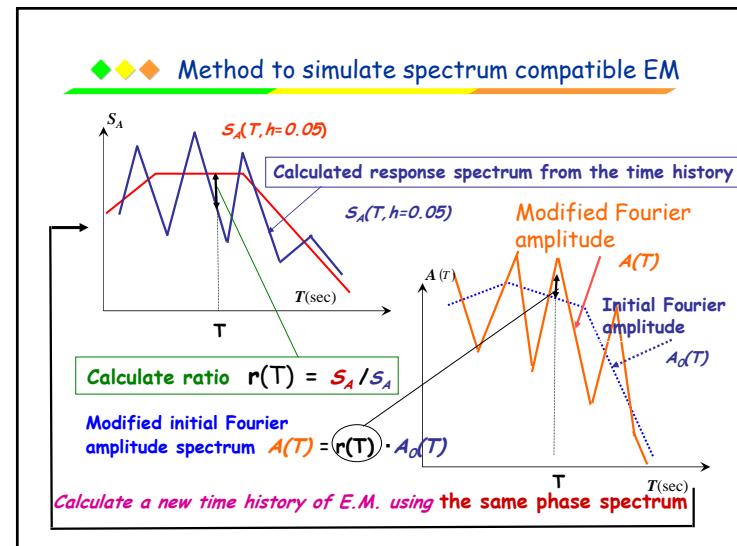
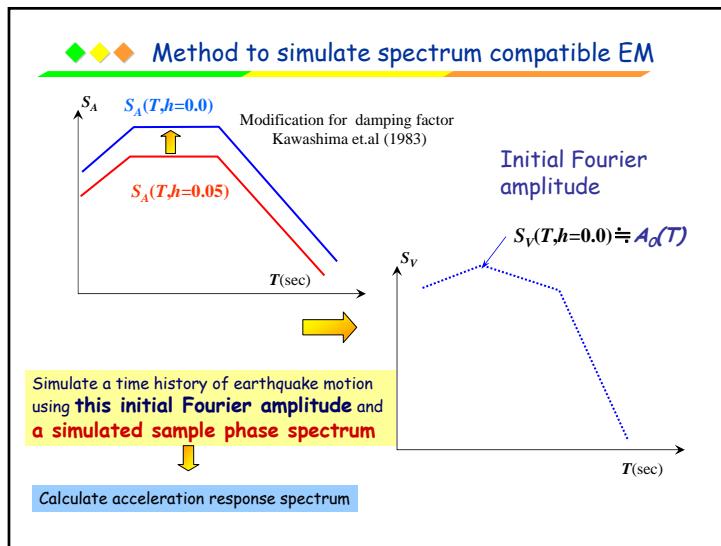


## Design response spectrum for intra-plate earthquake

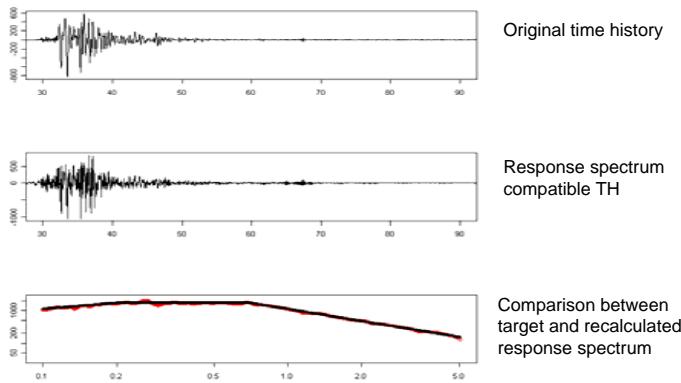


## Simulation of Design Spectrum Compatible Earthquake Motions

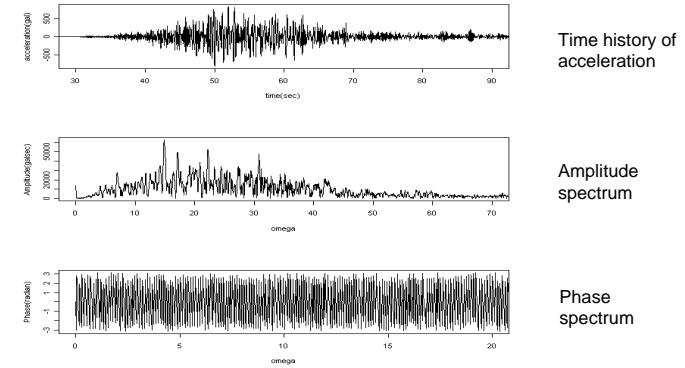
Inter and intra plate design spectra



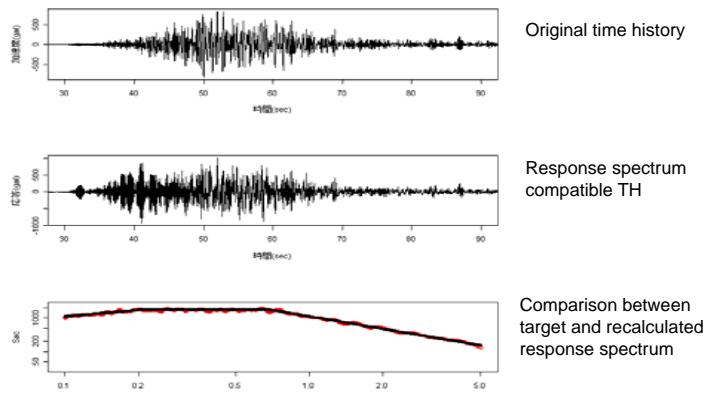
### For the case of Kobe Record



### Kushiro Record(1994)



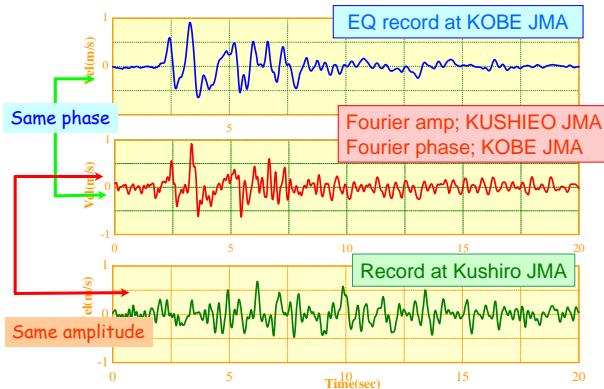
### For the case of Kushiro Record



## Modeling of Phase Spectra for Simulation of Design Earthquake Motions

Single Source Assumption

## Effect of phase on earthquake ground motion



## ◆ Definition of group delay time (GDT)

Group delay time

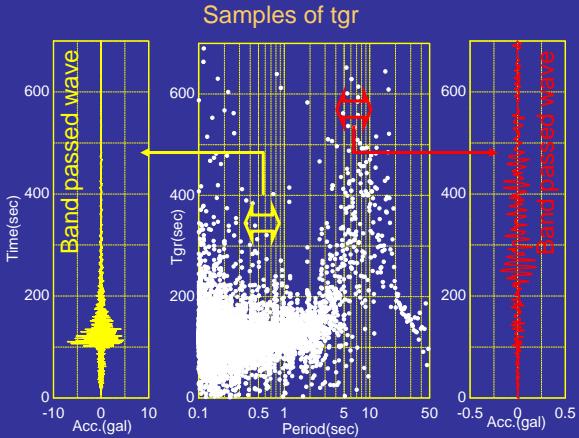
$$t_{gr} = \frac{d\phi(\omega)}{d\omega} \quad f(t) \Leftrightarrow A(\omega)\exp\{i\phi(\omega)\}$$



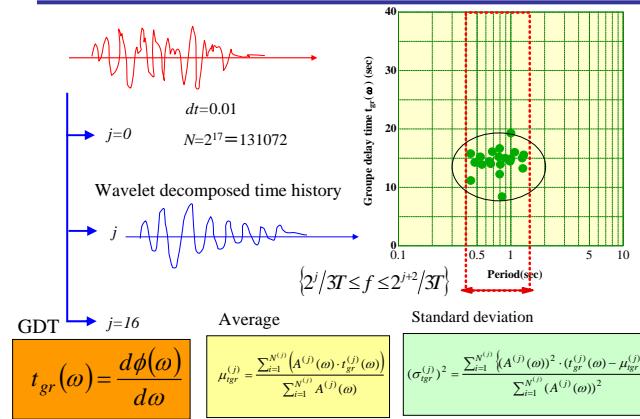
- Mean value : Arrival time of energy of E.M.
- Standard deviation : Duration of E.M.

Modeling of GDT is easier than the direct modeling of phase spectrum  $\phi(\omega)$

## Role of Group Delay Time



## Mean group delay time and its standard deviation - Using Mayer Wavelet -



## Decompositon of GDT into source, path and local site effects

$$\begin{aligned}
 & A(\omega) e^{i\phi(\omega)} \\
 &= A^{(S)}(\omega) \cdot A^{(P)}(\omega) \cdot A^{(L)}(\omega) \cdot \exp\left\{\left(\phi^{(S)}(\omega) + \phi^{(P)}(\omega) + \phi^{(L)}(\omega)\right)\right\} \\
 & t_{gr}(\omega) = \frac{d\phi}{d\omega} \\
 & t_{gr}^{(j)}(\omega) = t_{gr}^{(j)(S)}(\omega) + t_{gr}^{(j)(P)}(\omega) + t_{gr}^{(j)(L)}(\omega) \\
 & \mu_{igr}^{(j)} = \mu_{igr}^{(j)(S)} + \mu_{igr}^{(j)(P)} + \mu_{igr}^{(j)(L)} \\
 & (\sigma_{igr}^{(j)})^2 = (\sigma_{igr}^{(j)(S)})^2 + (\sigma_{igr}^{(j)(P)})^2 + (\sigma_{igr}^{(j)(L)})^2
 \end{aligned}$$

## Regression equation of GDT

$$\begin{aligned}
 \mu_{igr}^{(j)}(\omega) &= \alpha_1^{(j)} \cdot 10^{0.5M} + \beta_1^{(j)} \cdot R + \gamma_1^{(j)} \cdot H + \kappa_1^{(j)} \\
 (\sigma_{igr}^{(j)})^2 &= \alpha_2^{(j)} \cdot 10^M + \beta_2^{(j)} \cdot R^2 + \gamma_2^{(j)} \cdot H^2 + \kappa_2^{(j)}
 \end{aligned}$$

M: Earthquake magnitude

R: Hypocenter distance

H: Depth of surface ground

### ◆◆◆ Number of data used for analysis

Table 1 Number of data used for analysis

| Coefficients     | Number of data |
|------------------|----------------|
| $\alpha$         | 588            |
| $\beta$          | 786            |
| $\gamma, \kappa$ | 1618           |

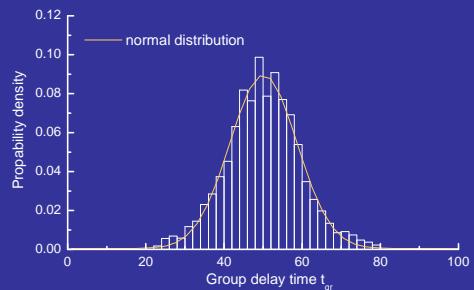
## Regression coefficients

Table 2 Result of regression analyses

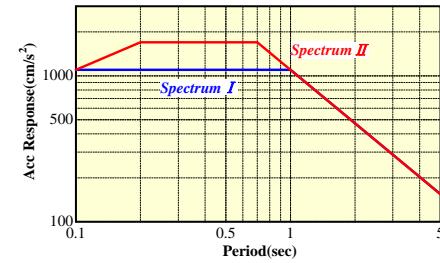
| j  | $\mu_{igr}^{(j)}$ |           |            |            | $(\sigma_{igr}^{(j)})^2$ |            |            |            |
|----|-------------------|-----------|------------|------------|--------------------------|------------|------------|------------|
|    | $\alpha_1$        | $\beta_1$ | $\gamma_1$ | $\kappa_1$ | $\alpha_2$               | $\beta_2$  | $\gamma_2$ | $\kappa_2$ |
| 8  | 1.359E-03         | 0.362     | 4.026E-03  | 0.250      | 1.206E-05                | 4.163E-03  | 6.408E-06  | 142.599    |
| 9  | 1.453E-03         | 0.326     | 4.404E-03  | 2.930      | 3.131E-06                | 3.433 E-03 | 7.440E-06  | 109.490    |
| 10 | 8.439E-04         | 0.296     | 3.345E-03  | 4.712      | 1.268E-06                | 3.480 E-03 | 5.918E-06  | 51.728     |
| 11 | 8.247E-04         | 0.286     | 2.180E-03  | 3.810      | 5.919E-07                | 3.112E-03  | 2.073E-06  | 23.115     |
| 12 | 6.080E-04         | 0.271     | 1.097E-03  | 3.442      | 8.891E-09                | 1.767E-03  | 4.627E-07  | 12.476     |
| 13 | 8.880E-04         | 0.251     | 6.145E-04  | 3.656      | 8.805E-08                | 6.257E-04  | 3.760E-07  | 11.656     |
| 14 | 1.143E-03         | 0.250     | 3.723E-04  | 3.174      | 8.068E-08                | 5.522E-04  | 3.724E-07  | 9.915      |
| 15 | 1.037E-03         | 0.246     | 1.553E-05  | 3.169      | 7.015E-07                | 9.468E-04  | 3.673E-07  | 12.376     |

## Stochastic characteristics of GDT

- Probabilistic density function -

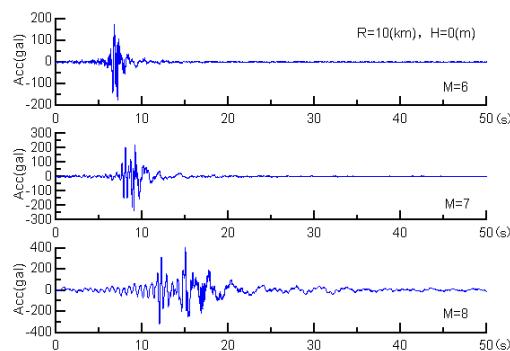


◆◆◆ Design acceleration response spectrum  
(Design standard of Japan Railway)

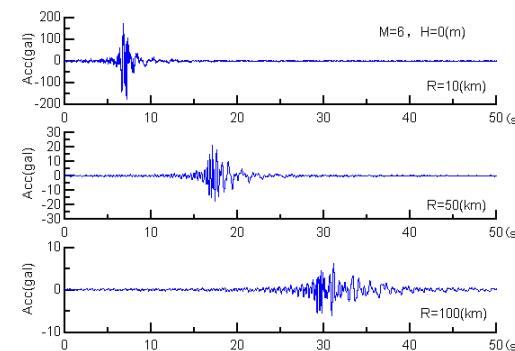


- Spectrum I : Inter plate earthquake
- Spectrum II : Intra plate active fault

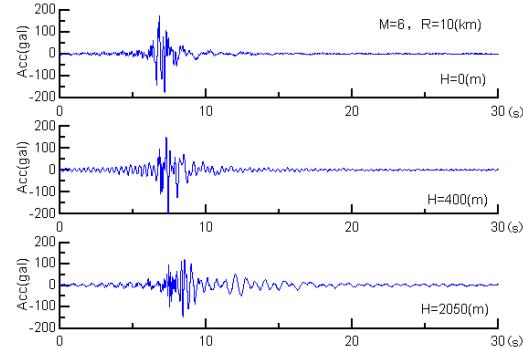
## EM compatible with RS effect of magnitude



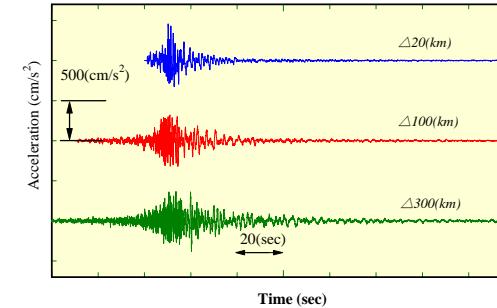
## EM compatible with RS effect of hypocenter distance



## EM compatible with RS effect of surface deposit (depth)



### ◆◆◆ Spectrum compatible EM -Spectrum I-



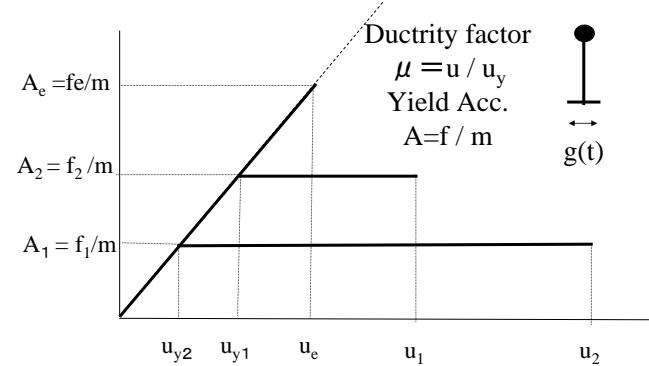
## Concept of Seismic Design

For the case of nonlinear design

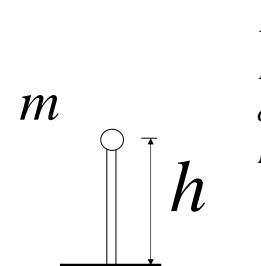
## Introduction of seismic design

- Concept of response spectra
- How to use response spectra for earthquake proof design of structures
- Concept of yield strength demand spectrum
- How to use the yield strength demand spectrum for earthquake proof design of structures

### Definition of yield acceleration and displacement as well as ductility factor



### Concept of aseismic design for a nonlinear structure



$$F = m A_y(T, h)$$

Bending moment at column foot

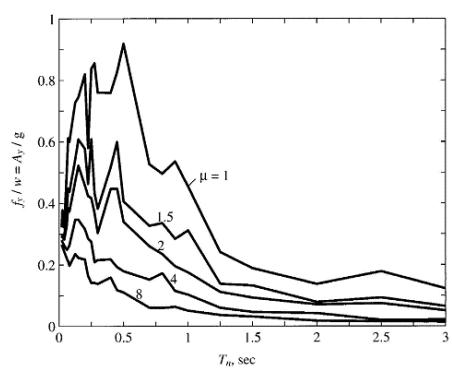
$$M = Fh = mhA_y(T, h)$$

$$M \leq M_{\max}$$

$$A_e(T, h) = S_a(T, h)$$

$$A_1(T, h) < A_2(T, h) < A_e(T, h)$$

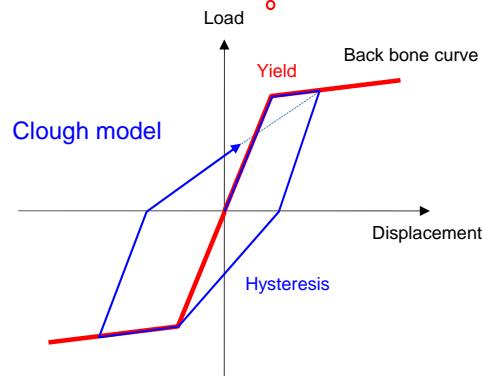
### Strength demand spectra



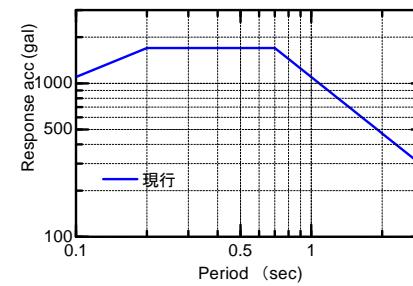
### Earthquake Phase Spectrum used for Nonlinear Structural Design

Concept of worst earthquake phase

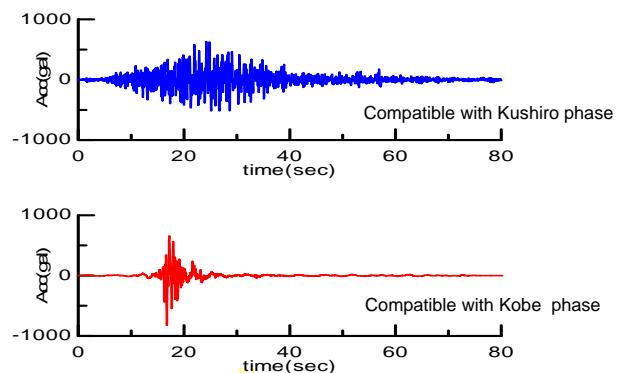
### Clough Hysteresis Model



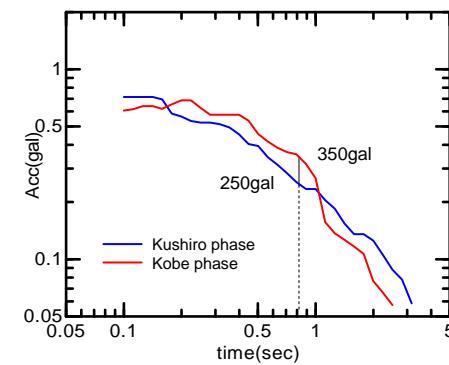
### Response spectrum used for calculation



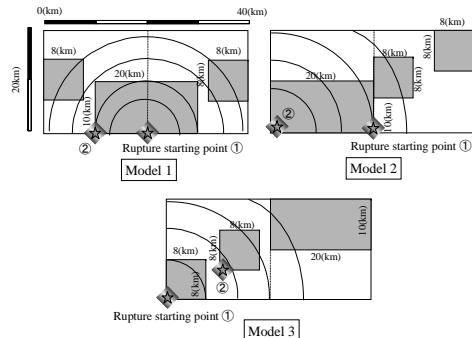
### Response spectrum compatible earthquake motions



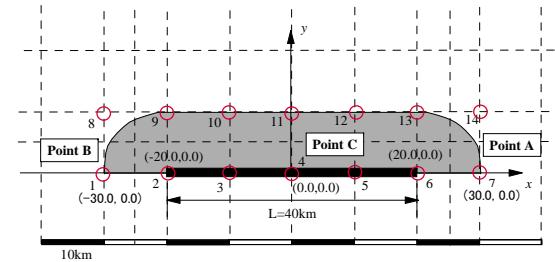
### Nonlinear response spectra



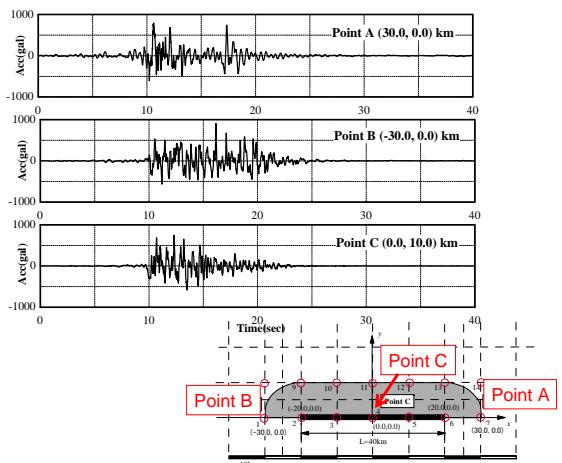
### Asperity distribution used for parameter studies



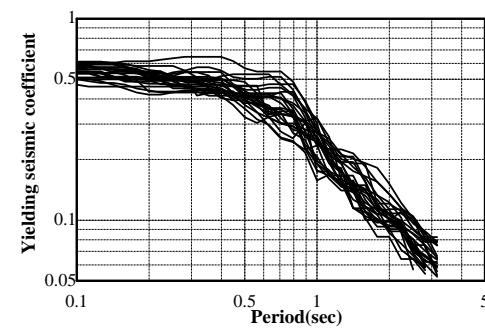
### Positions to simulate earthquake motions



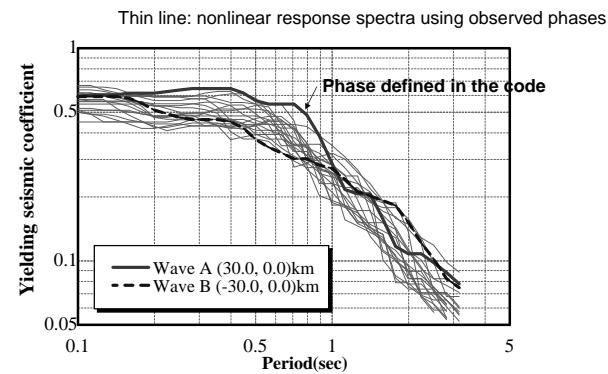
### Example of simulated earthquake motions



### Nonlinear response spectra using simulated earthquake motion's phases



Comparison with nonlinear response spectra  
with those of observed earthquake motion phases



Thank you very much for your attention



A棟、B棟、イベント広場を見る

Port Island Campus of Kobegakuin University